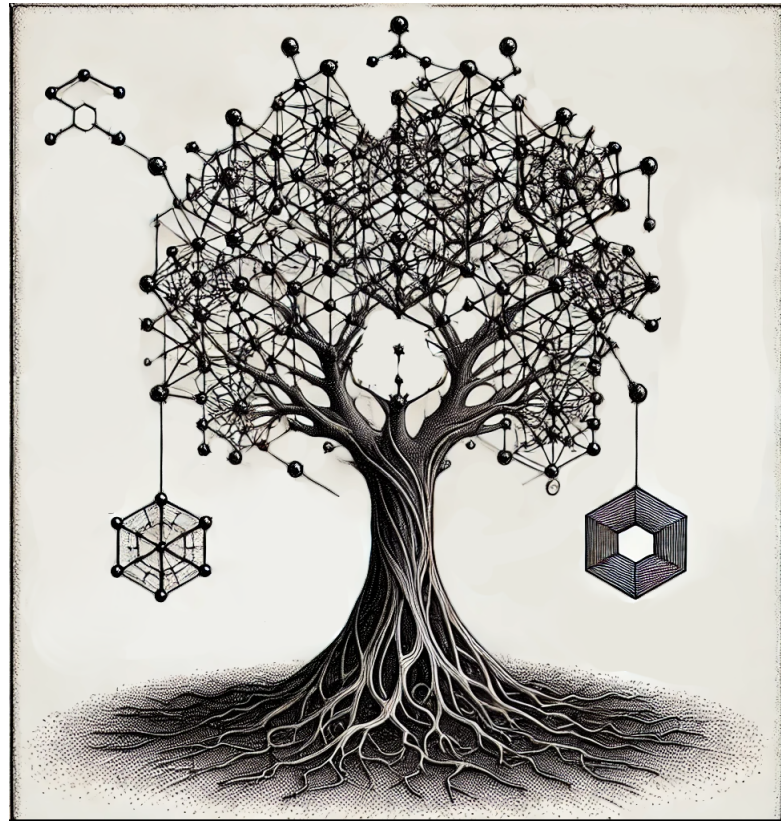


# Groups, Geometry and Logic



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I am grateful to  
**Samuel Adrian Antz, Anna Gaugler and Javier San Martín  
Martinez**  
for their valuable comments and corrections

Winter semester 2024-5

I intend to update the notes occasionally; if you spot any mistakes, please drop me an email at [fruchter@math.uni-bonn.de](mailto:fruchter@math.uni-bonn.de) (you will be acknowledged!).

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For the time being, hand-drawn figures appear in Appendix B. I intend to slowly convert them to TeX (and move them to the relevant places).

# I

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## Introduction and overview

**I**N this preliminary chapter we lay out foundational groundwork, giving a brief overview of fundamental concepts in the fields of first-order logic and model theory (with a focus on the study of groups from this perspective). We then survey important theorems from the past three decades concerning with the first-order theory of free groups.

Given a group  $G$ , our main goal is to understand the *theory of  $G$* , which is (roughly speaking) the following set:

$$\text{Th}(G) = \{\text{"things" that are true in } G\}.$$

To be able to talk about "things" in a precise manner, we will embrace the setting and conventions of *first-order logic*; not all "things" can be described in this setting, and as we will see different groups can have the same theory (whereas, under mild assumptions, others are completely determined by their theory). In the first part of the course, our discussion will focus on infinite groups, and in particular free groups. Our analysis of the theory of such groups will rely on topological and geometric tools.

Before making things precise, we give some assertions one can make about a group  $G$  in first-order logic. Such statements, are ones that involve:

1. **Quantifiers:**  $\forall$  (for all) and  $\exists$  (exists),
2. **Variables:**  $x, y, z, \dots$ , which allow us to refer to group elements,
3. **Equality:**  $=$  the equality sign,
4. **Logical connectors:**  $\neg$  (not/negation),  $\wedge$  (and/conjunction),  $\vee$  (or/disjunction) and  $\rightarrow$  (implies),

5. **Group theoretic symbols:**  $\cdot$  (group multiplication),  $-^{-1}$  (inverse operation) and  $1$  (trivial group element).

A few examples, that should give us better intuition as to one can or can not say about a group  $G$  using first-order statements, include:

**Examples I.0.1.** 1. The fact that a group  $G$  is trivial can be expressed by the sentence  $\forall x x = 1$ .

2. The fact that a group  $G$  is finite of size  $n$  can be expressed by the sentence

$$\varphi_n = \exists x_1 \cdots \exists x_n \left( \bigwedge_{1 \leq i < j \leq n} x_i \neq x_j \right) \wedge \left( \forall y \bigvee_{1 \leq i \leq n} y = x_i \right).$$

Note that this sentence depends on the constant  $n$ . Since **quantifying over natural numbers is not allowed** (and more generally, one can only quantify over *group elements*), there isn't a sentence that holds if and only if  $G$  is finite.

3. One can extend the idea above to construct a sentence that completely determines a finite group  $G$ : simply write down a finite multiplication table for  $G$ , and add  $x_i \cdot x_j = x_k$  to the sentence above for every entry in the multiplication table.
4. One can encode the fact that  $G$  is abelian in a first-order sentence:  $\forall x \forall y [x, y] = 1$ ; similarly, the negation of this sentence  $\neg(\forall x \forall y [x, y] = 1)$ , which is equivalent to  $\exists x \exists y [x, y] \neq 1$ , asserts that  $G$  is not abelian.
5. Similar to the fact that being finite can not be encoded into a first-order sentence, there is no sentence which states that " $G$  is torsion-free". However, given  $n$ , the sentence  $\psi_n = \forall x x \neq 1 \rightarrow x^n \neq 1$  asserts that there are no elements of order  $n$  in  $G$ . We conclude that  $G$  is torsion-free if and only if the set of sentences  $\{\psi_n : n \in \mathbb{N}\}$  is contained in the theory of  $G$ .

We seal the discussion with an exercise:

**Exercise I.** The point of this exercise is to show that free abelian groups are uniquely determined by their theory among finitely generated groups.

Let  $G = \mathbb{Z}^k$  and let  $H$  be a finitely generated group such that  $\text{Th}(H) = \text{Th}(G)$ . From the examples above, we already know that  $H$  is abelian and torsion-free, and therefore  $H \cong \mathbb{Z}^m$  for some  $m$ .

1. Suppose first that  $k = 1$ , that is  $G = \mathbb{Z}$ . Use the fact that every integer  $z \in \mathbb{Z}$  is either *even* or *odd* to construct a sentence  $\chi$  such that if  $\chi \in \text{Th}(H)$  then  $H$  must be isomorphic to  $\mathbb{Z}$ .
2. Generalize the idea above and construct a similar sentence when  $k > 1$ .

## I.1 Basic concepts in first-order logic

To make statements, one needs a language. In the context of first-order logic, a *language*  $\mathcal{L}$  is a set of symbols, which come in one of three types:

1. *constants*, usually denoted by  $c_1, c_2, \dots$ ,
2. *predicates, or relations*, usually denoted by  $P_1, P_2, \dots$ , and each of these will be interpreted later as a multivariable function with target in  $\{\text{True}, \text{False}\}$ ,
3. *functions*, usually denoted by  $f_1, f_2, \dots$ , which will be interpreted as multivariable functions that create new elements from given elements.

*Remark I.1.1.* Some authors refer to "=" as a 2-variable predicate, while others use the convention that = is a logical symbol (such as  $\wedge$  or  $\neg$ ). We will stick to the latter.

Given a language, one can form *structures*:

**Definition I.1.2.** Given a language  $\mathcal{L}$ , an  $\mathcal{L}$ -*structure*  $M$  consists of:

1. A set called a *universe*, or a *domain*. The universe of  $M$  is usually denoted by  $|M|$ .
2. An interpretation of the constant symbols: for each constant symbol  $c \in \mathcal{L}$ , we specify an element  $x \in |M|$  (usually denoted by  $c^M$ ).
3. An interpretation of the predicate symbols: for each  $n$ -ary predicate symbol  $P \in \mathcal{L}$ , we associate a function  $P^M : |M|^n \rightarrow \{\text{True}, \text{False}\}$ .
4. An interpretation of the function symbols: for each  $n$ -ary function symbol  $f \in \mathcal{L}$ , we associate a function  $f^M : |M|^n \rightarrow |M|$ .

**Example I.1.3.** Let  $\mathcal{L} = \mathcal{L}^{\text{gp}} = \{\cdot, {}^{-1}, 1\}$  be the language of groups, which consists of a constant symbol 1, and two function symbols: a 2-ary function symbol  $\cdot$  and a 1-ary function symbol  ${}^{-1}$ . Then every group  $G$  is an  $\mathcal{L}$ -structure, where 1 is interpreted as the identity element, and  $\cdot$  and  ${}^{-1}$  are interpreted as the group multiplication and inverse operations.

Statements in a language (usually) only make sense if they are phrased adhering to certain syntactic rules. We continue by defining appropriate syntax, which will enable us to make statements in a language  $\mathcal{L}$  about its structures. The first-order syntax coincides with what one would intuitively expect, and the definitions (as well as classical proofs in the study of first-order logic), are made by induction:

**Definition I.1.4.** A *term*  $t$  in a language  $\mathcal{L}$  is either

1. a variable,
2. a constant symbol, or
3.  $f(t_1, \dots, t_n)$  where  $f \in \mathcal{L}$  is an  $n$ -ary function symbol, and  $t_1, \dots, t_n$  are terms.

**Example I.1.5.** In the language of groups, the commutator of two variables is a term (involves applying  $^{-1}$  twice and  $\cdot$  thrice), and more generally any nested commutator of variables, that is an expression of the form  $[x_1, [x_2, \dots, [x_{n-1}, x_n] \dots]]$  is a term.

**Definition I.1.6.** A *formula*  $\varphi$  in a language  $\mathcal{L}$  is either

1. *atomic*, that is  $\varphi$  has one of the following two forms
  - (a)  $t_1 = t_2$  where  $t_1$  and  $t_2$  are  $\mathcal{L}$ -terms,
  - (b)  $P(t_1, \dots, t_n)$  where  $P \in \mathcal{L}$  is an  $n$ -ary predicate symbol, and  $t_1, \dots, t_n$  are terms.
2. obtained from formulas using logical symbols, e.g.  $\neg\varphi$  or  $\varphi \wedge \psi$  where  $\varphi$  and  $\psi$  are formulas, or
3. obtained from a formula  $\varphi$  by *bounding* a variable by a quantifier, that is  $\forall x\varphi$  and  $\exists x\varphi$  are both formulas.

We remark that, in order to make things clear, we will *always* wrap formulas in brackets brackets when constructing new formulas from old ones. This way, for example, if  $\varphi$  and  $\psi$  are formulas, the formula " $\varphi$  implies  $\psi$ " will be written as  $(\varphi) \rightarrow (\psi)$ . A quick inspection of different formulas reveals that variables can come in two flavours: they either appear *free*, or they are *bound* by a quantifier. We make this statement precies:

**Definition I.1.7.** Let  $\varphi$  be a formula. Looking at  $\varphi$  as a string  $a_1a_2\cdots a_n$ . Given a variable  $x$ , look at a specific occurrence of  $x$  in  $\varphi$ , that is choose some  $i$  with  $a_i = x$ . We say that this occurrence of  $x$  is *bound* by a quantifier if for some  $j < i - 1$ ,  $a_j \in \{\exists, \forall\}$ ,  $a_{j+1} = x$  and the *subformula* starting at  $a_j$  (that is, the minimal string starting at  $a_j$  which is itself a formula, or in other words it has a balanced number of parentheses), has the form  $a_jx(a_{j+3}\dots a_i\dots)$ . Otherwise, we say that the occurrence of  $x$  is *free* in  $\varphi$ .

*Remark I.1.8.* Note that the same variable can occur both boundedly and freely in a single formula, for example in the formula  $\varphi = (\forall x(x \cdot x = 1)) \vee x \cdot x \cdot x = 1$  the first occurrence of  $x$  is bounded, whereas the second one is free.

Armed with these definitions, we can now determine when a formula is *satisfied* in a model:

**Definition I.1.9.** Let  $\varphi$  be a formula in  $\mathcal{L}$  and let  $M$  be an  $\mathcal{L}$ -structure. We say that  $M$  satisfies  $\varphi$ , and denote it by  $M \models \varphi$ , if the following holds:

Let  $\sigma$  be an *assignment* of values for the variables in  $M$ , that is  $\sigma$  is a function from the collection of variables into  $|M|$ . Using the inductive definition of terms,  $\sigma$  can be easily extended to a map from the collection of all  $\mathcal{L}$ -terms into  $|M|$ . The assignment  $\sigma$  gives rise to a valuation  $v_\sigma$ , which is a map from the collection of all  $\mathcal{L}$ -formulas into  $\{\mathbf{True}, \mathbf{False}\}$ , defined inductively as follows:

1. if  $\varphi$  is atomic of the form  $t_1 = t_2$ ,  $v_\sigma(\varphi) = \mathbf{True}$  if and only if  $\sigma(t_1) = \sigma(t_2)$  in  $|M|$ ,
2. if  $\varphi$  is atomic of the form  $P(t_1, \dots, t_n)$  then  $v_\sigma(\varphi) = P(\sigma(t_1), \dots, \sigma(t_n)) \in \{\mathbf{True}, \mathbf{False}\}$ ,
3. if  $\varphi$  was obtained from formulas using logical symbols, we deduce the value of  $v_\sigma(\varphi)$  using the truth tables for the logical connectors, e.g. if  $\varphi = \psi \rightarrow \chi$  then  $v_\sigma(\varphi) = \mathbf{True}$  if and only if either  $v_\sigma(\psi) = \mathbf{False}$  or  $v_\sigma(\psi) = v_\sigma(\chi) = \mathbf{True}$ ,
4. if  $\varphi = \exists x\psi$  or  $\varphi = \forall x\psi$ , consider the collection of assignments  $\sigma_{x,m}$  ( $m \in |M|$ ), each defined by

$$\sigma_{x,m}(y) = \begin{cases} \sigma(y) & y \neq x \\ m & y = x \end{cases}.$$

Note that we already know the values of the different  $v_{\sigma_{x,m}}(\psi)$  by induction; we say that  $v_\sigma(\exists x\varphi) = \mathbf{True}$  if and only if  $v_{\sigma_{x,m}}(\psi) = \mathbf{True}$  for some  $m \in |M|$ , and that  $v_\sigma(\forall x\varphi) = \mathbf{True}$  if and only if  $v_{\sigma_{x,m}}(\psi) = \mathbf{True}$  for all  $m \in |M|$ .



Finally, we say that  $M \models \varphi$  if  $v_\sigma(\varphi) = \text{True}$  for every assignment  $\sigma$ .

The definition above is somewhat cumbersome, but it goes hand-in-hand with one's intuition. This way, for example, the formula  $x = x$  is satisfied in any structure (of any language), and the formula  $\xi = x \neq 1 \rightarrow x \cdot x = 1$  is satisfied in reflection groups, while in other groups it can be valued as **True** or **False** depending on the assignment (and therefore, generally,  $G \not\models \xi$  (meaning that  $\xi$  is not satisfied in  $G$ )). We next draw attention to the fact that a valuation does not depend on the value that the assignment assigns to bounded variables. In particular, if all of the occurrences of variables in a formula  $\varphi$  are bounded, the truth value of  $v_\sigma(\varphi)$  does not depend on the valuation (or the assignment). This motivates the following definitions:

**Definition I.1.10.** A formula  $\varphi$  is called a *closed formula* or a *sentence* if every occurrence of a variable in  $\varphi$  is bounded. A *Theory* is a set of sentences.

**Definition I.1.11.** The *theory* of an  $\mathcal{L}$ -structure  $M$  is

$$\text{Th}(M) = \{\varphi \mid \varphi \text{ is a sentence and } M \models \varphi\}.$$

If for two  $\mathcal{L}$ -structures  $M$  and  $N$   $\text{Th}(M) = \text{Th}(N)$ , we say that  $M$  and  $N$  are *elementarily equivalent* and denote it by  $M \equiv N$ .

Before continuing with our (shallow) overview of first-order logic and model theory, we are finally in a position to state Sela's incredible result, which will be the focal point of the first part of the course:

**Theorem I.1.12** ([16, et seq.], cf. [8]). *Let  $2 \leq m, n$ , then*

$$\text{Th}(F_m) = \text{Th}(F_n).$$

*Remark I.1.13.* We make the following obvious remark: the assumption that  $F_m$  and  $F_n$  are free of rank at least 2 is crucial: the group  $F_1 \cong \mathbb{Z}$  is abelian, so its first-order theory can not coincide with that of a non-abelian group. In fact, we have seen in an exercise that any finitely generated group  $G$  with  $\text{Th}(G) = \text{Th}(\mathbb{Z})$  has to be isomorphic to  $\mathbb{Z}$ . Lastly, we would like to draw the reader's attention to the fact that the theorem above holds also when one of the groups in question is countable, but not finitely generated.

We continue amassing a few definitions and theorems. First-order theory deals with *provability*: which axioms (that is, sentences) allow one to prove certain theorems, and similar questions. More formally, there is a notion of a *formal system* which

consists of a language and a *deductive system*. A deductive system is a set of rules that allow one to deduce new sentences from existing ones (for example, if we assume both  $\varphi$  and  $\psi$ , we can deduce that  $\varphi \wedge \psi$  is a theorem). Given a theory  $T$ , the fact that one can prove  $\varphi$  from the axioms in  $T$  is denoted by  $T \vdash \varphi$ . We will not dive into defining deductive systems and first-order logic proofs. Luckily for us, there are two important theorems that allow model theorists to "forget" about deductive systems, and simply look at how a sentence behaves in models of a given theory instead:

**Theorem I.1.14** ( $\Rightarrow$  Soundness Theorem  $\Leftarrow$  Gödel's Completeness Theorem). *Let  $\mathcal{L}$  be a language,  $T$  be a theory in  $\mathcal{L}$  and  $\varphi$  an  $\mathcal{L}$ -sentence. Then  $T \vdash \varphi$  if and only if for every  $\mathcal{L}$ -structure  $M$  such that  $M \models T$ , also  $M \models \varphi$ .*

*Remark I.1.15.* This theorem encourages model theorists to abuse notation, and write  $T \models \varphi$  instead of  $T \vdash \varphi$ .

We mention another fundamental theorem in first-order logic:

**Definition I.1.16.** An  $\mathcal{L}$ -theory  $T$  is called *consistent* if it does not prove a contradiction. In other words,  $T$  is consistent if and only if  $T \not\vdash \forall x(x \neq x)$ . A theory is *satisfiable* if it has a model, that is there is an  $\mathcal{L}$ -structure  $M$  such that  $M \models T$ .

*Remark I.1.17.* A variation on Gödel's completeness theorem, commonly referred to as the "Model Existence Theorem", shows that every consistent theory has a model. Since every set of formulas satisfied in a model has to be consistent, this theorem shows that consistency and satisfiability are in fact equivalent.

**Theorem I.1.18** (Compactness Theorem). *Let  $T$  be a theory. If  $T$  is finitely satisfiable, meaning that every finite  $T_0 \subset T$  has a model, then  $T$  is consistent, and therefore has a model.*

The compactness theorem is a standard technique for proving that theories are consistent. We give a simple example that illustrates how one can use the compactness in the context of group theory:

**Example I.1.19.** Suppose that  $G$  is a torsion group, and suppose that every group  $H$  which is a model of  $\text{Th}(G)$  is a torsion group. We will prove that  $G$  is of *bounded exponent*, meaning that there exists  $N \in \mathbb{N}$  such that  $g^N = 1$  for every  $g \in G$ .

Let  $\mathcal{L}' = \mathcal{L} \cup \{c\}$ , where  $\mathcal{L}$  is the language of groups and  $c$  is a constant symbol. Assume for a contradiction that  $G$  is not of bounded exponent. Let  $T = \text{Th}(G) \cup \{c^n \neq 1 \mid n \in \mathbb{N}\}$ , and let  $T_0$  be a finite subset of  $T$ . Let  $m$  be the largest such that  $c^m \neq 1$

appears in  $T_0$ , and since  $G$  is not of bounded exponent there is  $g \in G$  such that  $g, g^2, \dots, g^m \neq 1$ . Interpreting  $c$  as  $g$  in  $G$ , we obtain that  $G$  is an  $\mathcal{L}'$ -structure and that  $G \models T_0$ . It follows that  $T$  is finitely satisfiable, and therefore  $T$  has a model  $H$ .  $H$  is also a model of  $\text{Th}(G)$  and is therefore a torsion group, but  $c^{|H|}$  has to be of infinite order in  $H$ , a contradiction.

**Exercise II.** Prove (using the compactness theorem) that there isn't a finite list of  $\mathcal{L}$ -axioms  $A = \{\varphi_1, \dots, \varphi_n\}$  which axiomatize the class of infinite groups (that is, for a group  $G$ ,  $G \models A$  if and only if  $G$  is infinite).

**Notation I.1.20.** Let  $\varphi = \varphi(x_1, \dots, x_n)$  be an  $\mathcal{L}$ -formula with free variables  $x_1, \dots, x_n$ . Let  $M$  be an  $\mathcal{L}$ -structure and let  $a_1, \dots, a_n \in |M|$ . We denote by  $\varphi(a_1, \dots, a_n)$  the *formal expression* one obtains by replacing each occurrence of  $x_i$  in  $\varphi$  by  $a_i$ , and refer to the  $a_i$  as parameters. In this case, we can assign a truth value for  $\varphi(a_1, \dots, a_n)$  in  $M$ , and we say that  $M \models \varphi(a_1, \dots, a_n)$  if for some (equivalently, every, since  $x_1, \dots, x_n$  are the only free variables in  $\varphi$ ) assignment  $\sigma$  with  $\sigma(x_i) = a_i$ ,  $v_\sigma(\varphi) = \text{True}$ .

Armed with this notation, we can define the notion of *elementary embeddings*. We remark that an *isomorphism* of  $\mathcal{L}$ -structures  $f : M \rightarrow N$  is a bijection  $|M| \rightarrow |N|$ , such that the interpretations of all constant, function and relation symbols in  $M$  agree with those in  $N$  (applied to the image of the relevant arguments under  $f$ ). Similarly, we say that  $M$  is a *substructure* or *submodel* of  $M$  if  $|N| \subset |M|$ , the values of all constant symbols agree between  $N$  and  $M$ , and so are the values of all function and relation symbols (when they are applied to elements from  $|N|$ ).

**Definition I.1.21.** We say that a map  $f$  between two  $\mathcal{L}$ -structures  $f : N \rightarrow M$  is an *elementary embedding* if:

1.  $f$  is injective,
2.  $f(N)$ , with the suitable interpretations, is a substructure of  $M$  (and we will therefore assume, without loss of generality, that  $N$  is a substructure of  $M$ ),
3. for any formula  $\varphi(x_1, \dots, x_n)$  and every  $a_1, \dots, a_n \in |N|$ ,  $N \models \varphi(a_1, \dots, a_n) \iff M \models \varphi(a_1, \dots, a_n)$ .

In this case, we will often abuse notation and say that  $N$  is an *elementary submodel* (or *substructure*) of  $M$  and denote it by  $N \leq M$ .

*Remark I.1.22.* If  $N \leq M$  then clearly  $N \equiv M$ . Moreover, consider the language  $\mathcal{L}_N$ , obtained from  $L$  by adding a constant symbol  $c_n$  for every  $n \in N$ . Then, interpreting each  $c_n$  as  $n$ , we can view  $N$  and  $M$  as  $\mathcal{L}_N$  structures. Now if  $N \leq M$  as  $\mathcal{L}$ -structures, we have that  $N \equiv M$  as  $\mathcal{L}_N$  structures.

We can now state a stronger form of Sela's remarkable theorem:

**Theorem I.1.23** ([16, et seq.]). *Let  $2 \leq m < n \leq \omega$  and let  $f : F_m \rightarrow F_n$  be the natural embedding (that is,  $F_n = f(F_m) * F_{n-m}$ ). Then  $f$  is an elementary embedding.*

A converse of this theorem, was proven by Perin:

**Theorem I.1.24** ([13]). *Let  $F$  be a finitely-generated, non-abelian free group and let  $H$  be a subgroup of  $F$ . If  $H \leq F$  then  $H$  is a free factor of  $F$ .*

We will sketch a proof of this result, different to the standard one appearing in the literature, later on; the proof that we will sketch is a corollary of a relative version of the following theorem.

**Definition I.1.25.** Let  $M$  be an  $\mathcal{L}$ -structure, and let  $\bar{a} = (a_1, \dots, a_n) \in |M|^n$  be an  $n$ -tuple of elements of  $|M|$ . The *type* of  $\bar{a}$  is

$$\text{tp}^M(\bar{a}) = \{\varphi(x_1, \dots, x_n) \mid M \models \varphi(\bar{a})\}.$$

More generally, an  $\mathcal{L}$ -*type* of arity  $n$ ,  $p(x_1, \dots, x_n)$ , is a maximal set of consistent formulas with  $n$  free variables (by maximal, we mean that for every  $\varphi(x_1, \dots, x_n)$ , either  $\varphi(\bar{x}) \in p(\bar{x})$  or  $\neg\varphi(\bar{x}) \in p(\bar{x})$ ; note that the type of a tuple coming from a structure is always maximal).

*Remark I.1.26.* When it is clear from the context, we will omit the superscript  $M$  when referring to types of tuples of elements from  $M$ . One can also define types over sets of parameters  $A$ , by allowing parameters from  $A$  to appear in the formulas in the type. The type of a tuple  $\bar{a}$  over a set of parameters  $A$  is usually denoted by  $\text{tp}(\bar{a}/A)$ .

Free groups are commonly defined by their *universal property*: the free group  $F_n$  maps onto any  $n$ -generated group  $G$  by mapping the basis of  $F_n$  to the  $n$  generators of  $G$ . A similar-spirited phenomenon occurs also from a model-theoretic perspective:

**Theorem I.1.27** ([14]). *Let  $F$  be a non-abelian free group and let  $\bar{a}$  and  $\bar{b}$  be two  $n$ -tuples of elements from  $F$ . If  $\text{tp}(\bar{a}) = \text{tp}(\bar{b})$  then there is an automorphism  $f : F \rightarrow F$  such that  $f(a_i) = b_i$ .*

*Moreover, if  $F$  is finitely generated,  $A$  is a subgroup of  $F$  and  $\text{tp}(\bar{a}/A) = \text{tp}(\bar{b}/A)$  then there is an automorphism  $f : F \rightarrow F$  which maps  $\bar{a}$  to  $\bar{b}$ , and which restricts to the identity on  $A$ .*

In the next section, we will prove this theorem for  $F_2$ ; this was originally proven by Nies [11], but the proof that we give is different to Nies' original proof, and is one of a more topological flavour (it also resembles the proof of Theorem I.1.27 more closely).

## I.2 Homogeneity in $F_2$

In this section, we will prove a "model-theoretic" universal property for the free group of rank 2; that is, we will show that if two tuples of elements in  $F_2$  are indistinguishable from a first-order logic perspective, then there is an automorphism of  $F_2$  taking one to the other. More formally, we will prove the following theorem:

**Theorem I.2.1** ([11]). *Let  $\bar{a} = (a_1, \dots, a_n)$  and  $\bar{b} = (b_1, \dots, b_n)$  be two tuples of variables in  $F_2$ . If  $\text{tp}(\bar{a}) = \text{tp}(\bar{b})$  then there is an automorphism  $f : F_2 \rightarrow F_2$  with  $f(a_i) = b_i$ .*

We remark that the converse to this statement is easy to prove:

**Exercise III.** Let  $f$  be an automorphism of a non-abelian, finitely generated free group  $F$ , and let  $\bar{a}$  be a tuple of elements from  $F$ . Show that  $\text{tp}(\bar{a}) = \text{tp}(f(\bar{a}))$ .

Theorem I.2.1 was originally proven by Nies in 2003, but the proof that we give is a topological one, reminiscent of the general proof of Perín and Sklinos. We begin with the (rather easy) task of constructing a *homomorphism*  $f : F_2 \rightarrow F_2$  with  $f(a_i) = b_i$ .

**Lemma I.2.2.** *There is a homomorphism  $f : F_2 \rightarrow F_2$  mapping  $\bar{a}$  to  $\bar{b}$ .*

*Proof.* Let  $g$  and  $h$  be a free basis for  $F_2$ , and write each  $a_i$  as a word in the generators  $g$  and  $h$ ; we fix the notation  $a_i = w_{a_i}(g, h)$ . Therefore, for each  $a_i$ ,  $F_2 \models \exists x \exists y a_i = w_{a_i}(x, y)$  and

$$F_2 \models \varphi_{\bar{a}}(\bar{a}) = \exists x \exists y \bigwedge_{i=1}^n a_i = w_{a_i}(x, y).$$

It follows that  $F_2 \models \varphi_{\bar{a}}(\bar{b})$ , which implies that there are  $g', h' \in F_2$  such that for every  $i$ ,  $b_i = w_{a_i}(g', h')$ . This yields a homomorphism  $f_{\bar{a}} : F_2 \rightarrow F_2$  with  $f_{\bar{a}}(a_i) = b_i$ .  $\square$

Reversing the roles of  $\bar{a}$  and  $\bar{b}$ , we also obtain  $f_{\bar{b}} : F_2 \rightarrow F_2$  with  $f_{\bar{b}}(b_i) = a_i$ . Now set  $f = f_{\bar{b}} \circ f_{\bar{a}}$ . Our next goal, is to ensure that  $f$  is an automorphism. To do so, we will show that finitely generated, non-abelian free groups satisfy two properties defined by Heinz Hopf:

**Definition I.2.3.** A group  $G$  is called

1. *Hopfian*, if it is not isomorphic to any of its proper quotients; in other words, every epimorphism  $G \rightarrow G$  is an automorphism.
2. *co-Hopfian*, if it is not isomorphic to any of its proper subgroups; in other words, every monomorphism  $G \rightarrow G$  is an automorphism.

*Remark I.2.4.* A cautious reader would have probably noticed that free groups are *not* co-Hopfian; in fact, every two non-commuting elements in  $F_2$  generate a copy of  $F_2$ . However, free groups satisfy a *relative* version of this property.

**Theorem I.2.5.** *Let  $F$  be a finitely generated, non-abelian free group, and let  $H$  be a subgroup of  $F$  which is not contained in a proper free factor of  $F$ . Then every monomorphism  $f : F \rightarrow F$  whose restriction to  $H$  is the identity is an automorphism.*

We remind that a subgroup  $H$  of a group  $G$  is a *free factor* if  $G$  admits a free product decomposition of the form  $G = H * H'$ . This means that  $G$  has a presentation of the form  $\langle S_H, S_{H'} | R \rangle$  such that  $S_H$  and  $S_{H'}$  generate  $H$  and  $H'$  respectively, and each relation in  $R$  is written with generators coming from *exactly one* of  $X_H$  or  $X_{H'}$ . Free products admit a nice topological description:

**Exercise IV.** Let  $X$  and  $Y$  be two path connected topological spaces, and let  $X \vee Y$  be their wedge sum. Prove that  $\pi_1(X \vee Y) = \pi_1(X) * \pi_1(Y)$ .

We will not prove Theorem I.2.5 today, but it is worth mentioning that it follows rather easily from the *Shortening Argument* Theorem II.3.25. However, we will prove that free groups are Hopfian.

**Definition I.2.6.** A group  $G$  is called *residually finite* if for every  $1 \neq g \in G$  there is a finite quotient  $q : G \rightarrow Q$  such that  $q(g) \neq 1$ .

**Lemma I.2.7.** *Let  $G$  be a finitely generated, residually finite group. Then  $G$  is Hopfian.*

*Proof.* Let  $f : G \rightarrow G$  be an epimorphism, and suppose for a contradiction that there is  $1 \neq g \in G$  in  $\ker f$ . Since  $G$  is residually finite, there is a finite quotient  $q : G \rightarrow Q$  such that  $q(g) \neq 1$ . Consider the collection of quotients  $q_i = q \circ f^i : G \rightarrow Q$ ; we will show that  $q_i \neq q_j$  for  $i \neq j$ , contradicting the fact that there are only finitely many homomorphisms  $G \rightarrow Q$ .

Let  $i < j$ , and note that  $f^i$  is surjective so there is  $h \in G$  such that  $f^i(h) = g$ . It follows that  $q_i(h) = \alpha(f^i(h)) \neq 1$ . On the other hand,

$$q_j(h) = \alpha(f \circ \dots \circ f \circ f^i(h)) = \alpha(f \circ \dots \circ f(g)) = \alpha(1) = 1.$$

□

**Corollary I.2.8.** *Finitely generated, non-abelian free groups are Hopfian.*

*Proof.* By Lemma I.2.7, it is enough to prove that such an  $F$  is residually finite. We will give a simple topological proof. Suppose that  $F$  is generated by  $n$  elements, and realize  $F$  as the fundamental group of a rose graph  $R$  with  $n$  petals. Recall that finite-sheeted covering spaces of  $R$  stand in one-to-one correspondence with finite-index subgroups of  $F$ . It is therefore enough to construct for every  $g \in F$  a finite-sheeted covering  $R_g$  of  $R$  such that  $g \notin \pi_1(R_g)$ : indeed,  $[F : \pi_1(R_g)] = n < \infty$ , and one readily sees that  $N = \bigcap_{[F:H] \leq n} H$  (note that, since  $F$  is finitely generated, there are only finitely many groups participating in the intersection) is a finite-index normal subgroup of  $F$  which doesn't contain  $g$ . The map  $F \rightarrow F/N$  is the desired finite quotient.

To construct  $R_g$ , we note that a graph  $\Gamma$  covers  $R$  if and only if every vertex admits an in-going and out-going edge for each petal of  $R$ ; moreover,  $g \notin \pi_1(\Gamma)$  if and only if the lift of  $g$  to  $\Gamma$  does not close a loop. So to construct  $R_g$ , we fix a basepoint  $x$  and draw a loop that traverses the word  $g^2$ . Since every edge in that loop leaves one vertex and enters another, one can add edges between the vertices of the loop to obtain a covering  $R_g$  of  $R$ . Since no new vertices were added to the loop,  $R_g$  has finitely many vertices and it is a finite-sheeted cover of  $R$ . □

**A drawing will be added later**

We will also use the following auxiliary lemma in the proof of Theorem I.2.1:

**Lemma I.2.9.** *There is a formula  $\psi_2(x, y)$  such that for  $g, h$  in a non-abelian free group  $F$ ,  $F \models \psi_2(g, h)$  if and only if  $\langle g, h \rangle$  is a free group of rank 2.*

**Exercise V.** Prove that one can't form such formulas  $\psi_k(x_1, \dots, x_k)$  for  $k > 2$ . *Hint:* what can be said about the sentence  $\exists x_1 \exists x_2 \forall x_3 \dots \forall x_k \psi_2(x_1, x_2) \wedge \neg \psi_k(x_1, \dots, x_k)$ ?

*Proof of Lemma I.2.9.* The formula  $\psi_2$  is incredibly simple: we set  $\psi_2(x, y) = [x, y] \neq 1$ . Suppose now that  $F \models \psi_2(g, h)$ . It follows that  $\langle g, h \rangle$  is non-abelian, so it can't be a free group of rank 1 (i.e.  $\mathbb{Z}$ ). Since every subgroup of a free group is free (this statement is known as the Nielsen-Schreier theorem, and it follows from the fact that every covering space of a graph is a graph, and fundamental groups of graphs are always free), and since a free group with a basis of size  $k > 2$  can't be generated by 2 generators, we deduce that  $\langle g, h \rangle = F_2$ . □

We are finally ready to prove that  $F_2$  is homogeneous:

*Proof of Theorem I.2.1.* Recall that we have two tuples in  $F_2$ ,  $\bar{a}$  and  $\bar{b}$ , with  $\text{tp}(\bar{a}) = \text{tp}(\bar{b})$ . Let  $g, h$  be a basis of  $F_2$ , and note that

$$F_2 \models \chi_{\bar{a}}(\bar{a}) = \exists x \exists y \left( \left( \bigwedge_{i=1}^n a_i = w_{a_i}(x, y) \right) \wedge ([x, y] \neq 1) \right).$$

Now  $F_2 \models \chi_{\bar{a}}(\bar{b})$  so there are  $g', h'$  such that  $w_{a_i}(g', h') = b_i$  and  $\langle g', h' \rangle \cong F_2$ . By mapping  $g$  and  $h$  to  $g'$  and  $h'$  respectively, we get a homomorphism  $f_a : F_2 \rightarrow F_2$  which maps  $\bar{a}$  to  $\bar{b}$ . Moreover, the image of  $f_a$  is isomorphic to  $F_2$ , and since  $F_2$  is Hopfian by Corollary I.2.8, we deduce that  $f_a$  is injective. Similarly, we obtain an injective homomorphism  $f_b : F_2 \rightarrow F_2$  which maps  $\bar{b}$  to  $\bar{a}$ . Their composition  $f = f_b \circ f_a$  is a monomorphism of  $F_2$  which fixes  $\bar{a}$ .

If  $H = \langle \bar{a} \rangle$  is not contained in a proper free factor of  $F_2$ , then the relative co-Hopf property Theorem I.2.5 implies that  $f$  is an automorphism; this implies that  $f_a$  is an isomorphism. Otherwise, we have that  $\bar{a}$  is contained in a proper free factor of  $F_2$ .

Suppose now that  $\bar{a}$  is contained a proper free factor  $K$ ; such a free factor of  $F_2$  must be a free group of rank 1 (that is,  $\mathbb{Z}$ ), so write  $K = \langle g \rangle$ . In this situation, every  $a_i$  is a power of  $g$ . We first claim that  $g \in \text{Im}(f_b)$ . Write  $a_1 = g^{m_1}$  so  $F_2 \models \chi_1(\bar{a}) = \exists x a_1 = x^{m_1}$ ; it follows that  $F_2 \models \chi_1(\bar{b})$  and there is some  $g' \in F_2$  such that  $b_1 = g'^{m_1}$ . Since  $f_b(b_1) = a_1$ , we must have that  $f_b(g') = g$  (recall that roots of elements in a free group are unique).

To finish the proof, it suffices to show that  $\langle g' \rangle$  is also a free factor: if this is the case, the restriction  $f_b|_{\langle g' \rangle} : \langle g' \rangle \rightarrow \langle g \rangle$  which maps each  $b_i$  to  $a_i$  can be extended to an automorphism of  $F_2$ . Since  $f_b$  is injective, it is an isomorphism  $F_2 \rightarrow \text{Im}(f_b)$ . It is therefore enough to prove that  $K \leq \text{Im}(f_b)$  is a free factor of  $\text{Im}(f_b)$ . In the spirit of Corollary I.2.8, we will give a topological proof <sup>1</sup>.

Recall that in Exercise IV we saw that if a space  $Z$  is the wedge of two spaces  $X$  and  $Y$ , then  $\pi_1(X)$  and  $\pi_1(Y)$  are free factors of  $\pi_1(Z)$ . Since  $\langle g \rangle$  is a free factor of  $F_2$ , we can realize  $F_2$  as the fundamental group of a two-petaled rose  $R$  in which one of the petals corresponds to  $g$ . There is a (possibly infinite-sheeted) cover  $R'$  of  $R$  which corresponds to the subgroup  $\text{Im}(f_b)$ ; denote its basepoint by  $v$ . Since  $g \in \text{Im}(f_b)$ , there is a single-edged loop, which is a lift of  $g$  to  $R'$ , based at  $v$ . It

<sup>1</sup>In fact, the following more general claim holds: whenever  $G$  is a finitely generated group,  $K$  is a free factor of  $G$  and  $H \leq G$ ,  $K \cap H$  is a free factor of  $H$ . This is a simple consequence of the [Kurosh subgroup theorem](#). In more detail, there is an action of  $G$  on a simplicial tree  $T$  with trivial edge stabilizers, and such that  $K$  fixes a vertex  $v \in T$ . Any  $H \leq G$  also acts on  $T$  with trivial edge stabilizers, and  $K \cap H$  fixes  $v$ , so  $K \cap H$  is a free factor of  $H$ .



follows that  $R'$  is the wedge of this loop and another graph  $\Gamma$ . Therefore

$$\text{Im}(f_b) = \pi_1(R') = \langle g \rangle * \pi_1(\Gamma)$$

□

A drawing will be added later

# II

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## Algebraic Geometry over Groups

**W**E dive into understanding the first-order theory and start with the simplest type of formulas: those without quantifier and without inequalities, or in other words collections of systems of equations over free groups. Such formulas correspond to homomorphisms from a finitely generated group to a free group, and these can be encoded into a tree-like diagram called the *Makanin-Razborov* diagram. The vertices of such a diagram are *limit groups*, which will be introduced and studied in this chapter.

Our quest towards understanding the first-order theory of a finitely generated group  $G$  begins with understanding the behaviour of the simplest type of formulas: *positive* atomic formulas, or in other words atomic formulas that do not involve inequalities. Such formulas are always equivalent to one of the form  $w(x_1, \dots, x_n) = 1$  (where  $w$  is a word in a free group of rank  $n$ ).

**Definition II.0.1.** A (group theoretic) *equation* in variables  $\bar{x} = (x_1, \dots, x_n)$  is simply an element  $w \in F(\bar{x})$ . We will sometimes refer to the equation  $w$  as  $w(\bar{x})$  or  $w(\bar{x}) = 1$ , depending on the context. An *inequality* (or an *inequation*) is an expression of the form  $w(\bar{x}) \neq 1$  where  $w \in F(\bar{x})$ .

An *equation over a group  $G$*  in variables  $\bar{x}$  is an element  $w \in F(\bar{x}) * G$ . Recall that such  $w$  is an alternating product of elements from  $F(\bar{x})$  and  $G$ . As before, we will often refer to  $w$  as  $w(\bar{x}, \bar{a})$  where  $\bar{a}$  is a tuple of elements from  $G$ . An *inequality over a group  $G$*  is an expression of the form  $w(\bar{x}, \bar{a}) \neq 1$ .

Note that we can always refer to an equation  $w(\bar{x})$  as an equation over a group  $G$ . In this case we say that the equation is *without parameters*.

**Notation II.0.2.** Given a tuple of variables  $\bar{x} = (x_1, \dots, x_n)$ ,  $w \in F(\bar{x})$  and  $\bar{g} = (g_1, \dots, g_n) \in G^n$ , we write  $w(\bar{g})$  to denote the element of  $G$  obtained from  $w$  by replacing each  $x_i^{\pm 1}$  with the corresponding  $g_i^{\pm 1}$ . For  $w \in F(\bar{x}) * G$ ,  $w(\bar{g}, \bar{a})$  is defined similarly.

As with "standard" equations, group-theoretic equations can also have *solutions*:

**Definition II.0.3.** A *solution* to an equation  $w(\bar{x}, \bar{a}) = 1$  over a group  $G$  consists of a tuple  $\bar{g} = (g_1, \dots, g_n)$  of elements from  $G$ , of the same arity as  $\bar{x}$ , such that  $w(\bar{g}, \bar{a}) = 1$  holds in  $G$ .

**Examples II.0.4.** 1. The set of solutions to the equation  $[x, y] \in F(x, y)$  over any group  $G$  is set of all pairs  $(g_1, g_2)$  such that  $g_1$  and  $g_2$  commute. In a free group  $F$ , such a pair of commuting elements must lie in a common cyclic subgroup of  $F$ , that is, there exists  $g \in F$  such that  $g_1, g_2 \in \langle g \rangle$ .

2. Now fix a group  $G$  and let  $a \in G$ . Consider the equation  $w = [x, a] \in F(x) * G$  over  $G$ . Then the set of solutions of  $w$  is the centraliser of  $a$  in  $G$ .

Our next observation, is that there is a one-to-one correspondence between the set of solutions to a system of equations  $\Sigma(\bar{x}, \bar{a}) = \{w_i(\bar{x}, \bar{a})\}_{i \in I} \subset F(\bar{x}) * G$  over a group  $G$  and the set of homomorphisms from the group

$$G_\Sigma = \langle \bar{x}, \bar{a} \mid R(\bar{a}) \cup \Sigma(\bar{x}, \bar{a}) \rangle$$

to  $G$  which map  $\bar{x}$  to  $\bar{a}$ ; here,  $R(\bar{a})$  is a set of relations for which  $\langle \bar{a} \mid R(\bar{a}) \rangle$  is a presentation of the subgroup of  $G$  generated by  $\bar{a}$ .

If  $\bar{g}$  is a solution to  $\Sigma(\bar{x}, \bar{a}) = 1$ , there exists a homomorphism  $\varphi : G_\Sigma \rightarrow G$  mapping  $\bar{x}$  to  $\bar{g}$  and  $\bar{a}$  to  $\bar{a}$ ; on the other hand, given such a homomorphism  $\varphi$ , the tuple  $\varphi(\bar{x})$  is a solution to  $\Sigma(\bar{x}, \bar{a}) = 1$  over  $G$ . Therefore, in order to understand the behaviour of atomic formulas, and more generally positive formulas without quantifiers, over  $G$ , we need to understand the different spaces  $\text{Hom}(G_\Sigma, G)$ . This amounts to understanding the space of all homomorphisms from finitely generated groups to  $F$ .

**Examples II.0.5.** 1.  $\text{Hom}(F_n, F) = F^n$ .

2.  $\text{Hom}(\mathbb{Z}^n, F)$  can be described as follows: let  $f : \mathbb{Z}^n \rightarrow F$  and denote by  $p : \mathbb{Z}^n \rightarrow \mathbb{Z}$  the projection to the first coordinate. Then there is an automorphism  $\alpha \in \text{Aut}(\mathbb{Z}^n) = \text{GL}_n(\mathbb{Z})$  such that  $f \circ \alpha$  factors through  $p$ . Since homomorphisms from  $\mathbb{Z}$  to  $F$  correspond to choosing an element of  $F$ ,  $\text{Hom}(\mathbb{Z}^n, F)$  can be parametrized by  $\text{GL}_n(\mathbb{Z}) \times F$  (but different points in  $\text{GL}_n(\mathbb{Z}) \times F$  can yield the same point in  $\text{Hom}(\mathbb{Z}^n, F)$ ).
3. A similar phenomenon occurs in  $\text{Hom}(\pi_1(\Sigma), F)$ , where  $\Sigma$  is an orientable surface of genus  $n$ , and  $F$  is of rank  $n$ . Let  $f : \pi_1(\Sigma) \rightarrow F$ , and denote by  $r : \pi_1(\Sigma) \rightarrow F$  the map induced by “fillin” the surface, turning it into a solid handlebody. Then there is  $\alpha \in \text{Aut}(\pi_1(\Sigma))$  such that  $f \circ \alpha$  factors through  $r$ .

## II.1 From equations over free groups to limit groups

The contents of this section are based on Champatier’s and Guirardel’s introductory paper [4]. Some of the proofs appearing here are omitted in [4]; however, proofs of more advanced theorems appear in Champatier’s and Guirardel’s paper and we recommend an enthusiastic reader to complement this section with [4].

In what follows, we will restrict our attention to the case where  $G = F$  is a non-abelian free group. With slight modifications, the constructions, assertions and observations described in this chapter apply to any finitely generated group  $G$ . We invite the reader to think and make these modifications wherever they apply.

Consider the collection of all homomorphisms from finitely generated groups to  $F$ . In order to understand this collection, we first turn it into a topological space by equipping it with a topology; however, this will not be enough for our purposes. It is much more convenient to work with compact topological spaces. In order to compactify this space, we will add to it “points at infinity”, or *limit* points. These will be homomorphisms from finitely generated groups to groups which are not free, namely *limit groups*.

We begin by taking a topological approach towards limit groups; later on we will give an equivalent algebraic definition of limit groups, as well as a residual one. The algebraic definition will later reveal its full geometri power to us: it is through this construction that one gets an action of a limit group on an interesting metric space.

### II.1.1 Marked groups

As part of his study of groups of polynomial growth, Gromov came up with an idea as to how to equip a set of groups with a topology [6]. This idea led Grigorchuk to define a topological *space of marked groups* in his work on groups of intermediate growth from 1985 [5]. This topological space gives a natural setting in which to define limit groups.

Given a finitely generated group  $G$  with a generating tuple  $S = (g_1, \dots, g_n)$ , every homomorphism  $f$  from  $G$  to a free group  $F$  yields a possible generating tuple for the free group  $\text{Im}(f)$ :  $f(S) = \{f(g_1), \dots, f(g_n)\}$  (note that  $f(S)$  does not have to be a basis for  $\text{Im}(f)$ ).

**Definition II.1.1.** A *marked group* is a pair of the form  $(G, S)$  where  $G$  is a group and  $S$  is a finite tuple whose elements generate  $G$ . Given  $n \in \mathbb{N}$ , denote by  $\mathcal{G}_n$  the set of all marked groups  $(G, S)$  with  $|S| = n$ .

*Remark II.1.2.* We emphasize that  $S$  in Definition II.1.1 above is a tuple, that is  $S$  is ordered and repetitions are allowed. In addition, if  $G, (g_1, \dots, g_n)$  and  $G', (g'_1, \dots, g'_n)$  are two marked groups, and the map  $g_i \mapsto g'_i$  extends to an isomorphism  $G \rightarrow G'$ , we consider  $G, (g_1, \dots, g_n)$  and  $G', (g'_1, \dots, g'_n)$  as the same point in  $\mathcal{G}_n$ .

The next step is to define a topology on  $\mathcal{G}_n$ ; we do so by defining a metric on  $\mathcal{G}_n$ . Note that a priori this metric is a pseudometric, but identifying points as in Remark II.1.2 makes it a metric. Given  $(G, S), (G', S') \in \mathcal{G}_n$ , set  $v((G, S), (G', S'))$  to be the maximal  $N \in \mathbb{N} \cup \{\infty\}$  such that  $w(S) = 1$  in  $G$  if and only if  $w(S') = 1$  in  $G'$  for every word  $w \in F_n$  of length at most  $N$  (if  $(G, S)$  and  $(G', S')$  are isomorphic as marked groups, and they represent the same point in  $\mathcal{G}_n$ , set  $v((G, S), (G', S')) = \infty$ ).

**Definition II.1.3.** The metric  $d_n : \mathcal{G}_n \times \mathcal{G}_n \rightarrow \mathbb{R}_{\geq 0}$  is given by

$$d_n((G, S), (G', S')) = e^{-v((G, S), (G', S'))}.$$

We remind the reader that the *Cayley graph* of a group  $G$  with respect to a (finite) generating set  $S$  is a labelled, oriented graph whose vertices are the elements of  $G$ , and  $g, h \in G$  are connected by an edge with a label  $s$  if and only if  $h = gs$  (or  $g = hs$ , in which case the edge is oriented from  $h$  to  $g$ ). We denote the Cayley graph of  $G$  with respect to  $S$  by  $X(G, S)$ . The ball of radius  $N$  around 1 in  $X(G, S)$  (which is isomorphic to any  $N$ -ball in  $X(G, S)$ ) will be denoted by  $B_N(X(G, S))$ .

*Remark II.1.4.* Note that  $v((G, S), (G', S'))$  above can be replaced with the following quantity: the maximal  $N \in \mathbb{N}$  for which the Cayley graphs  $X(G, S)$  and  $X(G', S')$  are isomorphic. This  $N$  is smaller than  $v((G, S), (G', S'))$ , but the topologies induced by these metric agree. We will use both definitions interchangeably (and sometimes use  $v((G, S), (G', S'))$  to refer to  $N$  above), and choose the one which makes our proofs easier to follow.

Finally, we can give an alternative definition of limit groups:

**Definition II.1.5.** A group  $G$  is a *limit group* if there is  $n \in \mathbb{N}$  and a generating tuple  $S$  of  $G$  of size  $n$  such that  $(G, S)$  is the limit of a sequence  $(G_i, S_i)$  in  $\mathcal{G}_n$  and every  $G_i$  is a free group.

**Examples II.1.6.** We give a few examples that illustrate convergence in the space of marked groups:

1. The marked group  $(\mathbb{Z}, 1)$  is the limit of the sequence  $(\mathbb{Z}/n\mathbb{Z}, 1)_{n \in \mathbb{N}}$  in  $\mathcal{G}_1$ . Indeed, the balls of radius  $n/100$  in  $X(\mathbb{Z}, 1)$  and  $X(\mathbb{Z}/n\mathbb{Z}, 1)$  are isomorphic (for  $n$  large enough).
2.  $(\mathbb{Z}^2, ((1, 0), (0, 1)))$  is the limit of the sequence  $(\mathbb{Z}, (1, n))_{n \in \mathbb{N}}$  in  $\mathcal{G}_2$ . This is best explained with a drawing: **A figure illustrating this will be added later.** This implies that  $\mathbb{Z}^2$  (and in fact, any finitely generated free abelian group) is a limit group.

**Exercise VI.** 1. Prove that every finitely generated, residually finite group is the limit of finite groups in the space of marked groups.

2. Prove that if  $(G, S) \in \mathcal{G}_n$  is a finitely presented marked group, then there is a neighborhood  $N(G, S)$  in  $\mathcal{G}_n$  such that every  $(G', S') \in N(G, S)$  is a quotient of  $(G, S)$  (under the map which sends  $S$  to  $S'$ ).

Convergence in the space of marked groups is not always easy to understand; we will later give alternative descriptions of limit groups which will help us to give more examples.

We next turn to explain how limit groups compactify the space of free groups within  $\mathcal{G}_n$ ; the explanation is rather elementary, and it will be mostly left as an exercise.

Note that

$$\overline{\{(G, S) \in \mathcal{G}_n | G \text{ is free}\}} = \{(G, S) \in \mathcal{G}_n | G \text{ is free}\} \cup \{(G, S) \in \mathcal{G}_n | G \text{ is a limit group}\}$$

and it is therefore enough to establish that  $\mathcal{G}_n$  is a compact space. To do so, we identify  $\mathcal{G}_n$  with a subset of  $2^{F_n}$ . By Tychonoff's Theorem,  $2^{F_n}$  is compact, so it suffices to prove the following two claims:

**Claim II.1.7.** *The topology that  $\mathcal{G}$  inherits from  $2^{F_n}$  coincides with the topology induced by the metric  $d_n$ .*

**Claim II.1.8.**  *$\mathcal{G}$  is a closed subset of  $2^{F_n}$ .*

Endow  $F_n$  with a basis  $\{x_1, \dots, x_n\}$  and identify  $\mathcal{G}$  with a subset of  $2^{F_n}$  in the following manner: every  $(G, S = (s_1, \dots, s_n)) \in \mathcal{G}_n$  can be seen as a quotient of  $F_n$  through the map  $q_{(G,S)} : F_n \rightarrow G$  which sends  $x_i$  to  $s_i$ . Note that  $(G, S)$  and  $(G', S')$  are isomorphic as marked groups if and only if the maps  $q_{(G,S)} : F_n \rightarrow G$  and  $q_{(G',S')} : F_n \rightarrow G'$  have the same kernel, and therefore  $\mathcal{G}_n$  can be identified with the set of normal subgroups of  $F_n$  (which is a subset of  $2^{F_n}$ ), which we denote by  $\mathcal{N}_n$ .

$\mathcal{N}_n$  inherits the product topology from  $2^{F_n}$ ; a sub-basis for this topology is given by:

$$U_g = \{K \in \mathcal{N}_n \mid g \in K\} \quad \text{and} \quad V_g = \{K \in \mathcal{N}_n \mid g \notin K\}.$$

$\mathcal{N}_n$  also comes equipped with the metric that we previously defined on  $\mathcal{G}$ . This metric can also be described as follows: given  $K, K' \in \mathcal{N}_n$ , let

$$v_{\mathcal{N}}(K, K') = \max\{N \in \mathbb{N} \cup \infty \mid K \cap B_N(F_n, \{x_1, \dots, x_n\}) = K' \cap B_N(F_n, \{x_1, \dots, x_n\})\}.$$

We now define

$$d_{\mathcal{N}_n}(K, K') = e^{-v_{\mathcal{N}}(K, K')}.$$

Note that indeed  $v((G, S), (G', S')) = v_{\mathcal{N}}(\ker(q_{(G,S)}), \ker(q_{(G',S')}))$ .

**Exercise VII.** Prove Claim II.1.7: the topology that  $\mathcal{N}_n$  inherits as a subspace of  $2^{F_n}$  coincides with the topology induced by the metric  $d_{\mathcal{N}_n}$  defined above.

**Exercise VIII.** Prove Claim II.1.8:  $\mathcal{N}_n$  is a closed subset of  $2^{F_n}$ . In other words, consider a sequence  $(K_i)_{i \in \mathbb{N}}$  that converges to  $K \in 2^{F_n}$  and prove that  $K$  must be a normal subgroup of  $F_n$ .

## II.1.2 Algebraic limit groups

We continue by giving another description of limit groups. Recall that limit groups were defined as a set of points that compactify the collection of homomorphisms from finitely generated groups to a free group. The following definition gives another limiting process, and highlights the existence of a *limiting homomorphism* from a finitely generated group to a limit group. The process described in this subsection captures some of the aspects of taking limits in the *equivariant Gromov-Hausdorff topology*; we will see at a later point (in Section II.3.1 that every limit group comes equipped with an action on an  $\mathbb{R}$ -tree, obtained as an equivariant Gromov-Hausdorff limit of a sequence of group actions).

**Definition II.1.9.** Let  $G$  be a finitely generated group and let  $(\varphi_n)_{n \in \mathbb{N}} \in \text{Hom}(G, F)^\mathbb{N}$  be a sequence of homomorphisms from  $G$  to a non-abelian free group  $F$ . The sequence is called *stable* if for every  $g \in G$ , the sequence  $(\varphi_n(g))_{n \in \mathbb{N}} \in G^\mathbb{N}$  is eventually always 1, or eventually never 1. The *stable kernel* of  $(\varphi_n)_{n \in \mathbb{N}}$  is defined as

$$\underline{\ker}((\varphi_n)_{n \in \mathbb{N}}) = \{g \in G \mid \text{the sequence } (\varphi_n(g))_{n \in \mathbb{N}} \text{ is eventually always } 1\}.$$

*Remark II.1.10.* Note that  $\underline{\ker}((\varphi_n)_{n \in \mathbb{N}})$  is a normal subgroup of  $G$ . In addition, we remark that stable sequences of homomorphisms are by no means special: a standard diagonalization argument shows that every sequence of homomorphisms  $(\varphi_n)_{n \in \mathbb{N}} \in \text{Hom}(G, F)^\mathbb{N}$  has a stable subsequence (as long as  $G$  is countable, which is always the case since we assume that  $G$  is finitely generated).

**Definition II.1.11.** An *(algebraic) limit group* is a quotient of the form  $L = G / \underline{\ker}((\varphi_n)_{n \in \mathbb{N}})$  for some stable sequence  $(\varphi_n)_{n \in \mathbb{N}} \in \text{Hom}(G, F)^\mathbb{N}$ . We denote the quotient map by  $\varphi_\infty : G \twoheadrightarrow L$  and call it the *limit map* associated to  $(\varphi_n)_{n \in \mathbb{N}}$ .

A careful inspection of Definition II.1.11 shows that it coincides with Definition II.1.5:

**Lemma II.1.12.** *Let  $L$  be a group. Then  $L$  is a limit group if and only if it is an algebraic limit group.*

*Proof.* Suppose first that  $L$  is a limit group; in other words, there is  $n \in \mathbb{N}$ , a generating tuple  $S$  of  $L$  of size  $n$  and a sequence of marked groups  $(G_i, S_i) \in \mathcal{G}_n$  such that  $G_i$  is free for every  $i \in \mathbb{N}$  and

$$(G_i, S_i) \xrightarrow{i \rightarrow \infty} (L, S).$$



We will show that  $L$  is an (algebraic) limit group by constructing a stable sequence of homomorphisms  $(\varphi_i : F_n \rightarrow F)_{i \in \mathbb{N}} \in \text{Hom}(F_n, F)^{\mathbb{N}}$  for which  $L = F_n / \varprojlim (\varphi_i)_{i \in \mathbb{N}}$ .

We may assume that each of the groups  $G_i$  is a subgroup of  $F$ . Define  $\varphi_i : F_n \rightarrow F$  by mapping the standard generating tuple of  $F_n$  to the tuple  $(S_i) \in G_i^n \subset G^n$ . To show that this sequence is stable, let  $w \in F_n$ . If  $w(S) = 1$  in  $L$ , then for every  $(G_i, S_i)$  that is close enough to  $(L, S)$  in  $\mathcal{G}_n$  we have that  $w(S_i) = 1$ , so  $\varphi_i(w) = 1$ . Similarly, if  $w(S) \neq 1$  in  $L$ ,  $\varphi_i(w)$  is eventually never trivial. This also shows that the stable kernel  $\varprojlim (\varphi_i)_{i \in \mathbb{N}}$  coincides with  $\{w \in F_n \mid w(S) = 1\}$ , and hence  $L = F_n / \varprojlim (\varphi_i)_{i \in \mathbb{N}}$ .

For the converse, suppose that there is a group  $G$  generated by a tuple  $(g_1, \dots, g_n)$  and a stable sequence of homomorphisms  $(\varphi_i : G \rightarrow F_n)_{i \in \mathbb{N}} \in \text{Hom}(G, F_n)^{\mathbb{N}}$  such that  $L = G / \varprojlim (\varphi_i)_{i \in \mathbb{N}}$ . We will show that the marking

$$\left( L = G / \varprojlim (\varphi_i)_{i \in \mathbb{N}}, S = (g_1 \cdot \varprojlim (\varphi_i)_{i \in \mathbb{N}}, \dots, g_n \cdot \varprojlim (\varphi_i)_{i \in \mathbb{N}}) \right)$$

of  $L$  is the limit of the sequence  $(G_i = \varphi_i(G), S_i = (\varphi_i(g_1), \dots, \varphi_i(g_n)))_{i \in \mathbb{N}}$  in  $\mathcal{G}_n$ .

Note that for every  $w \in F_n$ , there exists  $i_w \in \mathbb{N}$  such that for  $i > i_w$ ,

$$w(S_i) = \varphi_i(w(g_1, \dots, g_n)) = 1 \text{ in } G_i \text{ if and only if } w(g_1, \dots, g_n) \in \varprojlim (\varphi_i)_{i \in \mathbb{N}},$$

or equivalently if  $w(S) = 1$  in  $L$ .

To finish, we will show that  $d_n((L, S), (G_i, S_i)) \leq e^{-N}$  for every  $N$ ; therefore, given some  $N$ , we need to find  $i_N$  such that for every  $i > i_N$  and every  $w \in F_n$  of length at most  $N$ ,  $w(S_i) = 1$  in  $G_i$  if and only if  $w(S) = 1$  in  $L$ . Since the number of words  $w \in F_n$  of length up to  $N$  is finite, choosing  $i_N = \max\{i_w \mid |w| \leq N\}$  completes the proof.  $\square$

## II.2 Residual properties and Noetherianity

Recall that a group  $G$  is called *residually finite* if every  $g \in G$  survives as a "non-trivial residue" in a finite quotient of  $G$  (see Definition 1.2.6). A simple observation is the following: if  $G$  is residually finite, then it is *fully residually finite*, meaning that for every finite subset  $S \subset G$  there is a finite quotient  $q : G \twoheadrightarrow Q$  such that  $Q$  is finite and  $q|_S$  is injective.

**Definition II.2.1.** A group  $G$  is *fully residually free* if for every finite subset  $S \subset G$  there is a free quotient  $q : G \twoheadrightarrow F$  such that  $F$  is free and  $q|_S$  is injective.

Our next goal is to establish that the class of limit groups coincides with the class of finitely generated, residually free groups, that is:

**Theorem II.2.2.** *A group  $G$  is a limit group if and only if it is finitely generated and fully residually free.*

One direction is easier than the other.

**Lemma II.2.3.** *Every finitely generated, fully residually free group is a limit group.*

*Proof.* Let  $G$  be a finitely generated, fully residually free group and let  $S$  be a generating tuple of  $G$  of size  $n$ . Let  $X_1 \subset X_2 \subset \dots$  be an exhaustion of  $G$  by finite sets. For each  $i$ , there is a homomorphism  $f_i : G \rightarrow F$  such that  $f_i$  is injective on  $X_i$ . Let  $(G_i, S_i) = (f_i(G), f_i(S))$ . We claim that

$$(G_i, S_i) \xrightarrow{i \rightarrow \infty} (G, S).$$

Given  $N \in \mathbb{N}$ , for every  $i$  large enough  $f_i$  is injective on  $B_N(X(G, S))$ . It follows that  $B_N(X(G, S)) \cong B_N(X(G_i, S_i))$  and  $d_n((G, S), (G_i, S_i)) \leq e^{-N}$ .  $\square$

The converse is a bit trickier to prove, and it requires us to show that free groups are *equationally Noetherian*, a term first coined by G. Baumslag, Miasnikov and Remeslennikov [2]. Recall that a ring  $R$  is *Noetherian* if every increasing sequence  $I_1 \subset I_2 \subset \dots$  of left ideals eventually stabilizes (or equivalently if every left ideal is finitely generated). We will prove that a similar phenomenon holds in free groups, where instead of ideals we consider solutions of systems of equations.

**Definition II.2.4.** A group  $G$  is called *equationally Noetherian* if the following holds: every system of equations  $\Sigma \subset G * F(\bar{x})$  with finitely many variables  $\bar{x} = (x_1, \dots, x_n)$  (and parameters from  $G$ ) admits a finite subsystem  $\Sigma_0 \subset \Sigma$ , such that the sets of solutions of  $\Sigma$  and of  $\Sigma_0$  coincide.

The fact that free groups are equationally Noetherian relies on Hilbert's basis theorem, which states that polynomial rings over Noetherian rings are Noetherian.

**Lemma II.2.5.** *Countable free groups are equationally Noetherian.*

*Proof.* Equational Noetherianity is inherited by subgroups; we will therefore prove the lemma for a free group of rank 2,  $F_2 = \langle x_1, x_2 \rangle$ , since every countable free group embeds in  $F_2$ .

$F_2$  embeds in  $\mathrm{SL}_2(\mathbb{Z})$  by mapping

$$x_1 \mapsto \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad x_2 \mapsto \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}.$$

We denote this embedding by  $\varphi : F_2 \rightarrow \mathrm{SL}_2(\mathbb{Z})$ . The fact that the subgroup of  $\mathrm{SL}_2(\mathbb{Z})$  generated by the two matrices above is a free group of rank 2 is standard, and can be easily verified by considering the action of  $\mathrm{SL}_2(\mathbb{Z})$  on the real plane  $\mathbb{R}^2$  and using the Ping Pong lemma with the sets  $\{(x, y) \in \mathbb{R}^2 \mid |x| > |y|\}$  and  $\{(x, y) \in \mathbb{R}^2 \mid |x| < |y|\}$  (a good explanation appears in the [Ping-Pong Lemma](#) Wikipedia article).

Let  $\Sigma \subset F_2 * F_n$  be a system of equations in  $F_2$  with variables  $\bar{y} = (y_1, \dots, y_n)$ . Let  $\Sigma' \subset \mathrm{SL}_2(\mathbb{Z}) * F_n$  be the corresponding system of equations in  $\mathrm{SL}_2(\mathbb{Z})$ , that is for every  $\sigma \in \Sigma$  define  $\sigma' \in \Sigma'$  to be the same equation where the parameters from  $F_2$  are replaced with their image under  $\varphi$  in  $\mathrm{SL}_2(\mathbb{Z})$ . Note that  $\sigma(\bar{g}) = 1$  in  $F_2$  (for  $\bar{g} \in F_2^n$ ) if and only if

$$\sigma'(\varphi(\bar{g})) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Regarding the  $n$  variables in each  $\sigma'$  as matrices with four entries, we get that  $\sigma'$  gives rise to four polynomial equations (with coefficients in  $\mathbb{Z}$ ) in  $4n$  variables  $\bar{z} = (z_1^1, z_2^1, z_3^1, z_4^1, \dots, z_1^n, z_2^n, z_3^n, z_4^n)$ , obtained by comparing the different entries with those of the identity matrix. Therefore, the system of equations  $\Sigma$  gives rise to a system of polynomial equations  $\Psi$  over  $\mathbb{Z}$ .

Consider the ideal  $(\Psi)$  in  $\mathbb{Z}[\bar{z}]$ ; by Hilbert's basis theorem,  $\mathbb{Z}[\bar{z}]$  is Noetherian, and therefore the ideal  $(\Psi)$  is finitely generated. Write  $(\Psi) = (\psi_1, \dots, \psi_k)$ . Each  $\psi_i$  was obtained from some  $\sigma'_i \in \Sigma'$ . It follows that  $\{\sigma'_1, \dots, \sigma'_k\} \subset \Sigma'$  is equivalent to  $\Sigma'$ , and therefore  $\{\sigma_1, \dots, \sigma_k\} \subset \Sigma$  is equivalent to  $\Sigma$ .  $\square$

**Corollary II.2.6.** *Every limit group is fully residually free.*

*Proof.* Let  $L$  be a limit group, that is there is a generating tuple  $S$  of  $L$  with  $|S| = n$ , and a sequence  $(G_i, S_i)_{i \in \mathbb{N}}$  in  $\mathcal{G}_n$  such that every  $G_i$  is free and

$$(G_i, S_i) \xrightarrow{i \rightarrow \infty} (G, S).$$

Our strategy will be to show that for large enough  $i$ , the map  $S \rightarrow S_i$  extends to a homomorphism  $f_i : L \rightarrow G_i$ . This is enough in order to show that  $L$  is fully residually free: let  $X$  be a finite subset of  $L$ , then  $X$  is contained in some  $B_N(X(L, S))$ , and for sufficiently large  $i$  the homomorphism  $f_i$  will be injective on  $B_N(X(L, S))$  and therefore on  $X$ .

Let  $f : F_n \twoheadrightarrow L$  be a surjection and let  $\Sigma = \ker f$ . It is enough to show that for  $i$  large enough,  $\sigma(S_i) =_{G_i} 1$  for every  $\sigma \in \Sigma$ . Recall that every  $G_i$  is a subgroup of  $F_n$ ; in addition, since  $F_n$  is equationally Noetherian, there is a finite  $\Sigma_0 \subset \Sigma$  admitting the same set of solutions as  $\Sigma$ . It follows that the sets of solutions to  $\Sigma_0$  and  $\Sigma$  coincide in every  $G_i$ .

Given  $\sigma \in \Sigma_0$ , let  $N_\sigma$  be such that  $\sigma$  lies in the  $N_\sigma$  ball in the Cayley graph of  $F_n$ . Note that  $\sigma(S) =_L 1$ , and this can be seen in  $B_{N_\sigma}(X(L, S))$ . Therefore, there exists  $i_\sigma$  such that for every  $i > i_\sigma$ ,  $\sigma(S_i) =_{G_i} 1$ . Now for  $i > \max\{i_\sigma : \sigma \in \Sigma_0\}$  we have that  $\sigma(S_i) =_{G_i} 1$ , so  $S_i$  is a solution to  $\Sigma_0$  in  $G_i$ . Therefore  $S_i$  is a solution to  $\Sigma$  as required.  $\square$

The proof above, also implies the following statement; we leave it as an exercise to convince oneself that it is indeed true.

**Exercise IX.** Let  $L$  be a limit group, let  $(\varphi_n : G \rightarrow F)_{n \in \mathbb{N}}$  be the corresponding stable sequence of homomorphisms and write  $L = G / \varprojlim \ker(\varphi_n)$ . Denote the limit map by  $\varphi_\infty : G \twoheadrightarrow L$ . Then for  $n$  large enough, the homomorphism  $\varphi_n$  factors via  $L$ , that is there exists  $\phi_n : L \rightarrow F$  such that  $\varphi_n = \phi_n \circ \varphi_\infty$ . In particular, one obtains a stable sequence of homomorphisms  $(\phi_n : L \rightarrow F)$  with a trivial stable kernel (compare this to a stable sequence of homomorphisms obtained from being fully residually free).

Naively, the discussion above seems to imply that limit groups are finitely presented. This is indeed the case, but the proof of that fact is a lot more complicated and delicate. We invite the reader to think why the proof above does *not* imply that limit groups are finitely presented. To seal the discussion, we give another equivalent characterization of equational Noetherianity in the following guided exercise.

**Exercise X.** Let  $G$  be a countable group. In this exercise we will prove that  $G$  is equationally Noetherian if and only if the following holds: for every finitely generated group  $H$ , and every stable sequence of homomorphisms  $(\varphi_n : H \rightarrow G)_{n \in \mathbb{N}}$ ,  $\varphi_i$  factors through  $\varphi_\infty : H \rightarrow H / \varprojlim \ker(\varphi_i)$  for *some*  $i$  (equivalently,  $i$  large enough). We remark that a group of the form  $\varphi_\infty(H)$  is called a *limit group over*  $G$ .

1. Prove the direction  $\implies$  by modifying the proof of Corollary [II.2.6](#) and Exercise [IX](#). In this case, the  $G_i$  in Corollary [II.2.6](#) are not free groups, but subgroups of  $G$ .

2. For the other direction, let  $\Sigma \subset G * F_n$  be a system of equations over  $G$ . Explain why  $\Sigma$  must be countable, and consider an exhaustion of  $\Sigma$  by nested finite subsets  $\Sigma_1 \subset \Sigma_2 \subset \dots$ . Use each  $\Sigma_i$  to construct  $\varphi_i : G * F_n \rightarrow G$  such that  $\varphi_i|_G = \text{Id}_G$  and  $\varphi_i(\sigma) = 1$  for every  $\sigma \in \Sigma_i$ .
3. Prove that  $\Sigma \subset \ker(\varphi_\infty)$ .
4. Note that  $G$  is not necessarily finitely generated. Consider the sequence  $(\varphi_i|_{F_n})$  and note that some element in this sequence factors via  $\varphi_\infty|_{F_n}$ . Prove that  $\varphi_i$  must factor via  $\varphi_\infty$  and derive a contradiction, showing that  $G$  is equationally Noetherian.

Using this new characterization of limit groups, we deduce:

**Lemma II.2.7.** *Let  $L$  be a limit group. Then*

1.  $L$  is torsion-free,
2. 2-generated subgroups of  $L$  are either free or free abelian,
3.  $L$  is commutative transitive, meaning that for  $g, h, k \in L$ , if  $[g, h] = [h, k] = 1$  then  $[g, k] = 1$ .

*Proof.* 1. Every  $1 \neq g \in L$  survives in a free quotient, and is therefore not a torsion element.

2. Let  $g, h \in L$ . If  $\langle g, h \rangle$  is abelian, then since  $L$  is torsion-free we have that  $\langle g, h \rangle$  is one of  $\{1\}, \mathbb{Z}$  or  $\mathbb{Z}^2$ . If  $\langle g, h \rangle$  is non-abelian, then there is a free quotient  $q : L \twoheadrightarrow F$  which is injective on  $\{g, h, [g, h]\}$ . It follows that  $q(g)$  and  $q(h)$  generate a non-abelian subgroup of  $F$ , so  $\langle q(g), q(h) \rangle \cong F_2$ . Since  $F_2$  is not a quotient of any 2-generated group other than  $F_2$ , we obtain that  $\langle g, h \rangle \cong F_2$ .
3. Suppose for a contradiction that  $[g, k] \neq 1$  and let  $q : L \twoheadrightarrow F$  be a free quotient of  $L$  which is injective on  $\{g, h, k, [g, k]\}$ . We have that  $[q(g), q(h)] = [(q(h), q(k))] = 1$  so  $q(g), q(h)$  and  $q(k)$  are all powers of the same element  $x \in F$ . It follows that  $[q(g), q(k)] = 1$ , a contradiction.

□

**Exercise XI.** Prove a stronger version of 3. in Lemma II.2.7 above: limit groups are CSA (Conjugacy Separated Abelian), meaning that every maximal abelian subgroup  $M$  of a limit group  $L$  is malnormal: for every  $g \in L$ , if  $gMg^{-1} \cap M \neq \{1\}$  then  $g \in M$ .

One can also use these results to give a first-order characterization of limit groups. We remind the reader that the *universal theory* of a group  $G$  is the set  $\text{Th}_\forall(G)$  of all sentences involving only universal quantifiers (after being put in disjunctive normal form), that is the set of all sentences of the form

$$\forall \bar{x} \bigvee_{i=1}^k \Sigma_i(\bar{x}) = 1 \wedge \Psi_i(\bar{x}) \neq 1,$$

where  $\Sigma(\bar{x})$  is a system of equations and  $\Psi(\bar{x})$  is a system of inequalities.

**Theorem II.2.8.** *A finitely generated group  $G$  is a non-abelian limit group if and only if  $\text{Th}_\forall(G) = \text{Th}_\forall(F)$  (where  $F$  is a non-abelian free group).*

*Remark II.2.9.* A priori, it is not clear that the universal theories of all non-abelian free groups coincide. However, it easily follows from the following fact: if  $H \leq G$  then  $\text{Th}_\forall(G) \subset \text{Th}_\forall(H)$ . Last, note that for every  $n \geq 2$  we have that  $F_2 \leq F_n \leq F_n$ .

*Proof of Theorem II.2.8.* Suppose first that  $G$  is a non-abelian limit group. By Lemma Lemma II.2.7,  $F_2 \leq G$  so  $\text{Th}_\forall(G) \leq \text{Th}_\forall(F_2)$ . To show that there is also inclusion in the other direction, let  $\varphi \in \text{Th}_\forall(F_2)$  and write

$$\varphi = \forall \bar{x} \chi(\bar{x}) = \forall \bar{x} \bigvee_{i=1}^k \Sigma_i(\bar{x}) = 1 \wedge \Psi_i(\bar{x}) \neq 1.$$

We will show that  $G \models \varphi$ , or in other words for every tuple  $\bar{g}$  of elements from  $G$ ,

$$G \models \chi(\bar{g}).$$

Let  $E$  be the set

$$E = \{1\} \cup \{\bar{g}\} \cup \{\sigma(\bar{g}) \mid \sigma \in \Sigma_i\} \cup \{\psi(g) \mid \psi \in \Psi_i\},$$

that is  $E$  is the set of all words participating in the sentence  $\varphi$  evaluated at  $\bar{g}$ . The set  $E$  is finite, so there is a free quotient  $q_E : G \twoheadrightarrow F \leq F_2$  which is injective on  $q_E$ . Therefore, for every word  $\sigma$  participating in  $\varphi$  we have that

$$\sigma(\bar{g}) =_G 1 \iff \sigma(q_E(\bar{g})) =_F 1.$$

Indeed, if  $\sigma(q_E(\bar{g})) =_F 1$  then the injectivity of  $q_E|_E$  implies that  $\sigma(\bar{g}) =_G 1$ , and if  $\sigma(q_E(\bar{g})) \neq_F 1$  then necessarily  $\sigma(\bar{g}) \neq_G 1$  since  $q_E(\sigma(\bar{g})) = \sigma(q_E(\bar{g}))$ . It follows that  $G \models \chi(\bar{g}) \iff F \models \chi(q_E(\bar{g}))$ , and since  $F \models \varphi$  it must be that  $G \models \chi(\bar{g})$ . Repeating this argument for every tuple  $\bar{g}$  from  $G$  we obtain that  $G \models \varphi$ .

For the other direction, suppose that  $\text{Th}_\forall(G) = \text{Th}_\forall(F_2)$ . Since every universal sentence is the negation of an existential sentence and vice-versa, we have that  $\text{Th}_\exists(G) = \text{Th}_\exists(F_2)$ . We will use this to show that  $G$  is the limit of free groups in the space of marked groups.

Let  $S$  be a generating tuple of  $S$  of size  $n$ . It is enough to find, for every  $N \in \mathbb{N}$ , a free group  $G_N$  and a generating tuple  $S_N$  such that  $B_N(X(G, S))$  and  $B_N(X(G_N, S_N))$  are isomorphic. To do so, one only needs to note (see Exercise XII) that there is a sentence of the form

$$\varphi_N = \exists x_1 \cdots \exists x_n \Sigma(\bar{x}) = 1 \wedge \Psi(\bar{x}) \neq 1.$$

such that for any group  $H$  and any tuple  $\bar{h}$  in  $H$ ,  $H \models \Sigma(\bar{h}) = 1 \wedge \Psi(\bar{h}) \neq 1$  if and only if

$$B_N(\langle \bar{h} \rangle, (\bar{h})) \cong B_N(G, S).$$

Now the tuple  $S$  asserts that  $G \models \varphi_N$ , so  $F_2 \models \varphi_N$ . This gives rise to a tuple  $S_N$  in  $F_2$  and a free marked group  $(G_N = \langle S_N \rangle, S_N)$  as desired.  $\square$

**Exercise XII.** Construct the sentence  $\varphi_N$  mentioned in the proof of Theorem II.2.8 above.

We seal this section by giving a few examples of limit groups, other than free and free abelian groups which were already discussed. The first example that we give is due to Gilbert Baumslag Baumslag.

**Theorem II.2.10.** *Let  $\Sigma$  be a closed, orientable surface of even genus  $2n$ . Then  $\pi_1 \Sigma$  is a limit group.*

The proof relies on the following lemma, which is an easy consequence of the Ping Pong lemma.

**Lemma II.2.11** (cf. [1, Proposition 1]). *Let  $F$  be a free group and let  $g_1, \dots, g_n, u \in F$ . If  $[u, g_i] \neq 1$  for every  $i$ , then there exists  $N \in \mathbb{N}$  such that for every  $|k_1|, \dots, |k_n| \geq N$ ,*

$$g_1 \cdot u^{k_1} \cdots g_n \cdot u^{k_n} \neq_F 1.$$

*Proof of Theorem II.2.10.* Write

$$\pi_1 \Sigma = \langle x_1, y_1, \dots, x_{2n}, y_{2n} \mid [x_1, y_1] \cdots [x_{2n}, y_{2n}] = 1 \rangle$$

and let  $f : \pi_1 \Sigma \rightarrow F_{2n} = \langle s_1, \dots, s_{2n} \rangle$  by mapping  $x_1, y_1, \dots, x_n, y_n$  to  $s_1, \dots, s_{2n}$ , and  $x_{n+1}, y_{n+1}, \dots, x_{2n}, y_{2n}$  to  $s_1, \dots, s_{2n}$ . Topologically,  $f$  admits the following description:

let  $\gamma$  be the loop on  $\Sigma$  which separates  $\Sigma$  into two identical parts (note that in the level of fundamental groups,  $[\gamma] = [x_1, y_1] \cdots [x_n, y_n]$ ). The map  $f$  is the map induced by the retraction of  $\Sigma$  onto one half-surface. Let  $\tau$  be the automorphism of  $\pi_1 \Sigma$  induced by a Dehn twist along  $\gamma$  (a nice visualization of  $\tau$  appears in the following [Wikipedia article](#)). On the level of fundamental groups,  $\tau$  restricts to the identity on one half surface, and to conjugation by  $[\gamma]$  on the other one. We will use  $f$  and  $\tau$  to construct a sequence of homomorphisms  $\varphi_n : \pi_1 \Sigma \rightarrow F_{2n}$  such that given  $g \in \pi_1 \Sigma$ ,  $\varphi_n(g) \neq 1$  for  $n$  large enough.

Define  $\varphi_n : f \circ \tau^n$  and let  $g \in \pi_1 \Sigma$ .  $g$  can be written as an alternating product  $g_1 h_1 \cdots g_n h_n$ , such that  $g_i, h_i \notin \langle [\gamma] \rangle$  (and they are non-trivial, except for, perhaps,  $g_1$  or  $h_n$ ). In particular,  $g_i$  and  $h_i$  do not commute with  $[\gamma]$ , as the only elements commuting with  $[\gamma]$  are its powers. One should also note that  $f(h_i)$  and  $f(g_i)$  do not commute with  $f([\gamma])$ . Applying  $\varphi_k$  to  $g$  we obtain

$$\varphi_k(g) = f(g_1) \cdot f([\gamma])^k \cdot f(h_1) \cdot f([\gamma])^{-k} \cdots f(g_n) \cdot f([\gamma])^k \cdot f(h_n) \cdot f([\gamma])^{-k}.$$

By Lemma [II.2.11](#),  $\varphi_k(g) \neq 1$  for  $k$  large enough. It follows that  $\pi_1(\Sigma)$  is fully residually free, and therefore a limit group.  $\square$

**Exercise XIII.** A *double* of a group  $G$  along a subgroup  $H$  is the amalgam  $G *_H G$  obtained by identifying the two copies of  $H$  inside the two copies of  $G$ . Let  $L$  be a limit group, and let  $C$  be a cyclic subgroup of  $L$ , which is maximal abelian in  $L$ . Prove that the double  $L *_C L$  is a limit group.

The doubling construction gives us a plethora of examples of limit groups. It turns out that every limit group can be obtained in such a manner:

**Definition II.2.12.** A *generalized double* of a group  $G$  is a group  $H$  admitting a splitting of the form  $A *_C B$  or  $A *_C$  satisfying:

1.  $A$  and  $B$  are finitely generated,
2.  $C$  is a non-trivial abelian group, which is maximal abelian in  $A$  (and  $B$ ),
3. there is a surjective homomorphism  $H \rightarrow G$  whose restriction to  $A$  (and  $B$ ) is injective.

*Remark II.2.13.* Similar to [Exercise XIII](#) above, every generalized double of a limit group is itself a limit group.



**Theorem II.2.14** ([4, Theorem 4.6]). *A group  $L$  is a limit group if and only if it can be obtained as an iterated generalized double over free groups (that is, starting with free groups and repeatedly taking generalized doubles and free products).*

Another family of examples of limit groups comes from a similar construction:

**Definition II.2.15.** Let  $G$  be a group, let  $g \in G$  and let  $C$  be the centraliser of  $g$ . The *free extension of the centraliser  $C$  of  $g$*  is the group obtained as follows:

Let  $C'$  be another copy of  $C$ , and let  $H = C' \times \mathbb{Z}$ . Now identify  $C$  and  $C'$  to obtain a new group  $G(g)$ . In other words,

$$G(g) = G *_C (C \times \mathbb{Z}).$$

**Lemma II.2.16.** *Let  $F$  be a free group, let  $g \in L$  and let  $C$  be the centraliser of  $g$ . The free extension of the centraliser  $C$ ,  $F(g)$ , is a limit group.*

*Sketch of proof.* Let  $g'$  be a generator of  $C_F(g) \cong \mathbb{Z}$  and write  $F(g) = F(g') = \langle F, t \mid [g', t] \rangle$ . Define  $\varphi_n : F(g) \rightarrow F$  by  $\varphi_n|_F = \text{Id}$  and  $\varphi_n(t) = g^n$ . The same argument used in Theorem II.2.10 shows that  $F(g)$  is a limit group.  $\square$

**Exercise XIV.** Show that every free extension of a centraliser of a limit group is again a limit group.

Note that subgroups of limit groups are limit groups themselves; this gives us another way of seeing that fundamental groups of closed, orientable surfaces of even genus are limit groups:

**Example II.2.17.** Let  $\Sigma$  be a closed, orientable surface of genus  $2n$  and let  $F_{2n}$  be a free group with  $2n$  generators, which we denote by  $x_1, y_1, \dots, x_n, y_n$ . Write  $g = [x_1, y_1] \cdots [x_n, y_n]$ . Note that  $F_{2n}$  is the fundamental group of an orientable surface  $\Sigma'$  of genus  $n$ , with a single boundary component  $g$ . Consider the group  $F_{2n}(g)$ ; it is the fundamental group of the space  $X$  obtained by taking  $\Sigma'$  and a 2-torus  $T$ , and identifying  $g$  with a coordinate circle of  $T$ . Write  $F_{2n}(g) = \langle F_{2n}, t \mid [t, g] = 1 \rangle$  and define  $f : F_{2n}(g) \rightarrow \mathbb{Z}/2$  by mapping  $F_{2n}$  to 0 and  $t$  to 1.  $\ker f$  is an index-2 subgroup of  $F_{2n}(g)$ . Topologically, it is the fundamental group of a double cover  $X'$  of  $X$  which can be thought of as taking two copies of  $\Sigma'$ , and gluing their boundaries by two annuli. Van-Kampen's theorem tells us that  $\pi_1 X' = \ker f = \pi_1(\Sigma) *_{\mathbb{Z}}$ , and in particular  $F_{2n}$  has  $\pi_1 \Sigma$  as a subgroup. This shows that  $\pi_1 \Sigma$  is a limit group. **A figure will be added later**

Again, a more general phenomenon holds in this case as well:

**Theorem II.2.18** ([7, Theorem 4]). *A group  $L$  is a limit group if and only if it is a finitely generated subgroup of an iterated centraliser extension of a free group.*

## II.3 Makanin-Razborov Diagrams, Factor Sets and Shortening Quotients

In the last section of this chapter we will construct the *Makanin-Razborov* diagram of a finitely generated group. This diagram, which takes the shape of a finite rooted tree, describes all homomorphisms from a finitely generated group  $G$  to a free group. The root vertex of the tree is labelled by  $G$ , and its other vertices are labelled by limit groups which are quotients of  $G$ ; the leaves are labelled by free groups and each edge comes equipped with a quotient map between its adjacent vertices. Each *branch* of this diagram, namely a path between the root vertex  $G$  and a leaf  $F$ , describes a collection of homomorphisms from  $G$  to  $F$ , which differ from each other by *twisting* by an automorphism at the vertices along the path. Each  $f : G \rightarrow F$  corresponds to a branch in the Makanin-Razborov Diagram. We remark that the diagram is *not* canonical, and one could construct different Makanin-Razborov diagrams with  $G$  as their root vertex. **A drawing will be added later**

We begin by describing the *first level* of a Makanin-Razborov diagram of a finitely generated group  $G$ , namely the collection of neighbors of the root vertex. We will first deal with the case where  $G$  is *not* a limit group. This is one of the rare occasions where it is easier to prove a theorem for a group that is not a limit group than it is for a limit group.

**Definition II.3.1.** Let  $G$  be a group. A *factor set* of  $G$  is a collection of quotients of  $G$   $\{q_i : G \twoheadrightarrow Q_i \mid i \in I\}$  such that every homomorphism from  $G$  to a free group  $F$  must factor via some  $q_i$ .

One readily sees that every finitely generated group which is not a limit group admits a finite factor set:

**Lemma II.3.2.** *Let  $G$  be a finitely generated group. If  $G$  is not a limit group, then it has a finite factor set.*

*Proof.* Since  $G$  is not a limit group, there is a finite subset  $X \subset G$  such that every homomorphism  $G \rightarrow F$  is not injective on  $X$ . Up to enlarging  $X$ , we can assume that every homomorphism from  $G$  to  $F$  kills an element of  $X$ . It follows that the collection of quotients  $\{q_x : G \twoheadrightarrow G/\langle\langle x \rangle\rangle \mid x \in X\}$  is a finite factor set.  $\square$

As mentioned earlier, the vertices of Makanin-Razborov diagrams (other than the root vertex) are always labelled by limit groups. We therefore need to strengthen

Lemma II.3.2 above, and show that one can always find a finite factor set of  $G$  which consists only of limit groups.

**Theorem II.3.3.** *Let  $G$  be a finitely generated group which is not a limit group. Then  $G$  admits a finite factor set consisting only of limit groups.*

*Proof.* The proof relies on Zorn's lemma. Construct a poset  $Q_G$  of quotients of  $G$  as follows:

- Every element in the poset is an *equivalence class* of limit quotients of  $G$ . We say that two limit quotients  $q_1 : G \twoheadrightarrow L_1$  and  $q_2 : G \twoheadrightarrow L_2$  of  $G$  are equivalent if there is an isomorphism  $f : L_1 \rightarrow L_2$  such that  $f \circ q_1 = q_2$ .
- We say that  $[q_1 : G \twoheadrightarrow L_1] \leq [q_2 : G \twoheadrightarrow L_2]$  if and only if there is a representative  $q'_1 \in [q_1]$  which factors via  $q_2$  (and in particular  $L_1$  is a quotient of  $L_2$ ).

Our goal is to show that the poset  $Q_G$  has finitely many maximal elements; these elements will give us the desired factor set (and in fact, every homomorphism from  $G$  to a limit group will have to factor through one of them).

Consider a chain  $q_1 < q_2 < \dots$  in  $Q_G$ . By Zorn's lemma, it suffices to show that the chain admits an upper bound  $[q] \in Q_G$ . We construct  $q$  using a diagonalization argument. Write  $q_i : G \twoheadrightarrow L_i$ , and let  $(\varphi_n^i : G \rightarrow F)_{n \in \mathbb{N}}$  be a stable sequence of homomorphisms which corresponds to  $L_i$ . Up to replacing each  $(\varphi_n^i)$  with a subsequence, we may assume that for every  $i$  and every  $n$ ,  $\varphi_n^i$  is injective on the set

$$X_{i,n} = \{g \in G \mid g \notin \ker q_i \text{ and } g \in B_n(G)\}$$

The diagonal sequence  $(\varphi_n^n)_{n \in \mathbb{N}}$  gives rise to a limit quotient  $q : G \twoheadrightarrow G / \varprojlim \ker \varphi_n^n = L$ . Recall that  $L$  is finitely presented, which implies that all of the relations of  $L$  lie in some  $B_N(G)$ . It follows that for every  $i$  and  $n$  large enough, every  $\varphi_n^i$  factors via  $q$  and therefore all but finitely many of the  $q_i$  factor via  $q$ . Since the  $q_i$  form a chain, we have that every  $q_i$  must factor through  $q$ , and hence  $q$  is an upper bound for the chain.

We have shown therefore that every limit quotient of  $G$  factors through a maximal element of  $Q_G$ , and it is left to show that there are only finitely many maximal elements in  $Q_G$ . Let  $(q_n)_{n \in \mathbb{N}}$  be a sequence of maximal elements in  $Q_G$ . Repeating the same diagonalization argument as above, show that all but finitely many of the  $q_i$  must factor via some  $q$ ; but since the  $q_i$  are maximal, we obtain that all but finitely many  $q_i$  lie in  $[q]$ , which completes the proof.  $\square$

**Exercise XV.** The proof of Theorem II.3.3 used the fact that limit groups are finitely presented. Prove Theorem II.3.3 without using this fact. *Hint:* Use the fact that free groups are equationally Noetherian.

**Corollary II.3.4.** *A finitely generated group is residually free if and only if it embeds as a subgroup of a direct product of finitely many limit groups.*

*Proof.* The fact that every subgroup of a direct product of limit groups is residually free is easy to prove: every non-trivial element in such a group projects non-trivially to some coordinate. Every coordinate is a limit group, and hence residually free.

For the other direction, let  $G$  be a finitely generated residually free group and let  $\{q_i : G \twoheadrightarrow L_i\}_{1 \leq i \leq n}$  be a finite factor set of  $G$  such that every  $L_i$  is a limit group. Define  $f = q_1 \times \dots \times q_n : G \rightarrow L_1 \times \dots \times L_n$  and note that  $\ker f = \bigcap_{i=1}^n \ker q_i$ . It is enough therefore to show that  $\bigcap_{i=1}^n \ker q_i \neq \{1\}$ . Indeed, if  $g \in G$  is non-trivial, the fact that  $G$  is residually free implies that there is a free quotient  $q : G \twoheadrightarrow F$  such that  $q(g) \neq 1$ . Since the  $q_i$  form a factor set,  $q$  must factor via some  $q_i$ , so  $q_i(g) \neq 1$  and  $g \notin \ker q_i \supset \bigcap_{i=1}^n \ker q_i$ .  $\square$

### II.3.1 Limiting actions on $\mathbb{R}$ -trees

As we have already seen, one often has to pass to subsequences when studying sequences of homomorphisms. To avoid passing to subsequences multiple times (and using nested indices), we introduce the language of *ultrafilters*. Loosely speaking, ultrafilters simply form “strainers” or “filters”, in the sense that they give us a precise manner of saying when a subset of a set  $X$  is either “small” or “large”.

**Definition II.3.5.** An *ultrafilter* (on  $\mathbb{N}$ ) is a finitely additive probability measure  $\omega : 2^{\mathbb{N}} \rightarrow \{0, 1\}$ . Alternatively, we can think of  $\omega$  as a collection of subsets of  $2^{\mathbb{N}}$  which is closed under finite intersections, is closed under taking supersets and is maximal in the sense that it is not a proper subset of any subset of  $2^{\mathbb{N}}$  that satisfies these properties.

We say that an ultrafilter  $\omega$  is *non-principal* if it satisfies  $\omega(F) = 0$  for every finite  $F \subset \mathbb{N}$ . We also define *limits* with respect to ultrafilters: the  $\omega$ -*limit* of a sequence  $(x_n)_{n \in \mathbb{N}}$  in  $\mathbb{R}$  is  $x \in \mathbb{R}$  if for every  $\varepsilon > 0$ ,

$$\omega(\{n \in \mathbb{N} \mid |x - x_n| < \varepsilon\}) = 1.$$

In this case we denote  $\lim_{\omega}(x_n) = x$ . We say that  $\lim_{\omega}(x_n) = \infty$  if  $\omega(\{n \in \mathbb{N} \mid x_n > N\}) = 1$  holds for every  $N \in \mathbb{N}$ .

*Remark II.3.6.* Every sequence of real numbers has a unique  $\omega$ -limit in  $\mathbb{R} \cup \{\pm\infty\}$  (and has a subsequence that converges to this limit). Note that if a sequence is bounded then its  $\omega$ -limit is always a real number, but the  $\omega$ -limit of an unbounded sequence can be in  $\mathbb{R}$ .

**Convention II.3.7.** Let  $P$  be a statement that applies to the elements  $(X_n)_{n \in \mathbb{N}}$  (note that the  $X_n$  are not necessarily numbers; they can be, for example, topological spaces). We say that  $P$  holds  $\omega$ -almost-surely (for the sequence  $(X_n)_{n \in \mathbb{N}}$ ) if

$$\omega(\{n \in \mathbb{N} \mid P \text{ holds for } n\}) = 1.$$

To practice the use of this convention, we rephrase the (algebraic) definition of limit groups using ultrafilters. Suppose if so that  $\omega$  is a non-principal ultrafilter on  $\mathbb{N}$ , and that  $(\varphi_n)_{n \in \mathbb{N}}$  is a sequence in  $\text{Hom}(G, F)$ , where  $G$  is finitely generated. The *stable kernel* of the sequence (with respect to  $\omega$ ), is

$$\underline{\ker}_\omega(\varphi_n) = \{g \in G \mid \varphi_n(g) = 1 \text{ } \omega\text{-almost-surely}\},$$

and a group  $L$  is a limit group if and only if it is obtained as  $G/\underline{\ker}_\omega(\varphi_n)$ .

Our next goal is to show that every limit group comes equipped with a *limiting action* on a topological space called an  $\mathbb{R}$ -tree; we remind the reader that a *tree* is a graph that contains no cycles. Equivalently, it is a graph in which every *triangle* (namely, a collection of three geodesics between three points  $x$ ,  $y$  and  $z$ ) is in fact a *tripod*: there exists a point  $c$  which lies at the intersection of the three geodesics  $[x, y] \cap [x, z] \cap [y, z]$ . Since a graph is a simplicial complex, such trees are often referred to as “simplicial trees”. We will focus on a family of spaces that generalizes trees:

**Definition II.3.8.** An  $\mathbb{R}$ -tree (or a *real tree*) is a geodesic metric space (that is, there is a geodesic, which is a segment of length  $d(x, y)$ , between every two points  $x, y$  in the space) in which every triangle is a tripod.

We next give a metric condition for when a space is an  $\mathbb{R}$ -tree.

**Definition II.3.9.** Let  $T$  be an  $\mathbb{R}$ -tree and let  $x, y, z \in T$ . Let  $c$  be the central point of the corresponding tripod. We denote by  $(x, y)_z$  the distance  $d(z, c)$ . Note that

$$(x, y)_z = \frac{1}{2} \cdot (d(x, z) + d(y, z) - d(x, y)).$$

**A drawing will be added later**

More generally, if  $X$  is a metric space and  $x, y$  and  $z$  are points in  $X$ ,  $(x, y)_z$  is defined as the magnitude appearing above, and is called the *Gromov product* of  $x$  and  $y$  at  $z$ .

In the early 20th century, discrete mathematicians were interested in the following question: let  $X$  be a finite collection of points, with assigned distances between each pair of points in  $X$ . Can one realize  $X$  as the leaf set of a finite tree? It turns out that it is enough to verify that every four points in  $X$  satisfy a condition. This result is known as Zaretskii's lemma; it was proven for integral distances by Zaretskii in 1965 [19], and generalized to real distances by Pereira in 1969 [18].

**Lemma II.3.10** (Zaretskii's Lemma). *A finite set  $X$  accompanied with distances as above can be realized as the leaf set of a tree if and only if for every  $x, y, z, t \in X$  the following inequality, known as the four-point condition, holds:*

$$(x, y)_t \geq \min((x, z)_t, (y, z)_t).$$

Note that a geodesic metric space is an  $\mathbb{R}$ -tree if and only if every finite subset of it spans a finite tree. Therefore,

**Corollary II.3.11.** *A geodesic metric space is an  $\mathbb{R}$ -tree if and only if every four points in the space satisfy the four-point condition.*

**Exercise XVI.** Prove Zaretskii's Lemma when the distances between points in  $X$  are integral. *Hint:* First, rearrange the four-point condition above and show that it is equivalent to

$$d(x, y) + d(z, t) \leq \max((d(x, z) + d(y, t)), (d(x, t) + d(y, z)))$$

Zaretskii's original paper [19] is available [online](#), and it is less than 3 pages long. It is in russian, but it includes figures and mathematical text.

*Remark II.3.12.* Some readers may be familiar with Ptholemy's theorem, which characterizes when four points in the plane are cocyclic: four points  $x, y, z, t$  lie on a circle if and only if

$$d(x, y) \cdot d(z, t) = d(x, z) \cdot d(y, t) + d(x, t) \cdot d(y, z).$$

**A drawing will be added**

As a matter of fact, Ptholemy proved a stronger [result](#): every four points  $x, y, z, t$  in the plane satisfy the following inequality:

$$d(x, y) \cdot d(z, t) \leq d(x, z) \cdot d(y, t) + d(x, t) \cdot d(y, z).$$

We would next like to highlight an unexpected relation between  $\mathbb{R}$ -trees and *tropical geometry*: the study of polynomials and their geometric properties when addition is

replaced with maximization and multiplication is replaced with ordinary addition. A “tropicalization” of Ptholemy’s inequality above yields the four-point condition as in Exercise XVI.

We are finally ready to construct an action of a limit group on an  $\mathbb{R}$ -tree. In what follows, we assume that all metric spaces are geodesic. A *pointed metric space* is a triplet  $(X, d, o)$  where  $(X, d)$  is a metric space and  $o \in X$ .

**Definition II.3.13.** Let  $(X_n, d_n, o_n)_{n \in \mathbb{N}}$  be a sequence of pointed metric spaces. The *ultralimit* of  $(X_n, d_n, o_n)_{n \in \mathbb{N}}$  with respect to an ultrafilter  $\omega$  is a triplet  $(X_\omega, d_\omega, o_\omega)$  where

$$X_\omega = \left( \prod_{n \in \mathbb{N}} X_n \right) / \omega = \frac{\{(x_n)_{n \in \mathbb{N}} \mid \lim_\omega d_n(x_n, o_n) < \infty\}}{(x_n)_{n \in \mathbb{N}} \sim (y_n)_{n \in \mathbb{N}} \iff \lim_\omega d_n(x_n, y_n) = 0},$$

$d_\omega : X_\omega \times X_\omega \rightarrow \mathbb{R}_{\geq 0}$  is given by

$$d_\omega([(x_n)_{n \in \mathbb{N}}], [(y_n)_{n \in \mathbb{N}}]) = \lim_\omega d_n(x_n, y_n)$$

and  $o_\omega$  is the equivalence class of the sequence  $(o_n)_{n \in \mathbb{N}}$ .

*Remark II.3.14.* We will often abuse notation and refer to the equivalence class of a sequence  $(x_n)_{n \in \mathbb{N}}$  in  $X_\omega$  as  $(x_n)_{n \in \mathbb{N}}$  instead of  $[(x_n)_{n \in \mathbb{N}}]$ . If a sequence  $(x_n)_{n \in \mathbb{N}}$  lies in  $X_\omega$  we call it a *visible sequence*.

It is straightforward (and recommended) to verify that  $(X_\omega, d_\omega, o_\omega)$  is a pointed metric space (that is,  $d_\omega$  is well-defined and satisfies the required conditions). We continue by showcasing a simple instance in which  $(X_\omega, d_\omega, o_\omega)$  inherits some properties from the spaces in the sequence  $(X_n, d_n, o_n)_{n \in \mathbb{N}}$ ; this will prove to be of great importance in Chapter III.0.3 **Reference will be added later**.

**Lemma II.3.15.** *Let  $(X_n, d_n, o_n)_{n \in \mathbb{N}}$  be a sequence of pointed metric spaces such that each  $(X_n, d_n)$  is a tree (or, more generally, an  $\mathbb{R}$ -tree). Then  $(X_\omega, d_\omega)$  is an  $\mathbb{R}$ -tree.*

*Proof.* It suffices to verify that  $X_\omega$  is a geodesic space that satisfies the four-point condition, that is for every four points  $(x_n), (y_n), (z_n), (t_n)$  in  $X_\omega$ ,

$$((x_n), (y_n))_{(z_n)} \geq \min\{((x_n), (z_n))_{(t_n)}, ((y_n), (z_n))_{(t_n)}\}.$$

It is easy to see that  $(X_\omega, d_\omega)$  is a geodesic space: given  $(x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}} \in X_\omega$ , let  $t_n : [0, d_n(x_n, y_n)] \rightarrow X_n$  be a geodesic from  $x_n$  to  $y_n$  in  $(X_n, d_n)$ . Define  $t : [0, d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})] \rightarrow X_\omega$  by

$$s \mapsto t_n \left( \frac{d_n(x_n, y_n)}{d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})} \cdot s \right).$$

It is straightforward to verify that  $t$  is the suitable geodesic in  $(X_\omega, d_\omega)$ . First, note that for every  $s \in [0, d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})]$  with  $t(s) = (s_n)_{n \in \mathbb{N}}$  we have that  $s_n$  is on the geodesic between  $x_n$  and  $y_n$  so

$$\lim_\omega d_n(o_n, s_n) \leq \lim_\omega (d_n(o_n, x_n) + d_n(x_n, s_n)) \leq \lim_\omega (d_n(o_n, x_n) + d_n(x_n, y_n)) < \infty$$

and  $t$  is well-defined. Furthermore, given  $s_1 < s_2 \in [0, d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})]$  we have that

$$\begin{aligned} d_\omega(t(s_1), t(s_2)) &= \lim_\omega d_n \left( \left( \frac{d_n(x_n, y_n)}{d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})} \cdot s_1 \right), \left( \frac{d_n(x_n, y_n)}{d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})} \cdot s_2 \right) \right) \\ &= \lim_\omega \left( \frac{d_n(x_n, y_n)}{d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})} \cdot (s_2 - s_1) \right) \\ &= \frac{\lim_\omega (d_n(x_n, y_n))}{d_\omega((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}})} \cdot (s_2 - s_1) = s_2 - s_1 \end{aligned}$$

and  $t$  minimizes distances.

Finally, given  $x_n, y_n, z_n, t_n \in X_n$  for every  $n \in \mathbb{N}$  we have that

$$(x_n, y_n)_{z_n} \geq \{(x_n, z_n)_{t_n}, (y_n, z_n)_{t_n}\}$$

and the inequality is preserved in the limit.  $\square$

*Remark II.3.16.* The proof above also shows that if geodesics in  $(X_\omega, d_\omega)$  are unique (e.g. when  $(X_\omega, d_\omega)$  is an  $\mathbb{R}$ -tree), then every geodesic in  $(X_\omega, d_\omega)$  can be approximated by geodesics in the spaces  $(X_n, d_n)$ .

Suppose now that  $G$  is a finitely generated group, and let  $S = (s_1, \dots, s_k)$  be a finite generating tuple of  $G$ . Let  $(X_n, d_n, o_n)$  be a sequence of pointed metric spaces, and suppose in addition that  $G$  acts on each  $(X_n, d_n, o_n)$ . Under a mild assumption, we get that  $G$  acts on  $X_\omega$ :

**Lemma II.3.17.** *If  $\lim_\omega d_n(o_n, s.o_n) < \infty$  for every  $s \in S$ , then  $G$  acts on  $X_\omega$  by  $g.(x_n)_{n \in \mathbb{N}} = (g.x_n)_{n \in \mathbb{N}}$ .*

*Proof.* We just need to verify that for every  $(x_n)_{n \in \mathbb{N}}$  and  $g \in G$  we have that  $(g.x_n)_{n \in \mathbb{N}} \in X_\omega$ , that is  $\lim_\omega d_n(o_n, g.x_n) < \infty$ . The other properties that define a group action easily follow.

Write  $g = s_1 \cdots s_k$  where  $s_i \in S$  for  $1 \leq i \leq k$  and note that

$$\begin{aligned} d_n(o_n, g.o_n) &= d_n(o_n, (s_1 \cdots s_k).o_n) \\ &\leq d_n(o_n, s_1.o_n) + d_n(s_1.o_n, (s_1 \cdot s_2).o_n) + \cdots + d_n((s_1 \cdots s_{k-1}).o_n, (s_1 \cdots s_k).o_n) \\ &= \sum_{i=1}^k d_n(o_n, s_i.o_n). \end{aligned}$$



and therefore

$$\begin{aligned}
\lim_{\omega} d_n(o_n, g.x_n) &\leq \lim_{\omega} d_n(o_n, g.o_n) + \lim_{\omega} d_n(g.o_n, g.x_n) \\
&= d_n(o_n, g.o_n) + \lim_{\omega} d_n(o_n, x_n) \\
&\leq \lim_{\omega} d_n(o_n, x_n) + \sum_{i=1}^k \lim_{\omega} d_n(o_n, s_i.o_n) < \infty
\end{aligned}$$

as desired.  $\square$

**Corollary II.3.18.** *Let  $H$  be a group acting on a sequence of pointed metric spaces  $(X_n, d_n, o_n)_{n \in \mathbb{N}}$ , let  $G$  be a group generated by a finite tuple  $S$  and let  $(\varphi_n)_{n \in \mathbb{N}}$  be a sequence in  $\text{Hom}(G, H)$ . For each  $n$ , we get an action  $G \curvearrowright X_n$  by setting  $g.x = \varphi_n(g).x$  for  $g \in G$  and  $x \in X_n$ . Therefore, by Lemma II.3.17, if  $\lim_{\omega} d_n(o_n, s.o_n) < \infty$  for every  $s \in S$  then  $G$  acts on  $X_{\omega}$ . Furthermore, if  $H$  is a free group, then it comes equipped with an action on a (simplicial) tree: its natural action on its Cayley graph. Therefore, under this assumption, we get that  $G$  acts on an  $\mathbb{R}$ -tree.*

The remainder of this subsection will focus on how to extract a (non-trivial) action of a limit group on a limiting  $\mathbb{R}$ -tree (that is, an action without a global fixed point). We therefore fix a free group  $F$  admitting a non-trivial action on its Cayley graph  $(X, d)$  which is a simplicial tree, and a limit group  $L = G/\overleftarrow{\ker}_{\omega}((\varphi_n)_{n \in \mathbb{N}})$ . We also assume that  $G$  is generated by a finite tuple  $S$ . The limiting real tree that we obtain will be a limit of a sequence of pointed metric spaces, where each element in the sequence is  $X$  equipped with a rescaling of the metric  $d$ . We therefore define:

**Definition II.3.19.** Let  $o$  be a choice of a basepoint of  $(X, d)$ , and let  $n \in \mathbb{N}$ . The *scaling factor of  $\varphi_n$  at  $o$*  is given by

$$\|\varphi_n\|_o = \max_{s \in S} d(o, \varphi_n(s).o).$$

Combining Lemmas II.3.15 and II.3.17 we obtain:

**Corollary II.3.20.** *Let  $(o_n)_{n \in \mathbb{N}}$  be a sequence of points in  $X$ . Then the sequence  $(X, d/\|\varphi_n\|_{o_n}, o_n)$  converges to a real tree  $(X_{\omega}, d_{\omega}, o_{\omega})$  on which  $G$  acts by  $g.(x_n)_{n \in \mathbb{N}} = (\varphi_n(h).o_n)_{n \in \mathbb{N}}$ . Furthermore,  $H \curvearrowright X_{\omega}$  gives rise to an action  $L \curvearrowright X_{\omega}$ .*

*Proof.* It is enough to show that the boundedness condition of Lemma II.3.17 holds. Indeed, given  $s \in S$  we have that

$$\|\varphi_n\|_{o_n}(o_n, \varphi_n(s).o_n) \leq \frac{\max_{s \in S} d(o, \varphi_n(s).o)}{\|\varphi_n\|_o} = 1$$

as desired. Lastly, since  $\overleftarrow{\ker}_{\omega}((\varphi_n)_{n \in \mathbb{N}})$  acts trivially on  $X_{\omega}$ , the action  $G \curvearrowright X_{\omega}$  induces an action  $L \curvearrowright X_{\omega}$ .  $\square$

Corollary II.3.20 is still not enough: there is nothing preventing the action  $G \curvearrowright X_\omega$  from having a global fixed point. Bestvina introduced a method for overcoming this problem in [3] (where the spaces considered are hyperbolic  $n$ -spaces), which was later generalised by Paulin in [12] (to accommodate any hyperbolic space). This method is often referred to as the “Bestvina-Paulin trick”, and it revolves around carefully choosing the sequence basepoints  $(o_n)_{n \in \mathbb{N}}$ . We amass the relevant definitions for explaining this method, and begin with an absolute version of the scaling factor defined above:

**Definition II.3.21.** Keeping the notation above, the *scaling factor* of a homomorphism  $\varphi_n : G \rightarrow H$  is

$$\|\varphi_n\| = \inf_{x \in X} \max_{s \in S} d(x, \varphi_n(s).x) = \inf_{x \in X} \|\varphi_n\|_x.$$

*Remark II.3.22.* Note that  $\|\varphi_n\|$  does not depend on a choice of a basepoint  $o$  of  $X$ .

The scaling factor of a homomorphism will play a crucial role in the study of *shortening quotients* (see Theorem II.3.25). We conclude with the following Theorem:

**Theorem II.3.23** (Bestvina-Paulin trick). *If  $L$  is a limit group then there exists a choice of basepoints  $(o_n)_{n \in \mathbb{N}}$  in  $X$  such that the sequence  $(X, d/\|\varphi_n\|, o_n)$  converges to a real tree  $(X_\omega, d_\omega, o_\omega)$  on which  $L$  acts non-trivially.*

*Proof.* For every  $n \in \mathbb{N}$ , choose  $o_n \in X$  that satisfies  $d(o_n, \varphi_n(s).o_n) = \|\varphi_n\|$  for some  $s \in S$  (this is possible since  $X$  is a simplicial tree, and so the metric  $d$  is discrete). As in Corollary II.3.20, we obtain an action  $G \curvearrowright X_\omega$  which gives rise to an action  $L \curvearrowright X_\omega$ ; it is enough to show that the action of  $G$  on  $X_\omega$  is non-trivial, that is, no  $(x_n)_{n \in \mathbb{N}} \in X_\omega$  is fixed by all of  $G$ .

Since  $S$  is finite, there exists  $s \in S$  such that  $d(o_n, \varphi_n(s).o_n) = \|\varphi_n\|$  holds  $\omega$ -almost surely. Therefore, for every  $(x_n)_{n \in \mathbb{N}} \in X_\omega$  we have that

$$\frac{d}{\|\varphi_n\|}(x, \varphi_n(s).x) \geq \frac{d(o_n, \varphi_n(s).o_n)}{\|\varphi_n\|} = 1$$

$\omega$ -almost surely, so  $d_\omega((x_n)_{n \in \mathbb{N}}, s.(x_n)_{n \in \mathbb{N}}) \geq 1$  and  $G$  does not fix  $(x_n)_{n \in \mathbb{N}}$ . □

*Remark II.3.24.* Note that  $G$  and  $L$  are both finitely generated, and therefore countable. If  $X_\omega$  is not a line, the valence of every vertex of  $X_\omega$  is uncountable and therefore the action  $G \curvearrowright X_\omega$  is not minimal. In other words,  $G$  has a proper invariant subtree of  $X_\omega$ . If needed, one can always reduce to a subtree on which the action is minimal.

### II.3.2 The Shortening Argument and generalized factor sets

We are finally ready to construct Makanin-Razborov diagrams; we begin with a simpler construction that yields a diagram with the required properties, but is not *canonical*. In simpler words, the construction of the diagram requires choice, and different choices will yield different diagrams (each of which gives a full description of  $\text{Hom}(G, F)$ ). Refining our arguments, we will then construct a canonical Makanin-Razborov diagram for a finitely generated group  $G$ . There is no ambiguity surrounding the diagram obtained with this construction: it is determined (up to equivalence) by a choice of a finite generating set of  $G$ .

At the heart of the construction, lies the following important theorem which will also play a key part in the next chapter: the *Shortening Argument*. This theorem admits many versions, the first one of them is due to Rips and Sela [15].

**Theorem II.3.25.** *Suppose that  $G$  does not split as a free product and let  $(\varphi_n)$  be a sequence in  $\text{Hom}(G, F)$ . If  $\overleftarrow{\ker}_\omega(\varphi_n) = 1$  then  $\varphi_n$  is not short  $\omega$ -almost-surely, meaning that there are homomorphisms  $\phi_n : G \rightarrow F$  such that  $\|\phi_n\| < \|\varphi_n\|$   $\omega$ -almost-surely.*

*Remark II.3.26.* The version of the shortening argument stated above does not reveal its full power: the proof of the shortening argument implies that  $\phi_n$  above can always be chosen to be of a specific form:

$$\phi_n = \text{ad}(g) \circ \varphi_n \circ \alpha,$$

where  $\alpha \in \text{Aut}(G)$  and  $\text{ad}(g)$  is conjugation by  $g \in F$ . Furthermore,  $\alpha$  can be chosen to be an automorphism that lies in the *modular group*  $\text{Mod}(G)$  of  $G$ . We will discuss, and make use, of  $\text{Mod}(G)$  in [the next chapter, a reference will be added later](#).

Recall that in Lemma II.3.2 and Theorem II.3.3 we constructed a factor set for a group  $G$  given that it is *not* a limit group. We couldn't adapt our construction to limit groups because we didn't have the means to construct *maximal* quotients of a limit group  $L$ . The shortening argument allows us to deal with that problem.

**Definition II.3.27.** Let  $G$  be a group. A *generalized factor set* of  $G$  is a collection of quotients of  $G$   $\{q_i : G \twoheadrightarrow Q_i \mid i \in I\}$  such that, up to precomposition by some  $\alpha \in \text{Aut}(G)$ , every homomorphism  $f : G \rightarrow F$  must factor via some  $q_i$  (that is  $f \circ \alpha$  factors via  $q_i$ ).

**Corollary II.3.28.** *Let  $L$  be a limit group which does not admit a free splitting. Then  $L$  admits a finite generalized factor set.*

*Proof.* This proof can be seen as a “limit version” of the proof of Lemma II.3.2. Enumerate the elements of  $L$ , that is write  $L = \{g_1, g_2, \dots\}$ , and let

$$F_n = \{q_i : L \twoheadrightarrow L/\langle\langle g_i \rangle\rangle \mid i \leq n\}.$$

We will show that some  $F_n$  must be a factor set of  $L$  (in fact,  $F_n$  is a factor set of  $L$   $\omega$ -almost-surely).

Suppose not, then for every  $n$  there exists  $\varphi_n : L \rightarrow F$  which is injective on  $\{g_1, \dots, g_n\}$ . Let  $\phi_n$  be the shortest homomorphism of the form  $\text{ad}(g) \circ \varphi_n \circ \alpha$  as in Remark II.3.26. Note that  $\phi_n$  is also injective on  $\{g_1, \dots, g_n\}$ . Hence the sequence  $\phi_n$  has a trivial stable kernel, contradicting Theorem II.3.25. Therefore, we could not choose such  $\varphi_n$   $\omega$ -almost-surely and for some  $n$  (in fact,  $\omega$ -almost-surely), every  $f : G \rightarrow F$  must factor via some  $q_i : G \rightarrow G/\langle\langle g_i \rangle\rangle$  where  $i \leq n$ .  $\square$

Armed with Corollary II.3.28, we can start constructing a Makanin-Razborov diagram for  $G$  by iterating the construction of a factor set. All that’s left for us to prove is that the resulting diagram is finite, that is, that the diagram does not admit infinitely-deep branches. Equivalently:

**Claim II.3.29.** *Every sequence of quotients  $L_1 \twoheadrightarrow L_2 \twoheadrightarrow L_3 \twoheadrightarrow \dots$  where each  $L_i$  is a limit group eventually stabilizes.*

*Proof.* The proof is a simple application of equational Noetherianity. We first note that an epimorphism  $q_i : L_i \twoheadrightarrow L_{i+1}$  induces an embedding

$$p_i : \text{Hom}(L_{i+1}, F) \rightarrow \text{Hom}(L_i, F)$$

by sending  $f : L_{i+1} \rightarrow F$  to  $p_i(f) = f \circ q_i : L_i \rightarrow F$ . Furthermore, if  $q_i$  is a proper quotient map (that is,  $q_i$  is not injective), then  $p_i$  is not surjective: indeed, if  $g \in \ker(q_i)$  then  $f \circ q_i(g) = 1$ , but since  $L_i$  is a limit group there is a homomorphism  $f_g : L_i \rightarrow F$  which does not kill  $g$  so  $f_g \notin \text{Im}(p_i)$ . It is therefore enough to prove that for large enough  $i$ ,  $p_i$  is an isomorphism.

For each  $i$ , fix a presentation  $\langle S \mid R_i \rangle$  where  $R_i \subset R_{i+1}$ . Let  $R = \bigcup_i R_i$  and  $L = \langle S \mid R \rangle$ . Note that  $R$  is a system of equations over a free group, and free groups are equationally Noetherian. Therefore  $R$  is equivalent to a finite subsystem  $R'$ , and  $R' \subset R_i$  for some  $i$ . Recall that the sets of solutions to  $R_i$  in  $F$  correspond to homomorphisms in  $\text{Hom}(L_i, F)$ . It follows that for every  $j \geq i$ ,  $p_j$  is a bijection as required.  $\square$

### II.3.3 Canonization for Makanin-Razborov diagrams

This chapter comes to an end with a detailed description of the *canonical* Makanin-Razborov diagram attached to a finitely generated group  $G$  (accompanied by a finite generating set  $S$ ).

Recall that the construction in Theorem II.3.3 yielded a specific factor set (up to equivalence); this factor set did not depend on anything except for the group  $G$  itself. In the following guided exercise, you will prove an analogous version for limit groups, in which the quotients in the (generalized) factor set are *shortening quotients*. This version however *does* depend on the choice of a generating set.

**Definition II.3.30.** Let  $L$  be a limit group which does not admit a free splitting. A quotient  $q : L \twoheadrightarrow Q$  is a *shortening quotient* if it is obtained from  $L$  by quotienting out the stable kernel of a sequence of homomorphisms  $\varphi_n : L \rightarrow F$ , such that for every  $g \in F$  and every  $\alpha \in \text{Mod}(G)$ ,  $\|\varphi_n\| \leq \|\text{ad}(g) \circ \varphi_n \circ \alpha\|$ .

*Remark II.3.31.* Note that the shortening argument Theorem II.3.25 implies that every shortening quotient of  $L$  is a proper quotient. In addition, the way in which the scaling factor  $\|\varphi_n\|$  was defined, implies that the collection of shortening quotients of  $L$  depends on a choice of a generating set of  $L$ .

**Theorem II.3.32.** Let  $L$  be a freely indecomposable limit group. Then  $L$  admits a generalized factor set consisting of shortening quotients of  $L$ , and which depends only on the generating set of  $L$ .

**Exercise XVII.** Prove Theorem II.3.32. Let  $L$  be a freely indecomposable limit group and let  $S$  be a generating set of  $L$ .

1. Define an equivalence relation on the set  $\mathcal{S}(L, S)$  of shortening quotients of  $L$  (with respect to  $S$ ) as in Theorem II.3.3 (note that here one has to allow twisting by elements of  $\text{Mod}(L)$ ). Define a partial order on the set  $\mathcal{S}(L, S)$  as in Theorem II.3.3.
2. Prove that every increasing chain in  $\mathcal{S}(L, S)$  admits an upper bound in  $\mathcal{S}(L, S)$  (that is, the upper bound is itself a shortening quotient).
3. Prove that there are only finitely many (equivalence classes) of maximal shortening quotients in  $\mathcal{S}(L, S)$ .

After giving informal descriptions of Makanin-Razborov diagrams, we are finally in the position to give a precise description (of the canonical Makanin-Razborov diagram of  $G$  with respect to  $S$ ). We will also make use of the following theorem:

**Theorem II.3.33** (Grushko's theorem). *Let  $G$  be a finitely generated group. Then  $G$  can be decomposed as a (possibly trivial) free product*

$$G = G_1 * \cdots * G_k * F_n$$

where each  $G_i$  is freely indecomposable and  $F_n$  is free. Furthermore, this decomposition is canonical in the following sense: if  $G = G'_1 * \cdots * G'_m * F_\ell$  then  $m = k$ ,  $n = \ell$ , and up to permuting the factors, each  $G_i$  is conjugate to  $G'_i$  in  $G$ .

As we have already mentioned, the Makanin-Razborov diagram  $\text{MR}(G, S)$  is a rooted tree. Starting with the root vertex, which is labelled by  $G$ ,  $\text{MR}(G, S)$  can be constructed inductively as follows:

1. The edges coming out of  $G$  connect it to vertices labeled by the different factors in its canonical factor set from Theorem II.3.3; we label these edges by the corresponding quotient maps. If  $G$  is a limit group, we connect it to vertices labelled by the different factors in its Grushko decomposition (so if  $G$  is freely indecomposable, there is a single edge coming out of  $G$  and ending at another vertex labeled by  $G$ ). These edges are all unlabeled.
2. Let  $H$  be a vertex connected to  $G$ . Since  $H$  is a quotient of  $G$ , it comes equipped with a generating set which is the image of  $S$ . Then by Theorem II.3.3 and Theorem II.3.32,  $H$  admits a finite (generalized) factor set. Connect  $H$  by edges to vertices labeled by the quotients appearing in this factor set, and label each edge by the corresponding quotient map.
3. Let  $K$  be a vertex connected to  $H$ . If  $K$  is free, there are no more edges attached to  $K$ . Otherwise, repeat (1) for  $K$  (and the generating set that it inherits from  $G$ ).
4. By Claim II.3.29, our construction must terminate after finitely many steps.

**A drawing will be added later**(same as the drawing titled "Introduction to Section II.3")

To finish, we describe how the factorization of a homomorphism  $f : G \rightarrow F$  can be read from the diagram. To each such  $f$ , we associate a *subdiagram*  $T_f$  of the Makanin-Razborov diagram, constructed as follows:

1. The root vertex of  $T_f$  is labeled by  $(G, f)$ .
2. Since the vertices adjacent to  $G$  in the diagram are a factor set,  $f$  must factor via an edge corresponding to a quotient  $q : G \twoheadrightarrow Q$ ; write  $f = f' \circ q$ . Add an edge labeled by  $q$  connecting  $(G, f)$  to a vertex labeled by  $(Q, f')$ .
3. The vertex  $(Q, f')$  is now a limit group. Let  $Q = Q_1 * \cdots * Q_n * F_m$  be its Grushko decomposition. Then

$$\text{Hom}(Q, F) = \prod_{i=1}^n \text{Hom}(Q_i, F) \times F^m,$$

and  $f'$  decomposes as  $(f_1, \dots, f_n, f^m)$  in this product. Attach vertices labelled by  $(Q_i, f_i)$  (and  $(F_m, f^m)$ ) to  $(Q, f')$  by unlabeled edges. The vertex  $(F_m, f^m)$  is a leaf of  $T_f$ .

4. Now, continue with each  $(Q_i, f_i)$  as follows: the vertices adjacent to  $Q_i$  in the Makanin-Razborov diagram form a generalized factor set of  $Q_i$ . Therefore  $f_i$  is equivalent to some  $\widehat{f}_i$ , and  $\widehat{f}_i$  factors via a shortening quotient  $q : Q_i \twoheadrightarrow Q'$  of  $Q_i$ . Write  $\widehat{f}_i = \widehat{f}' \circ q$  and add an edge labeled by  $q$  connecting  $(Q_i, f_i)$  to a vertex labeled by  $(Q', \widehat{f}')$ .
5. Go back to step 3. and repeat the construction for  $(Q', \widehat{f}')$ .

# III

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## Formal solutions and $\text{Th}_{\forall\exists}^+(F)$



ERZLYAKOV studied *positive* formulas in free groups and came up with an algorithm that, given an  $\forall\exists$ -sentence  $\varphi$  which holds in  $F$ , yields a proof that  $F \models \varphi$ . Merzlyakov's proof implies that all non-abelian free groups share the same positive  $\forall\exists$  theory. In this chapter we will prove Merzlyakov's theorem using modern techniques (which are quite different to Merzlyakov's original combinatorial argument).

We begin by laying the groundwork which will allow us to state (and outline a rough strategy for the proof of ) Merzlyakov's theorem. Let  $\varphi$  be a sentence in the language of groups, and assume that  $\varphi$  is in *disjunctive normal form* (definition will be added to prelims later), that is

$$\varphi = \forall \bar{x}_1 \exists \bar{x}_2 \cdots \bigvee_{i=1}^k \bigwedge_{j=1}^{m_i} w_j(\bar{x}_1, \dots, \bar{x}_n) \stackrel{=}{\neq} 1.$$

The sentence  $\varphi$  is called *positive* if  $\neq$  does not appear in  $\varphi$ . We denote the *positive theory* of a group  $G$ , which consists of all the positive sentences which are true in  $G$ , by  $\text{Th}^+(G)$ .

*Remark III.0.1.* Note that some non-positive sentences may look positive upon first inspection. For example, the sentence  $\forall x \forall y \forall z \ xy = xz \rightarrow y = z$  does not contain the symbol  $\neq$ , but it is logically equivalent to the following sentence in DNF form

$$\forall x \forall y \forall z \ xy \neq xz \vee y = z,$$

which is not a positive sentence.

The following simple observation, which is left as an exercise, is crucial for our strategy:



**Exercise XVIII.** Let  $\varphi$  be a positive sentence and suppose that  $G \models \varphi$ . Let  $f : G \rightarrow H$  be a surjective homomorphism. Prove that  $H \models \varphi$ .

We remark (although we will not use this result) that in 1959, Lyndon proved the converse:

**Theorem III.0.2** ([9, Corollary 5.3]). *Let  $\varphi$  be a sentence such that whenever  $G \models \varphi$ , then  $\varphi$  holds in every homomorphic image of  $G$ . Then  $\varphi$  is logically equivalent to a positive sentence.*

The observation from Exercise XVIII turns the problem of showing that all free groups share the same positive  $\forall\exists$ -theory into a *lifting problem*: let  $\varphi$  be a positive  $\forall\exists$ -sentence. For expositional purposes, we assume for now that  $\varphi$  takes the following form,

$$\varphi = \forall \bar{x} \exists \bar{y} \Sigma(\bar{x}, \bar{y}) = 1,$$

where  $\Sigma(\bar{x}, \bar{y})$  is a system of equations in the variables  $\bar{x}, \bar{y}$  (so that  $\varphi$  is a disjunction of a single statement). Fix a non-abelian free group  $F_n$ , and suppose that  $F_n \models \varphi$ . Consider the finitely generated (in fact, finitely presented) group

$$G_\Sigma = \langle \bar{x}, \bar{y} \mid \Sigma(\bar{x}, \bar{y}) \rangle.$$

Note that the subgroup  $\langle \bar{x} \rangle$  of  $G_\Sigma$  must be isomorphic to the free group on  $\bar{x}$ : otherwise, there would be some  $\sigma \in \Sigma(\bar{x}, \bar{y})$  which involves only the variables  $\bar{x}$ , which contradicts the fact that  $F_n \models \varphi$ . In order to show that  $F_m \models \varphi$ , we need to solve the following lifting problem:

$$\begin{array}{ccc} & G_\Sigma & \\ & \uparrow i & \searrow \exists \widehat{f} \\ \langle \bar{x} \rangle \cong F(\bar{x}) & \xrightarrow{f} & F_m \end{array}$$

where  $i$  is the inclusion map  $\langle \bar{x} \rangle \hookrightarrow G_\Sigma$  and  $f : \langle \bar{x} \rangle \rightarrow F_m$  is an arbitrary homomorphism. Indeed, given any tuple  $\bar{g}$  in  $F_m$  of the same arity as  $\bar{x}$ , we can define  $f$  by mapping  $\bar{x}$  to  $\bar{g}$  and  $F_m \models \Sigma(\bar{g}, \widehat{f}(\bar{y}))$ .

Merzlyakov solved this lifting problem in the strongest possible way, namely by constructing the following diagram (note that in such a diagram we can replace  $F_m$  with any group  $G$ )

$$\begin{array}{ccc}
& G_\Sigma & \\
& \uparrow & \\
& \exists r \quad i & \\
& \downarrow & \\
\langle \bar{x} \rangle \cong F(\bar{x}) & \xrightarrow{f} & G
\end{array}$$

where  $r : G_\Sigma \rightarrow \langle \bar{x} \rangle$  is a *retraction* (the restriction  $r|_{\langle \bar{x} \rangle}$  is the identity map). Such a retraction is called a *formal solution* for the system of equations  $\Sigma(\bar{x}, \bar{y}) = 1$ . Simply put, a formal solution converts the "relations" between  $\bar{x}$  and  $\bar{y}$  given by  $\Sigma(\bar{x}, \bar{y})$  into a mechanism, that given a choice of values  $f(\bar{x})$  for  $\bar{x}$  in  $G$ , outputs suitable values for  $\bar{y}$  ( $f \circ r(\bar{y})$ ), which can be written as words in  $\bar{x}$ . In other words,

**Theorem III.0.3** ([10]). *Let  $\varphi = \forall \bar{x} \exists \bar{y} \Sigma(\bar{x}, \bar{y}) = 1$  and let  $F$  be a non-abelian free group. If  $F \models \varphi$  then there is a formal solution for  $\Sigma(\bar{x}, \bar{y}) = 1$ .*

We immediately deduce:

**Corollary III.0.4.** *All non-abelian free groups share the same positive  $\forall \exists$ -theory.*

*Remark III.0.5.* Note that the existence of a formal solution implies that if  $\varphi$  is a positive  $\forall \exists$ -sentence which holds in a (non-abelian) free group, then  $\varphi$  is satisfied by every group. Exercise XVIII also implies this fact, under the assumption that the positive  $\forall \exists$ -theories of all non-abelian free groups coincide. In other words,  $\text{Th}_{\forall \exists}^+(F) \subset \text{Th}_{\forall \exists}^+(G)$  for every  $G$ .

This is the origin of the following terminology: if  $\text{Th}_{\forall \exists}^+(G)$  coincides with that of  $F$ , we say that  $G$  has *trivial positive  $\forall \exists$ -theory*.

*Remark III.0.6.* In a recent paper, Casals-Ruiz, Garreta, and de la Nuez González proved that if a group  $G$  satisfies a positive sentence which is not satisfied by  $F$ , then  $G$  satisfies a positive  $\forall \exists$ -sentence which is not satisfied by  $F$ . Therefore, if  $G$  has trivial positive  $\forall \exists$ -theory then it has *trivial positive theory*: every positive sentence satisfied by  $G$  is satisfied by all groups.

Lastly, we would like to bring the reader's attention to the following connection:

*Remark III.0.7.* Recall the *implicit function theorem*: Let  $F : \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a continuously differentiable function, and suppose that  $F(x_0, y_0) = 0$  for some point  $(x_0, y_0) \in \mathbb{R}^n \times \mathbb{R}^m$ . If the Jacobian matrix  $\frac{\partial F}{\partial x}(x_0, y_0)$  is invertible (i.e., it has full rank), then we can solve the equation  $F(x, y) = 0$  locally for  $y$  as a function of  $x$ . Specifically,

there exists a neighborhood  $U$  of  $x_0$  in  $\mathbb{R}^n$  and a continuously differentiable function  $g : U \rightarrow \mathbb{R}^m$  such that:

$$F(x, g(x)) = 0 \quad \text{for all } x \in U,$$

with  $g(x_0) = y_0$ . In other words, the implicit relation between  $x$  and  $y$  given by  $F(x, y) = 0$  can be converted into an explicit function  $y = g(x)$  in a neighborhood of  $x_0$ .

This statement bears a great resemblance to Merzlyakov's Theorem [III.0.3](#); for this reason, some authors refer to Merzlyakov's theorem as an implicit function theorem for free groups.

Lastly, we would like to mention that Merzlyakov's theorem admits many generalizations. These include the introduction of inequalities, a restriction of  $\bar{x}$  to a variety, and versions for other classes of groups (hyperbolic groups, acylindrically hyperbolic groups,  $\pi$ -groups).

### III.1 Outline of the strategy of the proof of Merzlyakov's Theorem [III.0.3](#)

We begin by briefly outlining our strategy for proving Merzlyakov's Theorem [III.0.3](#):

1. Since  $F \models \forall \bar{x} \exists \bar{y} \Sigma(\bar{x}, \bar{y}) = 1$ , every choice of a tuple  $\bar{g}$  in  $F$  (of the same arity as  $\bar{x}$ ) gives rise to a homomorphism  $f_g : G_\Sigma = \langle \bar{x}, \bar{y} \mid \Sigma(\bar{x}, \bar{y}) \rangle$ . This suggests that if we carefully choose a sequence different tuples  $\bar{g}_n$  in  $F$ , we will be able to control the way  $L$  acts on the limiting  $\mathbb{R}$ -tree  $T$ .
2. We will choose the sequence of tuples  $\bar{g}_n$  to be a *test sequence*: a sequence of elements satisfying a *small cancellation* property, which essentially means that the different elements of  $\bar{g}_n$  do not share “long subwords”. Each  $\bar{g}_n$  will give rise to a homomorphism  $\varphi_n : G_\Sigma \rightarrow F$ .
3. To utilize (a relative version of) the shortening argument, we will choose  $\varphi_n$  to be the *shortest* homomorphism which maps  $\bar{x}$  to  $\bar{g}_n$  (up to conjugation). The shortening argument will imply that the elements of  $\varphi_\infty(\bar{x})$  all act hyperbolically on the limiting tree  $T$ .

4. The small cancellation above will tell us how different translates of segments of the form  $[o, x_i.o]$  interact in  $T$ . Using the *Rips machine* we will deduce that  $T$  has a fundamental domain for the action of  $L$  which consists of the basepoint, along with the interior of the segments  $[o, x_i.o]$ . We will also prove that  $L$  acts transitively on the vertices of  $T$ . This implies that  $L$  coincides with the free group on  $\bar{x}$ , which completes the proof.

Before beginning with the construction of a test sequence, we make the following simple observation:

**Lemma III.1.1.** *The subgroup  $\langle \bar{x} \rangle$  of  $G_\Sigma$  is free.*

*Proof.* Suppose not, then there is a word  $w$  such that  $w(\bar{x}) = 1$  in  $G_\Sigma$ . Then the system of equations  $\Sigma(\bar{x}, \bar{y})$  has the same set of solutions as  $\Sigma(\bar{x}, \bar{y}) \cup \{w(\bar{x}) = 1\}$  (in any group). But clearly there is a tuple of elements  $\bar{g}$  in  $F$  such that  $w(\bar{g}) \neq 1$ , contradicting the fact that  $F \models \exists \bar{y} \Sigma(\bar{g}, \bar{y}) = 1$ .  $\square$

## III.2 Test sequences

Recall that an element  $g \in F$  is called *cyclically reduced* every cyclic permutation of  $g$  is a reduced word; this is equivalent to saying that the first and last letters of  $g$  are not inverses of one another, or that the word length  $|g|_F$  of  $g$  is the minimal in its conjugacy class. In particular, every element in  $F$  is conjugate to a cyclically reduced element. As Exercise [XXV](#), if  $g$  is cyclically reduced then 1 lies on  $\text{Axis}(g)$  in the Cayley graph of  $F$ .

**Definition III.2.1.** Let  $g_1, \dots, g_k \in F$  be cyclically reduced elements and let  $R$  be the collection of all cyclic permutations of  $g_1, \dots, g_k, g_1^{-1}, \dots, g_k^{-1}$ . A *piece*  $u$  is an element of  $F$  that appears as a maximal initial subword of two distinct  $r_1, r_2 \in R$ . We say that  $g_1, \dots, g_n$  satisfy the *metric small cancellation*  $C'(\lambda)$  (for some  $\lambda > 0$ ) if for every piece  $u$ , and every  $r \in R$  such that  $u$  is a subword of  $r$ ,

$$|u|_F < \lambda \cdot |r|_F.$$

We say that a tuple  $\bar{g}$  in  $F$  (of elements which are not necessarily cyclically reduced) satisfies the  $C'(\lambda)$ -metric small cancellation condition if replacing each element of  $\bar{g}$  with a cyclically reduced conjugate results in a tuple that satisfies the  $C'(\lambda)$ -metric small cancellation condition.

**Example III.2.2.** If  $F$  is the free group on  $a, b, \dots, z$ ,  $g_1 = \text{ronald}$  and  $g_2 = \text{mcdonald}$ , then  $\text{onald}$  is the longest piece (in fact, the only piece) and  $g_1, g_2$  satisfy the  $C'(0.9)$  metric small cancellation condition. On the other hand, if  $g_1 = \text{groups}$  and  $g_2 = \text{logic}$  then every piece is of length 1 and  $g_1, g_2$  satisfy the  $C'(1/4)$  metric small cancellation condition.

The metric small cancellation condition tells us about how the axes of conjugates of elements can intersect:

**Exercise XIX.** Let  $g_1, \dots, g_k \in F$  be cyclically reduced elements that satisfy the  $C'(\lambda)$ -metric small cancellation condition. Prove that if

$$\text{diameter}(\text{Axis}(g_i) \cap \text{Axis}(hg_jh^{-1})) \geq \lambda \cdot \min\{\ell(g_i), \ell(g_j)\},$$

then  $i = j$  and  $h$  commutes with  $g_i$ .

*Remark III.2.3.* The condition described above is also known as the *geometric  $\lambda$ -small cancellation condition*, and it can be defined for elements in groups which are not free (for example, for hyperbolic elements in a group that acts on a tree). In the case of free groups it is equivalent to the metric small cancellation condition. Also, if  $\bar{g}$  satisfies a small cancellation condition, we can often deduce nice properties of the quotient  $F/\langle\langle\bar{g}\rangle\rangle$ .

We can now define *test sequences*:

**Definition III.2.4.** Keeping the notation from before, a *test sequence* for  $G_\Sigma$  is a sequence of homomorphisms  $\varphi_n : G_\Sigma \rightarrow F$  such that

1. for every  $n$ , the tuple  $\varphi_n(\bar{x})$  satisfies the  $C'(\epsilon_n)$ -metric small cancellation condition and  $\lim_{n \rightarrow \infty} \epsilon_n = 0$ ,
2. for every  $i, j$  there exists  $0 < r_{i,j} < \infty$  such that  $\frac{\ell(\varphi_n(x_i))}{\ell(\varphi_n(x_j))} \rightarrow r_{i,j}$  as  $n \rightarrow \infty$ .

It is easy to construct test sequences:

**Lemma III.2.5.** *Under our assumptions, there exists a test sequence for  $G_\Sigma$ .*

*Proof.* As we have already discussed, since  $F \models \forall \bar{x} \exists \bar{y} \Sigma(\bar{x}, \bar{y})$ , for every tuple  $\bar{g}$  in  $F$  of the same arity as  $\bar{x}$ , there exists a homomorphism  $G_\Sigma \rightarrow F$  which maps  $\bar{x}$  to  $\bar{g}$ . Therefore, it is enough to construct tuples  $\bar{g}_n$  in  $F$  satisfying the desired metric small cancellation conditions.

Write  $\bar{g}_n = (g_{1,n}, \dots, g_{k,n})$  and define

$$\begin{aligned} g_{1,n} &= abab^2 \dots ab^n, \\ g_{2,n} &= ab^{n+1} ab^{n+2} \dots ab^{2n} \\ &\dots \\ g_{k,n} &= ab^{(k-1)n+1} \dots ab^{kn}. \end{aligned}$$

An easy calculation shows that  $\bar{g}$  satisfies the  $C'(\epsilon_n)$ -metric small cancellation condition for  $\epsilon_n \approx 1/n$ , and that

$$\frac{\ell(\varphi_n(x_i))}{\ell(\varphi_n(x_j))} \rightarrow \frac{i - 1/2}{j - 1/2}.$$

□

Before continuing with the proof of Merzlyakov's Theorem [III.0.3](#), we make the following remark which will be useful later on:

*Remark III.2.6.* Note that for every  $n$ , the axes of all of the elements in  $\bar{g}_n$  pass through 1 in the Cayley graph of  $F$  since each  $g_{i,n}$  is cyclically reduced. In addition, if  $\phi_n : G_\Sigma \rightarrow F$  is a sequence of homomorphisms that coincides with  $\varphi_n$  on  $\bar{x}$  up to conjugation, then  $(\phi_n)$  is also a test sequence.

### III.3 The limiting tree

Armed with a test sequence  $\varphi_n : G_\Sigma \rightarrow F$ , we obtain a limit group  $L = G_\Sigma / \underline{\ker}_\omega(\varphi_n)$  which acts on a limiting tree  $T$ . For the time being, we make the following assumption: the tree  $T$  is not a line. As we will see, this occurs exactly when the tuple  $\bar{x}$  consists of a single element; we will deal with this case later.

**Lemma III.3.1.** *The quotient map  $\varphi_\infty : G_\Sigma \rightarrow L$  is injective on  $\bar{x}$ .*

*Proof.* Let  $g \in \langle \bar{x} \rangle$  be a nontrivial reduced word; the  $C'(\epsilon_n)$ -metric small cancellation condition tells us that at most  $\epsilon_n \cdot |\varphi_n(g)|$  of the letters in  $\varphi_n(g)$  can cancel, so the word length of  $\varphi_n(g)$  is positive for  $n > 2$  which implies that  $g \notin \underline{\ker}_\omega(\varphi_n)$ . □

We will therefore, from now on, identify  $\varphi_\infty(\bar{x})$  with  $\bar{x}$  and refer to both as  $\bar{x}$ . The shortening argument Theorem [II.3.25](#) will appear numerous time in our proof. However, the version that we will use is slightly different to the one already mentioned. We will use a *relative* version of the shortening argument; we amass the relevant definition first:

**Definition III.3.2.** Let  $G$  be a finitely generated group and let  $H \leq G$ . Given  $\varphi : G \rightarrow F$ , recall the definition of  $\|\varphi\|$  Definition II.3.21. We say that  $\varphi$  is *short* with respect to  $H$  if  $\|\varphi\| \leq \|\text{ad}(g) \circ \varphi \circ \alpha\|$  for every  $g \in F$  and  $\alpha \in \text{Aut}(G)$  which fixes  $H$ .

**Theorem III.3.3** (The relative shortening argument). *Suppose that  $G$  is freely indecomposable relative to  $H$  and let  $\varphi_n : G \rightarrow F$  be a sequence of homomorphisms. Suppose that  $H$  fixes a point in the limiting tree  $T$ . If  $\underline{\ker}_\omega(\varphi_n) = 1$  then  $\varphi_n$  is not short with respect to  $H$   $\omega$ -almost-surely.*

Using the relative shortening argument, we will construct a test sequence which satisfies the following properties:

1.  $L$  is freely indecomposable with respect to  $\bar{x}$ , and
2. Every element of  $\bar{x}$  acts hyperbolically on  $T$ .

To this end, we make the following assumption: when constructing  $\varphi_n : G_\Sigma \rightarrow F$ , we choose the images of  $\bar{y}$  to be the “shortest possible”, or in other words, such that  $\varphi_n$  is short with respect to  $\bar{x}$ .

**Lemma III.3.4.** *Let  $\theta_n : L \rightarrow F$  be such that  $\varphi_n$  factors via  $\theta_n$   $\omega$ -almost-surely. We may assume that:*

1.  $L$  is freely indecomposable relative to  $\langle \bar{x} \rangle$ ,
2.  $\theta_n$  is short relative to  $\bar{x}$ ,
3.  $\underline{\ker}_\omega(\theta_n)$  is trivial (or in other words, the action of  $L$  on  $T$  does not have a global fixed point).

*Proof.* Suppose not, then  $L = L_1$  splits as a free product  $L = L^1 * L'^1$  such that  $\bar{x} \leq L^1$ . There is a quotient map  $q^1 : L \rightarrow L^1$ . Consider the sequence of homomorphisms  $\theta_n|_{L^1} : L^1 \rightarrow F$ , and replace each  $\theta_n|_{L^1}$  with the shortest morphism  $L^1 \rightarrow F$  relative to  $\bar{x}$  which coincides with  $\theta_n|_{L^1}$  on  $\bar{x}$  up to conjugation.

If the stable kernel of the new sequence is trivial, we are done. Otherwise, consider the quotient  $q^1 : L^1 \rightarrow L_2 = L^1 / \underline{\ker}_\omega(\theta_n)$ . Note that it is still injective on  $\bar{x}$  by the properties of the test sequence. If  $L_2$  is freely indecomposable with respect to  $\bar{x}$ , we are done; otherwise, write  $L_2 = L^2 * L'^2$  and repeat the process above to obtain  $q_2 : L_2 \rightarrow L^2$  and  $q^2 : L^2 \rightarrow L_3$ . Iterate this process. By Claim II.3.29 the sequence eventually stabilizes, which gives the desired result. **a diagram describing the factorizations will be added** □

From this, we deduce:

**Lemma III.3.5.** *Every element of  $\bar{x}$  acts hyperbolically on  $T$ .*

*Proof.* As mentioned in Remark III.2.6, for every  $n$  there exists  $p_n$  in the Cayley graph  $X$  of  $F$  which lies in the intersection of the axes of the elements of  $\varphi_n(\bar{x})$ . It is enough to prove that  $(p_n)$  is visible. Indeed, if this is the case, the relative shortening argument Theorem III.3.3 implies that not all of the elements of  $\bar{x}$  fix  $(p_n)$  (in which case,  $\langle \bar{x} \rangle$  would fix  $(p_n)$  which is a contradiction). But now, the second condition of Definition III.2.4 implies that if some element of  $\bar{x}$  moves  $(p_n)$  then so do all of the elements of  $\bar{x}$ , because in the limiting tree  $T$

$$\frac{d((p_n), x_i.(p_n))}{d((p_n), x_j.(p_n))} = r_{i,j} > 0.$$

In addition, for every  $x_i$  in  $\bar{x}$  and every  $(t_n) \in T$  we have that  $d((p_n), x_i.(p_n)) \leq d((t_n), x_i.(p_n))$  and therefore if  $x_i$  does not fix  $(p_n)$  then it doesn't fix a point in  $T$ , so it acts hyperbolically.

It is therefore left to show that there exists such a point  $(p_n) \in T$ . By our choice of the tuples  $\bar{g}_n = \varphi_n(\bar{x})$ , every element in  $\text{Axis}(\varphi_n(x_1)) \cap \text{Axis}(\varphi_n(x_2))$  is contained in every  $\text{Axis}(\varphi_n(x_i))$  **a drawing will be added**. We remark that this is not necessarily the case with every test sequence, but the proof in the general case is similar. Therefore, in our case, it is enough to find a point  $p_n \in \text{Axis}(\varphi_n(x_1)) \cap \text{Axis}(\varphi_n(x_2))$  such that  $(p_n)$  is visible.

Consider the basepoint  $o_n \in X$ , and by Exercise XXV,

$$d_n(o_n, \varphi_n(x_1).o_n) = 2d_n(o_n, \text{Axis}(\varphi_n(x_1))) + \ell(\varphi_n(x_1)).$$

Let  $p_n^1$  be the point on  $\text{Axis}(\varphi_n(x_1))$  which realizes the distance above. Since

$$\lim_{\omega} d_n(o_n, \varphi_n(x_1).o_n) < \infty,$$

we have that  $d_n(o_n, p_n^1) < \infty$   $\omega$ -almost-surely, so  $(p_n^1)$  is a visible sequence of points that lie on  $\text{Axis}(\varphi_n(x_1))$ . Similarly, one gets a visible sequence  $(p_n^2)$  of points that lie on  $\text{Axis}(\varphi_n(x_2))$ . Therefore, the geodesic between  $(p_n^1)$  and  $(p_n^2)$  lies in  $T$ , and by Lemma II.3.15 and Remark II.3.16, every point which lies on this geodesic can be approximated by points on the geodesic  $[p_n^1, p_n^2]$  in  $X$  (and vice versa). Since paths between points in a tree are unique, the geodesic  $[p_n^1, p_n^2]$  in  $X$  passes through a point  $p_n$  on  $\text{Axis}(\varphi_n(x_1)) \cap \text{Axis}(\varphi_n(x_2))$ . We deduce that  $(p_n)$  is a visible sequence as desired.  $\square$



*Remark III.3.6.* In light of this lemma, we may assume that the basepoint  $o = (o_n)$  of  $T$  is simply  $o = (1)$ .

Our next goal, is to show that the action of  $\langle \bar{x} \rangle$  on  $T$  “covers” the entire tree; in other words, as stated earlier, we wish to show that the basepoint  $o$ , along with the interiors of the segments  $[o, x_i.o]$ , form a fundamental domain for the action of  $L$  on  $T$ . In other words, we wish to show that the *minimal tree* for the action of  $\langle \bar{x} \rangle$  on  $T$  is the entire tree  $T$ . We introduce the following notation:

**Notation III.3.7.** As before, write  $\bar{x} = x_1, \dots, x_n$ , and denote by  $o = (o_n)_{n \in \mathbb{N}}$  the basepoint of  $T$ . For each  $1 \leq i \leq n$ , let  $\gamma_i$  be the geodesic segment  $[o, x_i.o]$  in  $T$ . The subgroup  $\langle \bar{x} \rangle$  of  $L$  acts on  $T$ , and it admits a *minimal subtree*  $\bar{T}$ : a subtree  $\bar{T} \subset T$  on which  $\langle \bar{x} \rangle$  acts, without an invariant subtree; we choose  $\bar{T}$  to be the minimal subtree for  $\langle \bar{x} \rangle$  containing  $o$  (and therefore,  $\gamma_i \subset \bar{T}$  for every  $1 \leq i \leq n$ ). Note that  $\bar{T}$  is covered by translates of  $\gamma_1 \cup \dots \cup \gamma_n$ , and coincides with the *convex hull* of (that is, the minimal convex subset containing) the axes of the hyperbolic elements in  $\langle \bar{x} \rangle$ .

Before we can prove that  $T$  coincides with  $\bar{T}$ , we need to understand  $T$  (and the action of  $L$  on  $T$  better). For this, we will use the *Rips machine*, which under mild assumptions yields a decomposition of  $T$  into components which are easier to understand. We begin by defining what a “decomposition” of an  $\mathbb{R}$ -tree means in this case:

**Definition III.3.8.** Let  $T$  be an  $\mathbb{R}$ -tree, and let  $\{T_i \mid i \in I\}$  be a family of closed subtrees of  $T$ . We say that  $\{T_i\}$  forms a *transverse covering* of  $T$  if the following conditions are met:

1. the family of subtrees covers  $T$ , that is  $\bigcup_{i \in I} T_i = T$ ;
2. for every  $i \neq j$ ,  $T_i \cap T_j$  is either empty or a single point;
3. every arc  $\gamma \subset T$  is covered by finitely many  $T_i$ .

**Theorem III.3.9** (The Rips Machine). *Let  $G$  be a finitely presented, torsion free group, which acts on an  $\mathbb{R}$ -tree  $T$ . Suppose that the action of  $G$  on  $T$  satisfies the following conditions:*

1. *the action is minimal (that is, there is no invariant subtree  $T' \subset T$  for the action of  $G$ ),*
2. *the stabilizer of every tripod in  $T$  is trivial, and*

3. the action is superstable: let  $I \subset T$  be an arc with a non-trivial stabilizer, then for every subarc  $J \subset I$  we have that  $\text{Stab}(I) = \text{Stab}(J)$ .

Then there are finitely many subtrees  $T_1, \dots, T_k \subset T$  whose collection of translates by  $G$  forms a transverse covering of  $T$ , and such that every  $T_i$  has one of the following forms (we denote by  $G_i$  the subgroup of  $G$  which preserves  $T_i$ ):

1.  $T_i$  is axial, that is  $T_i$  is a line,  $G_i$  acts on  $T_i$  with dense orbits and the image of  $G_i$  in  $\text{Isom}(T_i)$  is finitely generated.
2.  $T_i$  is of surface type, that is  $T_i$  is dual to a measured foliation on a surface (with boundary).
3.  $T_i$  is simplicial, that is every branching point in  $T_i$  is isolated.
4.  $T_i$  is exotic, and  $G$  splits as a free product.

*Remark III.3.10.* Exotic components do not admit a uniform description as the other types, but we will later see that the fact that  $L$  is freely indecomposable with respect to  $\langle \bar{x} \rangle$  will allow us to ignore them.

We also highlight the following property of axial, surface type and exotic components, which will come into play later in the proof:

**Definition III.3.11.** Keeping the notation above, we say that a component  $T_i$  has the *mixing property* if for any two arcs  $I, J \subset T$ , there is a partition of  $I$  into finitely many arcs  $I_1, \dots, I_\ell$ , and elements  $g_1, \dots, g_\ell \in G_i$ , such that  $g_i.I_i \subset J$  for every  $1 \leq i \leq \ell$ .

**Exercise XX.** Given a transverse covering  $\{T_i\}$  of  $T$ , the *skeleton* corresponding to the transverse covering is a bipartite graph  $S$  defined as follows:

- The vertex set  $V(S)$  is the disjoint union of the sets  $V_1 = \{T_i\}$  and  $V_2$  which consists of all points  $x \in T$  which belong to at least two distinct subtrees  $T_i$  and  $T_j$ .
- The edge set  $E(S)$  consists of pairs of the form  $(T_i, x)$  where  $T_i \in V_1$ ,  $x \in V_2$  and  $x \in T_i$ ,

Prove that  $S$  is a tree, and that if for every  $T_i$ ,  $g.T_i$  is some  $T_j \in \{T_i\}$ , then  $S$  endowed with a suitable action of  $G$ . Deduce that  $G$  splits as a graph of groups whose vertex groups are the subgroups  $G_i \leq G$  preserving the subtrees  $T_i$ .

*Remark III.3.12.* A graph of groups as described in Exercise [XX](#) above, together with the additional information recrding the trees  $T_i$  and the actions of  $G_i$  on each  $T_i$ , is called a *graph of actions*.

Having recollected the relevant definitions, we are ready to show that in our case, the action of  $L$  on  $T$  satisfies the conditions of Theorem [III.3.9](#).

**Lemma III.3.13** (Stability lemma). *The action of  $L$  on  $T$  satisfies the following:*

1. *Tripod stabilizers are trivial.*
2. *Arc stabilizers are abelian.*
3. *The action is superstable.*

*Proof.* For 1., let  $P$  be a tripod in  $T$  spanned by three points  $x = (x_n), y = (y_n)$  and  $z = (z_n)$ ; let  $g \in L$  be an element that fixes  $P$ . Denote the centre of the tripod by  $c = (c_n)$ . The tripod  $P$  gives rise to approximating tripods  $P_n$  in the rescaled Cayley graphs  $X_n$  of  $F$ , spanned by  $x_n, y_n$  and  $z_n$  and admitting a centre  $c_n$ . Let

$$\ell = \min\{d(x, c), d(y, c), d(z, c)\}$$

and since  $g$  fixes each of the points  $x, y$  and  $z$ , we have that **replace  $\ell$  with  $d_n(x_n, c_n)$  and  $g$  by  $\varphi_n(g)$**

$$d_n(x_n, g.x_n) < \ell/3, \quad d_n(x_n, g.y_n) < \ell/3 \quad \text{and} \quad d_n(z_n, g.z_n) < \ell/3.$$

Consider the tripod  $P'_n$  spanned by  $g.x_n, g.y_n$  and  $g.z_n$ . Since  $X_n$  is a tree, paths are unique, and each of the arcs  $[g.x_n, g.y_n], [g.x_n, g.z_n]$  and  $[g.y_n, g.z_n]$  must pass through  $c_n$ . **A figure will be added.** It follows that  $c_n \in P'_n = g.P_n$  and that  $g$  must fix  $c_n$ . Since the action of  $L$  on  $X_n$  is free,  $g$  must be trivial.

The proof of 2. follows the same idea: let  $[x = (x_n), y = (y_n)]$  be an arc in  $T$ , and let  $g, h \in \text{Stab}([x, y])$ . We will show that  $[g, h] = 1$ . Denote  $d(x, y) = \ell$ , and as before, looking at the approximations  $X_n$  of  $T$  we have that

$$d_n(x_n, g.x_n) < \ell/6, \quad d_n(y_n, g.y_n) < \ell/6, \quad d_n(x_n, h.x_n) < \ell/6 \quad \text{and} \quad d_n(y_n, h.y_n) < \ell/6.$$

Let  $p_n$  be the point on  $[x_n, y_n]$  at distance  $\ell/6$  from  $x_n$ , and let  $q_n$  be the point on  $[x_n, y_n]$  at distance  $\ell/6$  from  $y_n$ . The condition above implies that both  $g$  and  $h$  act on (a subarc of length  $\ell/3$  of)  $[p_n, q_n]$  by translation of length at most  $\ell/6$ . Let  $c_n \in [p_n, q_n]$  be the midpoint of  $[x_n, y_n]$ . Then  $[g, h].c_n = c_n$  **a drawing will be added later** and as before  $[g, h] = 1$ .

We can now easily deduce that 3. holds. Let  $J \subset I$  be arcs in  $T$ ; we have that  $\text{Stab}(I) \leq \text{Stab}(J)$  and suppose for a contradiction that  $\text{Stab}(I) \neq \text{Stab}(J)$ . Therefore, there exists  $g \in L$  which fixes  $J$  and does not fix  $I$ . We will show that under these circumstances, the stabilizer of  $I$  must be trivial.

Write  $I = [a, b]$  and note that  $g$  cannot fix both  $a$  and  $b$  (since it doesn't fix  $I$ ). Assume that  $g.b \neq b$ . Note that  $g.b$  cannot lie on  $[a, b]$ : this would only be possible if  $g.b = a$ , but  $g$  does not invert  $I$  since it fixes  $J$ . Now, let  $h \in \text{Stab}(I)$ . Since  $h$  fixes  $I$ , it also fixes its subarc  $J$  and by 2.  $h$  and  $g$  commute. Also, we have that  $h.a = a$  and  $h.b = b$ . To finish, note that  $h.(g.b) = g.h.b = g.b$ , which implies that  $h$  fixes the (non-degenerate) tripod spanned by  $a, b$  and  $g.b$ . By 1.,  $h = 1$ .  $\square$

**Exercise XXI.** Let  $T'$  be a bi-infinite line in  $T$ , and suppose that  $L' \leq L$  preserves  $T'$  and its end-points (so that every  $g \in L'$  acts on  $T'$  by translation). Prove that  $L'$  is abelian.

We continue by proving what perhaps is the key lemma in the proof of Theorem III.0.3, and in which the small cancellation condition (Definition III.2.1) plays a crucial role. For this, we introduce the following notation:

**Lemma III.3.14.** *Let  $I$  be an arc contained in  $\gamma_i$  for some  $1 \leq i \leq n$ . Then for every  $1 \neq g \in L$ , and any  $1 \leq j \leq n$ ,  $g.I \cap \gamma_j$  is at most a point.*

**Corollary III.3.15.** *This means that  $\overline{T}$  lies on the discrete part of  $T$ . Indeed, it intersects each of the components of  $T$  with the mixing property in at most a point: if  $T_i$  is a component with the mixing property that intersects  $\overline{T}$  in more than a point, then it has a common arc with  $\overline{T}$ . Therefore, there are two arcs  $I, J$  in  $\overline{T}$ , covered by translates of some  $\gamma_i$  and  $\gamma_j$ , and some  $g \in L$ , such that  $g.I \subset J$ , contradicting Lemma III.3.14.*

*Proof of Lemma III.3.14.* Suppose that for some  $1 \neq g \in L$ , and some  $I \subset \gamma_i$ ,  $g.I$  intersects some  $\gamma_j$  in more than a point. Up to replacing  $I$  with a subarc, we may assume that  $g.I \subset \gamma_j$ . Write  $I = [a, b] = [(a_n), (b_n)]$ . We next turn to look at  $I$  and  $g.I$  in the approximations  $X_m$  of  $T$ . We denote the lengths of  $I$ ,  $\gamma_i$  and  $\gamma_j$  by  $\ell, \ell_i$  and  $\ell_j$  respectively.

In  $X_m$ , the arc  $[a_m, b_m]$  is labeled by a word  $w_m$  which is a subword of  $\varphi_m(x_i)$ ; the arc  $[\varphi_m(g).a_m, \varphi_m(g).b_m]$  is labeled by the same word  $w_m$ , which is a subword of  $\varphi_m(x_j)$  (note that we didn't require that  $i \neq j$ ). Since  $g \neq 1$  in  $L$ , we have that  $\varphi_m(g) \neq 1$   $\omega$ -almost-surely. Therefore,  $\varphi_m(g)$  does not fix any point of  $X$  (as  $F$  acts

freely on its Cayley graph  $X$ ). This implies that  $w_m$  is a piece for  $\varphi_m(x_1), \dots, \varphi_m(x_n)$ . Measuring distances in  $T$ , we have that

$$\lim_{\omega} \frac{|w_m|_F / \|\varphi_m\|}{\min(d_m(1, \varphi_m(x_j)), d_m(1, \varphi_m(x_j)))} = \frac{\ell}{\min(\ell_i, \ell_j)} > 0$$

but on the other hand, the small cancellation condition from Definition III.2.4 implies that

$$\begin{aligned} \lim_{\omega} \frac{|w_m|_F / \|\varphi_m\|}{\min(d_m(1, \varphi_m(x_j)), d_m(1, \varphi_m(x_j)))} &\leq \\ \lim_{\omega} \epsilon_m \cdot \min(d_m(1, \varphi_m(x_j)), d_m(1, \varphi_m(x_j))) &= \\ \lim_{\omega} \epsilon_m \cdot \min(\ell_i, \ell_j) &= 0, \end{aligned}$$

a contradiction. □

## III.4 Shortening in practice

Having established that  $\overline{T}$ , the minimal tree for  $\langle \overline{x} \rangle$  under  $L \curvearrowright T$  (and all of its translates) is contained in the simplicial components of  $T$ . In this section, we will dive deeper into the shortening argument, and use it to show that  $T$  is in fact a simplicial tree; we will do so by showing that the components of  $T$  outputted by the Rips machine Theorem III.3.9 are all simplicial. Recall that, as we have already mentioned, if some component  $T_i$  of  $T$  were exotic, then the subgroup  $L_i$  of  $L$  preserving  $T_i$  would split as a free product. This decomposition, would ascend to a free decomposition of  $L$  where  $\langle \overline{x} \rangle$  is contained in one of the factors, contradicting Lemma III.3.4 which showed that  $L$  is freely indecomposable relative to  $\langle \overline{x} \rangle$ .

**Proposition III.4.1.** *Let  $T_1, \dots, T_k$  be the components of  $T$  obtained from the Rips machine. Then every  $T_i$  is simplicial (or in other words, none of the components is axial or of surface type).*

The proof of Proposition III.4.1 easily follows from the proof of the Shortening argument Theorem III.3.3; however, in order to use it, we need to state it in further detail, in a form that caters for our specific needs. We begin by stating a version suited for axial and surface type components.

**Theorem III.4.2.** *Let  $G$  be a finitely generated group acting on a real tree  $T$  with basepoint  $o$ , and suppose that satisfies the conditions of Theorem III.3.9. Denote by  $T_1, \dots, T_k$  the components of  $T$  outputted by the Rips machine. Let  $Y$  be a finite subset of  $G$  and let  $T_i$  be an axial component or a component of surface type. Then there exists an automorphism  $\alpha_i \in \text{Aut}(G)$  such that for every  $y \in Y$  the following holds:*

1. If  $[o, y.o]$  intersects a translate of  $T_i$  in more than a point, then

$$d(o, \alpha_i(y).o) < d(o, y.o).$$

2. Otherwise,  $\alpha_i(y) = y$ .

An explanation, as given in class, is non-examinable (but might be added to the notes at a later point)

*Proof of Proposition III.4.1.* Suppose that some component  $T_i$  of  $T$  is axial or of surface type. Since the action of  $L$  on  $T$  is minimal,  $T$  is covered by translates of segments of the form  $[o, x_j.o]$  and  $[o, y_j.o]$ . By Corollary III.3.15, no translate of  $[o, x_i.o]$  can intersect non-trivially a component with the mixing property; hence, for some  $j$ , some translate of  $[o, y_j.o]$  intersects  $T_i$  in an arc. Replacing  $T_i$  by a translate, we may assume that  $T_i$  intersects  $[o, y_j.o]$  in an arc.

By Theorem III.4.2, setting  $Y = \bar{x} \cup \bar{y}$  there exists an automorphism  $\alpha_i$  of  $L$  such that  $d(\alpha_i(y_j).o) < d(o, y_j.o)$ ; note that for every  $y_k$  we have that  $d(\alpha_i(y_k).o) \leq d(o, y_k.o)$ . Similarly, since  $[o, x_k.o]$  does not intersect any (translate of a) component with the mixing property non-trivially, we deduce that  $\alpha_i(x_k) = x_k$ .

Recall that the factorization of the homomorphisms  $\varphi_n : G_\Sigma \rightarrow F$  via  $L$  was denoted by  $\theta_n : L \rightarrow F$ , and that by Lemma III.3.4,  $\theta_n$  is short relative to  $\bar{x}$   $\omega$ -almost-surely. But we have that

$$d_n(\theta_n \circ \alpha_i(y_k).o_n, o_n) < d_n(\theta_n(y_k).o_n, o_n)$$

$\omega$ -almost-surely, so  $\|\theta_n \circ \alpha_i\| < \|\theta_n\|$ , a contradiction.  $\square$

**Corollary III.4.3.** *The tree  $T$  is a simplicial tree.*

Recall that by Lemma III.3.14, every edge of  $\bar{T}$  is trivially stabilized; the same holds for every edge of the simplicial tree  $T$ :

**Proposition III.4.4.** *For every edge  $e$  of  $T$ ,  $\text{Stab}(e) = \{1\}$ .*

To prove the proposition, we will use the following version of the shortening argument, which allows us to deal with the simplicial case.

**Definition III.4.5.** Let  $G$  be a group acting on a real tree  $T$ , and let  $e$  be an edge of  $T$  (that is, an arc that contains no branching points). Suppose that  $\text{Stab}(e)$  fixes  $e$  pointwise, that is, no element of  $\text{Stab}(e)$  acts on  $e$  by inversion. The edge  $e$  induces a splitting of  $G$ , obtained as follows: write  $e = [a, b]$ , and consider  $S = T - \bigcup_{g \in G} g.e$ .

Let  $A$  be the connected component of  $S$  containing  $a$ , and let  $B$  be the connected component of  $S$  containing  $b$ . Denote by  $G_A$  and  $G_B$  the (setwise) stabilizers of  $A$  and  $B$  respectively. Then the *splitting of  $G$  induced by  $e$*  has one of the following forms:

1. an amalgamated product of the form  $G = G_A *_{\text{Stab}(e)} G_B$ , or
2.  $A$  and  $B$  are conjugate in  $G$ , and  $G$  splits as an HNN extension of the form  $G_A *_{\text{Stab}(e)}$ .

**Exercise XXII.** Prove that every nontrivially stabilized edge  $e$  of  $T$  induces a splitting of  $T$ :

1. Use the Stability Lemma (Lemma III.3.13) to show that  $L$  acts on  $T$  without inversions, and therefore every edge  $e$  of  $T$  with a nontrivial stabilizer induces a splitting of  $L$ .
2. Prove that the setting described in Definition III.4.5 gives rise to a splitting as described.

**Theorem III.4.6.** *Suppose that  $L$  is a limit group, denote by  $\theta_n : L \rightarrow F$  the corresponding sequence of homomorphisms and denote by  $T$  the limiting  $\mathbb{R}$ -tree. Let  $e = [p, q]$  be a simplicial edge of  $T$  as in Definition III.4.5 and suppose that the stabilizer of  $e$  is nontrivial. Let  $Y$  be a finite subset of  $L$ . Then there exists a sequence of automorphisms  $\alpha_n \in \text{Aut}(L)$  such that for every  $y \in Y$  the following holds:*

1. *If  $T'$  is the component of  $T - \bigcup_{g \in G} g.e$  that contains  $p$  (which, after translation, can be chosen to contain  $o$ ), and  $y$  is not in the setwise stabilizer of  $T'$ , then  $d_n(o_n, \theta_n(\alpha_n(y))) < d_n(o_n, \theta_n(y))$   $\omega$ -almost-surely.*
2. *Otherwise,  $d_n(o_n, \theta_n(\alpha_n(y))) = d_n(o_n, \theta_n(y))$   $\omega$ -almost-surely.*

Moreover, in either case we have that  $d(o, \alpha_n(y).o) = d(o, y.o)$  for every  $n$ .

*Remark III.4.7.* Note that in this case we cannot shorten the action of the relevant  $y \in Y$  on  $T$ , but rather we shorten the action of  $\theta_n(y)$  in the approximations  $(F, d_n)$  of  $T$ . Moreover, the automorphism  $\alpha_n$  can be chosen to be a power of a *Dehn twist* [add reference - mentioned in previous section](#) about an element in  $\text{Stab}(e)$ .

*Proof of Proposition III.4.4.* Let  $e$  be an edge of  $T$ ; if  $e$  lies in  $\bar{T}$  then Lemma III.3.14 implies that  $\text{Stab}(e)$  is trivial. Otherwise, we may assume without loss of generality that  $e$  is covered by a translate of  $[o, y_k \cdot o]$  for some  $k$  (if not, replace  $e$  by a shorter edge  $e' \subset e$  which has the same stabilizer by the Stability Lemma (Lemma III.3.13)). Therefore, there is an edge  $f$  which is a translate of  $e$  and which is contained in  $[o, y_k \cdot o]$ .

Consider the splitting induced by  $f$  as in Definition III.4.5; note that  $o \in A$ , and since no translate of  $[o, x_j \cdot o]$  can intersect  $f$  in more than a point (since for every subarc  $f' \subset f$ ,  $\text{Stab}(f') = \text{Stab}(f) = \text{Stab}(e) \neq \{1\}$ ) we have that  $\langle \bar{x} \rangle \leq G_A$ . In particular, every  $\alpha_n$  as in Theorem III.4.6, which is a Dehn twist about a power of an element in  $\text{Stab}(f)$ , fixes every  $x_i$ . In addition, we have that  $d_n(o_n, \theta_n(\alpha_n(y_k)) \cdot o_n) < d_n(o_n, \theta_n(y_k) \cdot o_n)$   $\omega$ -almost-surely. Therefore  $\theta_n \circ \alpha_n$  is shorter than  $\theta_n$  relative to  $\langle \bar{x} \rangle$ , contradicting Lemma III.3.4.  $\square$

## III.5 Deriving a formal solution

**Corollary III.5.1.** *The tree  $T$  coincides with  $\bar{T}$ .*

*Proof.* Suppose not, then there exists some  $y_i$  such that  $y_i \cdot o \notin \bar{T}$ . Since the tree  $T$  is simplicial, there is a point  $p \in [o, y_i \cdot o]$  such that the entire arc  $[p, y_i \cdot o]$  lies outside of  $\bar{T}$ . But now, Definition III.4.5 gives rise to a free splitting  $L = L_1 * L_2$  where  $\langle \bar{x} \rangle \leq L_1$ , contradicting the fact that  $L$  is freely indecomposable relative to  $\langle \bar{x} \rangle$ . It follows that every  $y_i \in \bar{y}$  lies on  $\bar{T}$ , and since  $T$  is spanned by the segments of the form  $[o, x_i \cdot o]$  and  $[o, y_i \cdot o]$ ,  $T = \bar{T}$ .  $\square$

We are finally in a position to prove Theorem III.0.3:

*Proof of Theorem III.0.3.* To construct a retraction  $G_\Sigma \twoheadrightarrow \langle \bar{x} \rangle$ , it suffices to construct a retraction  $L \twoheadrightarrow \langle \bar{x} \rangle$ ; to do so, we will show that  $L$  splits as a free product of the form  $\text{Stab}(o) * \langle \bar{x} \rangle$ , which yields the desired retraction.

To this end, it is enough to show that for every  $y_i \in \bar{y}$ , there exists  $g \in \langle \bar{x} \rangle$  such that  $y_i \cdot o = g \cdot o$ . Indeed, in this case, we will get that the edges  $[o, x_i \cdot o]$  form a fundamental domain for  $L \simeq T$ , and the quotient graph of groups  $T/L$  takes the form of a rose. The unique vertex group is  $\text{Stab}(o)$ , and each petal gives a stable letter for the splitting, with a trivial stabilizer.

We will therefore suppose for a contradiction that for some  $y_i \in \bar{y}$ ,  $y_i \cdot o$  does not coincide with some  $g \cdot o$  as described above. In particular, there exists some  $h \in \langle \bar{x} \rangle$ ,



and some  $x_j \in \bar{x}$ , such that  $y.o$  lies in the interior of  $h.[o, x_j.o]$ . It follows that  $h^{-1}y_i.o$  lies in the interior of  $[o, x_j.o]$ , and  $h^{-1}y_i.[o, x_j.o] \cap [o, x_j.o]$  is a nontrivial arc. This contradicts the small cancellation condition as in Lemma III.3.14.  $\square$

There are still two (potential) issues one has to consider:

**Exercise XXIII.** Our proof of Theorem III.0.3 holds only in the case where  $T$  is not a line; in this exercise we will prove that the theorem holds also when  $T$  is a line.

1. Using the Lemma III.3.13, we have that  $L$  is abelian. Prove that  $\bar{x}$  is in fact a singleton  $x$ .
2. Now  $L$  acts on a line, so it decomposes as  $K \oplus L'$  where  $K$  consists of the elements of  $L$  that act trivially, and  $L'$  is a finitely generated, free abelian group of elements that act on  $T$  by translation. Imitate the argument in Lemma III.3.4 and show that we can assume that  $x$  does not fix a point of  $T$ .
3. Show that for every  $y_i \in \bar{y}$ , there exists  $k_i \in \mathbb{Z}$  such that  $\ell(y_i) = k_i \cdot \ell(x)$  (to do so, use the same argument as in Section III.5 and Lemma III.3.14). Deduce that Merzlyakov's theorem holds.

**Exercise XXIV.** In Theorem III.0.3, we assumed that the formula  $\varphi$  takes the shape  $\forall \bar{x} \exists \bar{y} \Sigma(\bar{x}, \bar{y}) = 1$ , when in fact a general positive  $\forall \exists$ -formula takes the shape


$$\forall \bar{x} \exists \bar{y} \bigvee_{i=1}^k \Sigma_i(\bar{x}, \bar{y}) = 1.$$

Explain why there exists  $1 \leq i \leq k$  for which we can carry out the proof and obtain a retraction  $G_{\Sigma_i} \twoheadrightarrow \langle \bar{x} \rangle$ .

# A

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## Group actions on simplicial trees

EAN-PIERRE Serre developed in the 1970s a theory which allows one to describe the structure of a group based on its action on a simplicial tree. A detailed account of this theory appears in [17], and is commonly known as *Bass-Serre theory* (Hyman Bass was the editor for an earlier, French, monograph of Serre's). In this appendix we give a brief overview of this theory.

Let  $G$  be a group acting on a (simplicial) tree  $T$  by isometries (so that each  $g \in G$  gives an isometry of  $T$ ). We begin by classifying these isometries by dividing them into two categories.

**Definition A.0.1.** Let  $g$  be an isometry of a simplicial tree  $T$ . The *translation length* of  $g$  is

$$\ell(g) = \inf_{x \in T} d(x, gx).$$

If  $\ell(g) = 0$ , that is, when  $g$  fixes a point, we say that  $g$  is *elliptic*; otherwise, we say that  $g$  is *hyperbolic*.

**Exercise XXV.** Given an isometry  $g$  of  $T$ , the *axis* of  $g$  is

$$\text{Axis}(g) = \{x \in T \mid d(x, gx) = \ell(g)\}.$$

1. Prove that  $\text{Axis}(g)$  is a nonempty subspace of  $T$ .
2. If  $g$  is elliptic, then clearly its axis coincides with its set of fixed point. Prove that  $\text{Fix}(g)$  is a connected subtree of  $T$ .

3. Prove that if  $G$  is finitely generated and the action of every  $g \in G$  on  $T$  is elliptic, then there is a global fixed point for the action  $G \curvearrowright T$ .
4. Prove that if  $g$  is hyperbolic then  $\text{Axis}(g)$  is a bi-infinite line  $L$  that embeds in  $T$ , and  $g$  acts on  $L$  by translation by  $\ell(g)$ .

*Remark A.0.2.* One can also assign translation lengths to isometries of a general metric space  $X$ ; however, in the general case, elements do not always fall into the two aforementioned categories. A general metric space  $X$  can admit *parabolic* isometries, which can be thought of as “isometries fixing a point at infinity”.

We continue with a motivating example of groups acting on simple trees: lines.

**Example A.0.3.** Let  $T$  be a bi-infinite line whose vertices are indexed by the integers, and let  $G_1$  and  $G_2$  be two groups that act on it as follows:

1.  $G_1 = \mathbb{Z} = \langle g \rangle$  where  $g.x = x + 1$ .
2.  $G_2 = D_\infty = \langle g, h \mid g^2 = h^2 = 1 \rangle$ , where  $g$  acts by reflection around 0 (that is,  $g.x = -x$ ) and  $h$  acts by reflection around 1 (that is,  $h.x = 2 - x$ ).

One easily sees that in the first example,  $\text{Axis}(g) = T$  and  $g$  acts on its axis by translation with translation length 1 and  $g$  is hyperbolic. In the second example, the axes of both  $g$  and  $h$  are a single point, and both generators act elliptically on  $T$ .

Consider the two quotient spaces  $X_1 = T/G_1$  and  $X_2 = T/G_2$ . We have that  $X_1 \cong S^1$ , and the fundamental group of the circle is  $\mathbb{Z}$ . In this case, one could recover the group  $G_1$  just by looking at the action on  $T$  (or rather, its quotient). The tree  $T$  can also be recovered as the universal cover of  $X_1$ . On the other hand,  $X_2 \cong [0, 1]$  and the fundamental group of an interval is trivial.

The key idea behind Bass-Serre theory is the following: if we keep track of the stabilizers of the vertices and edges of  $T$  (as well as how the edge stabilizers embed into the corresponding vertex stabilizers) in the quotient  $T/G_2$ , we can reconstruct  $G_2$  (as well as  $T$ ) from the quotient. In this case, our quotient graph  $T/G_2$  has two vertices connected by a single edge. One of these vertices is the image of 0, which is stabilized by  $\langle g \rangle \cong \mathbb{Z}/2$ , and the other is the image of the vertex 1 (stabilized by  $\langle h \rangle$ ). The edge between 0 and 1 is not stabilized by any element of  $G_2$  (except for, of course, the trivial element). Bass-Serre theory tells us that looking at the "marked quotient" (or "graph of groups")

$$\langle g \rangle \cong \mathbb{Z}/2 \bullet \overset{\{1\}}{\text{---}} \bullet \langle h \rangle \cong \mathbb{Z}/2$$

we can reconstruct  $G_2$  and  $T$ .

*Remark A.0.4.* If two vertices (or edges) in  $T$  are in the same orbit, then their vertices are conjugate and therefore isomorphic. Therefore, the choice of a preimage of the vertices (or edges) does not affect the "marked quotient".

**Definition A.0.5.** A (*simplicial*) *tree* is a 1-dimensional simplicial complex (or, in other words, a discrete graph) that contains no cycles. Let  $G$  be a group acting on a tree  $T$  and assume that the action does not invert any edge  $e$  of  $T$ . A *graph of groups* is a quotient of the form  $X = T/G$ , along with labels on the vertices and edges of the quotient graph  $X$  such that:

1. for every  $v \in V(X)$ , choose  $\tilde{v} \in V(T)$  that's mapped to  $v$  by the quotient map and label  $v$  by  $\text{Stab}(\tilde{v})$ ,
2. for every  $e \in E(X)$  choose  $\tilde{e} \in E(T)$ . Write  $e = \{v, u\}$  and  $\tilde{e} = \{\tilde{v}, \tilde{u}\}$  where  $\tilde{v}, \tilde{u}$  are mapped to  $v, u$  respectively in the quotient. Note that  $\text{Stab}(\tilde{e})$  is a subgroup of  $\text{Stab}(\tilde{v})$  and of  $\text{Stab}(\tilde{u})$  and denote the inclusion homomorphisms by  $i_v$  and  $i_u$  respectively. We label the edge  $e$  by  $\text{Stab}(\tilde{e})$ , and record the *edge maps*  $i_v$  and  $i_u$ .

We can also define graphs of groups without a group action on a tree:

**Definition A.0.6.** A (*Serre*) *graph*  $X$  consists of a vertex set  $V$  and an edge set  $E$ ;  $X$  also comes equipped with

1. an *edge reversal* map  $\bar{\cdot} : E \rightarrow E$  satisfying  $\bar{\bar{e}} = e$  and  $\bar{e} \neq e$ , and
2. an *initial vertex* map  $\iota : E \rightarrow V$  which maps  $e$  to its initial vertex (so that the edge  $e$  connects the vertices  $\iota(e)$  and  $\iota(\bar{e})$ ). We will sometimes use  $\tau : E \rightarrow V$  to denote the *terminal vertex* map which sends  $e$  to its terminal vertex (that is,  $\tau(e) = \iota(\bar{e})$ ).

A *graph of groups*  $\mathcal{X}$  is comprised of the following data:

1. a connected graph  $X$ ,
2. a *vertex group*  $X_v$  for every  $v \in V$ ,
3. an *edge group*  $X_e$  for every  $e \in E$ , and
4. an injective *edge map*  $i_e : X_e \rightarrow X_{\iota(e)}$  for every  $e \in E$ .

We can attach a *fundamental group* to a graph of groups. Just like in topological spaces, we can look at *paths* and *loops* in a graph of groups  $\mathcal{X}$ . In this context, a path from  $v \in V$  to  $u \in V$  is a finite sequence of the form

$$(a_0, e_1, a_1, e_2, \dots, e_n, a_n),$$

where  $(e_1, \dots, e_n)$  is a path from  $v$  to  $u$ ,  $a_i \in X_{\iota(e_{i+1})}$  for  $i < n$  and  $a_n \in X_{\tau(e_n)}$ ; a loop is a path from a vertex  $v \in V$  to itself. Note that each path is an element of  $(\ast_{v \in V} X_v) \ast F(E)$ . Much like in the case of the standard fundamental group of a topological space, we want to consider loops up to "homotopy". In the case of a graph of groups, instead of homotopy we define an equivalence relation on paths. We say that two paths  $p_1$  and  $p_2$  are  $\mathcal{X}$ -*equivalent* if  $p_2$  can be obtained from  $p_1$  by a finite sequence of replacements according to the following rule:

$$(e, i_{\bar{e}}(g), \bar{e}) \longleftrightarrow (i_e(g)).$$

We denote the equivalence class of a path  $p$  by  $[p]$ . Finally, we define the *fundamental group of  $\mathcal{X}$  at  $v \in V$*  by

$$\pi_1(\mathcal{X}, v) = \{[p] \mid p \text{ is a loop based at } v\}.$$

One easily sees that  $\pi_1(\mathcal{X}, v)$  has a group structure (where multiplication is given by path concatenation), and that its definition does not depend on  $v$ . We will therefore write  $\pi_1(\mathcal{X})$  without specifying a base point.

The fundamental group of  $\mathcal{X}$  can also be described by the following presentation: fix a *spanning tree*  $T$  of  $X$  (that is, a subtree  $T$  of  $X$  which contains every  $v \in V$ ), and fix a presentation  $\langle S_v \mid R_v \rangle$  for every vertex group  $X_v$ . Then the fundamental group of  $\mathcal{X}$  (with respect to  $T$ ) has the presentation:

$$\pi_1(\mathcal{X}, T) = \left\langle \bigcup_{v \in V} S_v \cup \{t_e \mid e \in E\} \mid \bigcup_{v \in V} R_v \cup R \right\rangle$$

where  $R$  contains the following relations:

- $t_e$  for every  $e \in T$ ,
- $t_e t_{\bar{e}}$  for every  $e \in E$ , and
- $i_e(g) = t_e \cdot i_{\bar{e}}(g) \cdot t_e^{-1}$  for every  $e \in E$  and  $g \in X_e$ .

Again, it is not hard to see that the resulting group does not depend on the spanning tree  $T$  (and we will therefore refer to it as  $\pi_1(\mathcal{X})$ ).

**Exercise XXVI.** Show that the two definitions of  $\pi_1(\mathcal{X})$  coincide.

We continue with a few examples of group actions on simplicial trees (along with their corresponding graph of groups decompositions and simplicial trees on which they act). A graph of groups decomposition of a group is also called a *splitting* of the group; we will embrace this terminology. Before getting hands on with the examples, we should point out that the *Bass-Serre tree*  $T$  corresponding to a graph of groups  $\mathcal{X}$  should be thought of as the universal cover of  $\mathcal{X}$ . In the construction of  $T$ , we essentially “unwind”  $\mathcal{X}$ , unidentifying as many edges and vertices as possible, while maintaining an action of  $\pi_1(\mathcal{X})$  on the resulting object such that the corresponding quotient is  $\mathcal{X}$ . We begin with the case where all of the edge groups are trivial.

**Examples A.0.7.** Figures depicting each of the graphs and some of the trees below will be added at a later point.

1. Let  $G = A * B$  be the free product of two groups  $A$  and  $B$ . From the discussion above, it should be clear that  $G$  admits a graph of group splitting with two vertices, one labeled by  $A$  and one by  $B$ , and a single edge labeled by the trivial group. Since we unidentify as many vertices and edges as possible, the vertices of the tree  $T$  stabilized by conjugates of  $A$  stand in bijection with the cosets of  $A$  in  $G$ :  $G$  acts on these cosets with a single orbit, so there will be a single vertex labeled by  $A$  in the quotient (and the same holds for  $B$ ). Similarly, the edges of  $T$  biject with the cosets of the trivial group in  $G$ , or in other words, the elements of  $G$ . In addition, the quotient  $\mathcal{X}$  tells us that in  $T$ , vertices which correspond to cosets of  $A$  are connected only to vertices which correspond to cosets of  $B$ .

We next understand which vertices of  $T$  are connected by an edge. Let  $gA$  and  $hB$  be two vertices of  $T$ .

To understand how we “unwind” loops in  $\mathcal{X}$ , we begin with the simplest possible type of loop: a non-trivial element  $a \in A$ . Let  $v$  be a vertex of  $T$  that is not stabilized by  $a$ , or in other words, any vertex other than  $1 \cdot A$ . Consider an element of  $\pi_1(\mathcal{X})$ ; it has the form  $a_1 \cdot b_1 \cdots a_n \cdot b_n$ , where non of the  $a_i$  and  $b_i$  are trivial (except for possibly  $a_1$  and  $b_n$ ). If  $A$  and  $B$  are countable, then  $G$  acts on a simplicial tree in which every vertex has a countable degree. This action will have two orbits of vertices - one stabilized by conjugates of  $A$  and one by conjugates of  $B$ . To construct the action on the tree  $T$ , we can choose an arbitrary vertex  $v \in V(T)$  and label it by  $A$ ; we can enumerate the edges

incident to  $v$  by the elements of  $A$ , now  $A$  acts on these edges by permuting them according to left multiplication. The vertex  $u$  connected to  $v$  by an edge labeled by 1 is the vertex stabilized by  $B$ . A vertex  $u'$  connected to  $v$  by an edge labeled by  $a \in A$  will be stabilized by  $a \cdot B \cdot a^{-1}$ . One can iterate this construction and obtain an action of  $G$  on all of  $T$ .

One can also verify that the tree  $T$  admits the following description: its vertices are indexed by the cosets of  $A$  and  $B$  in  $G$ , and two cosets  $gA$  and  $hB$  are connected by an edge if and only if there exists some  $b \in B$  such that  $hbA = gA$ .

2. Similar to the example above, we can consider a graph of groups  $\mathcal{X}$  whose underlying graph is a finite tree, and all of whose edges are labeled by the trivial group. It is not hard to see that in this case, the fundamental group of this graph of groups is simply the free product of the different edge groups. The tree  $T$  on which  $\pi_1(\mathcal{X})$  acts admits a similar description to the one above. Suppose that  $A$  is a vertex group of  $\mathcal{X}$  and that  $A_1, \dots, A_k$  are the vertex groups adjacent to  $A$  in  $X$ . If  $v \in V(T)$  is stabilized by  $A$ , then the edges adjacent to  $v$  in  $T$  stand in bijection with  $A \times \{1, 2, \dots, k\}$  and  $A$  permutes these edges according to the following rule: the element  $a \in A$  sends the edge labeled by  $(a', i)$  to the one labeled by  $(aa', i)$ . As before, one can iteratively extend this construction to obtain a full description of  $T$  (and the action of  $\pi_1(\mathcal{X})$  on  $T$ ). Again, one can think of the vertices of  $T$  as labeled by the cosets of the different vertex groups, and two vertices are connected by an edge if they satisfy the same condition as in 1. above.
3. To complicate things (a bit) further, let's consider a graph of groups  $\mathcal{X}$  whose underlying graph is an  $n$ -cycle and whose edge groups are all trivial. Let  $A_1, \dots, A_n$  be the vertex groups of  $\mathcal{X}$ . By the description of the fundamental group of  $\mathcal{X}$  above,  $\pi_1(\mathcal{X}) = A_1 * \dots * A_n * \mathbb{Z}$  (a spanning tree  $T$  for  $X$  is simply a path of length  $n - 1$ , so if  $e = X - T$ , the  $\mathbb{Z}$ -factor is generated by  $t_e$ ). Constructing the tree on which  $\pi_1(\mathcal{X})$  acts in this case is slightly more complicated, but the idea should be clear after we talk about *HNN extensions* in the next set of examples. We remark that the vertices of  $T$  can still be thought of as the cosets of  $A_1, \dots, A_n$ , and that the edges adjacent to a vertex  $gA_i$  stand in bijection with  $A_i \times \{1, 2\}$ . In this case, we still have that the vertex  $A_1$  is adjacent to  $A_2$ ,  $A_2$  is adjacent to  $A_3$  etc., but  $A_{n-1}$  is no longer adjacent to  $A_1$  (even though they are adjacent in the quotient), but rather to the vertex  $t_e A_1$ .

From here, one can easily verify that the fundamental group of a graph of groups  $\mathcal{X}$  with trivial edge stabilizers is the free product of the vertex groups of  $\mathcal{X}$  and the fundamental group of the underlying graph  $X$  of  $\mathcal{X}$ .

We continue by highlighting two specific types of group splittings: *amalgamated products* and *HNN extensions*; these occur when the action of  $G$  on  $T$  has a single orbit of edges, and in some way they capture the behaviour of any cocompact group action on a simplicial tree. Indeed we will later explain why every graph of groups can be obtained as a sequence of amalgamations followed by a sequence of HNN extensions.

**Definition A.0.8.** An *amalgamated product* is a graph of groups that consists of a single edge and two distinct vertices. In this case, we have that

$$\pi_1(\mathcal{X}) = \langle G_v, G_u \mid i_e(g) = i_{\bar{e}}(g) \ \forall g \in G_e \rangle.$$

We will denote  $\pi_1(\mathcal{X})$  by  $G_v *_{G_e} G_u$  (or use other variants of this notation), and call it the amalgam of  $G_v$  and  $G_u$  over  $G_e$ .

**Examples A.0.9.** Figures will be added later.

1. With this terminology, the free product  $A * B$  is simply the amalgam of  $A$  and  $B$  over  $\{1\}$ .
2. Let  $F_2 = \langle a, b \rangle$  and  $F'_2 = \langle a', b' \rangle$  be two copies of  $F_2$ . Then the amalgam  $F_2 *_{a=a'b'a'^2b'^4} F'_2$  is the group

$$\langle a, b, a', b' \mid a = a'b'a'^2b'^4 \rangle \cong F_3.$$

Indeed, one can just "forget" about  $a$  in the presentation above. In fact, an old theorem of Shenitzer says that an amalgam of two free groups over a  $\mathbb{Z}$  is free if and only if one of the copies of  $\mathbb{Z}$  is generated by a basis element in one of the sides.

3. Keeping the notation from 2. above, consider the amalgam  $F_2 *_{[a,b]=[a',b']} F'_2$ . We can look at  $F_2$  as the fundamental group of a torus with a single boundary component which is equal to  $[a, b]$  in the level of fundamental groups. It follows from Van Kampen's theorem that the amalgamated product is the fundamental group of a 2-holed torus.



4. More generally, consider  $G = A *_C B$ . One can construct a simplicial tree  $T$  on which  $G$  acts with the desired properties (namely there are two orbits of vertices stabilized by conjugates of  $A$  and  $B$ , and a single orbit of edges stabilized by conjugates of  $C$ ). Suppose such  $T$  exists, and let  $v \in V(T)$  be the vertex stabilized by  $A$ . Then the edges adjacent to  $A$  correspond to the cosets of  $C$  in  $A$ . As before, we can enumerate the vertices of  $T$  by the left cosets of  $A$  and  $B$  in  $G$ . Now, two cosets  $gA$  and  $hB$  are connected by an edge whenever there exists  $b \in B$  such that  $gA = hbA$ . One can think of the tree  $T$  as a quotient of the tree corresponding to  $A * B$ : grouping together edges with the same origin that belong to the same coset of  $C$  (so, for every  $c \in C$  and  $a \in A$ , the edges  $\{gA, gaB\}$  and  $\{gA, gacB\}$  are the same).

**Definition A.0.10.** An *HNN extension* is a graph of groups that consists of a single edge  $e$  and one vertex  $v$  (a loop). In this case, we have that

$$\pi_1(\mathcal{X}) = \langle G_v, t_e \mid i_e(g) = t_e \cdot i_{\bar{e}}(g) \cdot t_e^{-1} \ \forall g \in G_e \rangle.$$

We will denote  $\pi_1(\mathcal{X})$  by  $G_v *_G G_e$  (or use other variants of this notation), and call it the HNN extension of  $G_v$  along  $G_e$ . The element  $t_e$  is called the *stable letter* of the extension.

**Examples A.0.11.** figures will be added later

1.  $\mathbb{Z}$  is the (only) HNN extension of the trivial group; the corresponding action on a simplicial tree was discussed in the beginning of Appendix A.
2. HNN extensions of the integers, with a non-trivial edge group, are called *Baumslag-Solitar* groups. Note that every non-trivial subgroup of  $\mathbb{Z}$  is of the form  $a\mathbb{Z}$  for some integer  $a$ ; therefore, the two edge maps corresponding to the edges  $e$  and  $\bar{e}$  are just multiplication by integers  $a_e$  and  $a_{\bar{e}}$ . The corresponding Baumslag-Solitar group is denoted by  $BS(a_e, a_{\bar{e}})$ . These groups are fairly hard to understand, and they provide a rich family of counter-examples to many group theoretic properties: for example,  $BS(2, 3)$  is not residually finite (and also not equationally Noetherian).
3. As in the case of amalgamated products, surfaces can also be built from free groups using HNN extensions. The fundamental group of a genus  $n$  surface with two boundary components is given by

$$F = \langle a_1, b_1, \dots, a_n, b_n, x, y \mid [a_1, b_1] \cdots [a_n, b_n] = x \cdot y \rangle,$$

where the loops  $x$  and  $y$  correspond to the boundary of the surface. By Van-Kampen's theorem, The HNN extension  $F_{\star_{x=y}}$  is the fundamental group of a surface of genus  $n + 1$ .

4. Again, in the general case, the HNN extension  $G = A \star_C$  acts on a tree whose vertices are enumerated by the cosets of  $A$  in  $G$ , and two vertices  $gA$  and  $hA$  are connected by an edge if there exists  $a \in A$  such that  $gA = hat_e A$  or  $gA = hat_{\bar{e}} A = hat_e^{-1} A$ . Each vertex in the tree is stabilized by a conjugate of  $A$ , and the edges adjacent to a vertex biject with the left cosets of  $i_e(C)$  and  $i_{\bar{e}}(C)$  in  $A$ .

These examples can be summed up in the following theorem, known as the Fundamental Theorem of Bass-Serre Theory:

**Theorem A.0.12.** *Let  $G$  be a group acting on a simplicial tree  $T$  without edge inversions. Denote by  $\mathcal{X}$  the corresponding quotient graph of groups. Then  $\pi_1(X) \cong G$ , and the tree  $T$  admits the following description:*

1. *the vertices of  $T$  can be enumerated by the cosets of the different vertex groups in  $G$ ,*
2. *every lift  $\tilde{v}$  of a vertex  $v$  of  $X$  to  $T$  is stabilized by a conjugate of  $G_v$ ,*
3. *every lift  $\tilde{e}$  of an edge  $e$  of  $X$  to  $T$  is stabilized by a conjugate of  $G_e$ .*

**Exercise XXVII.** Given a graph of groups  $\mathcal{X}$ , construct the corresponding Bass-Serre tree  $T$  based on Examples A.0.9 and Examples A.0.11.

A short text about *normal forms* in graphs of groups will be added later

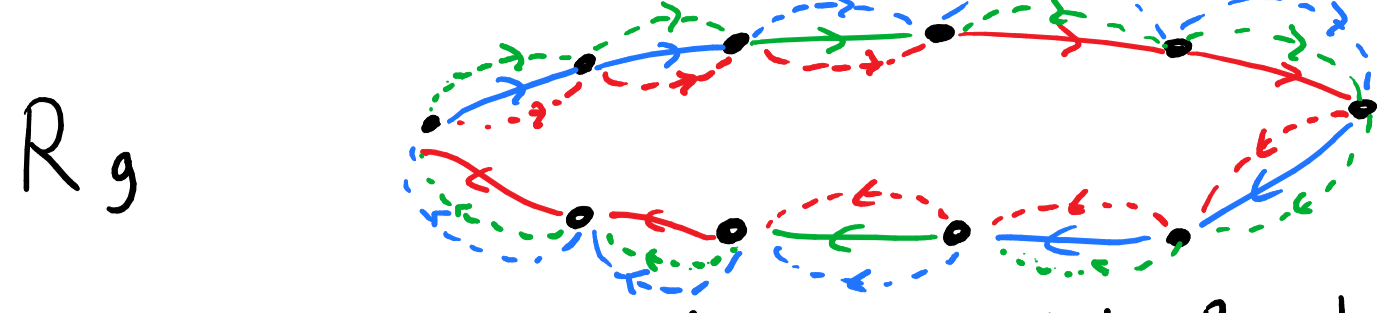
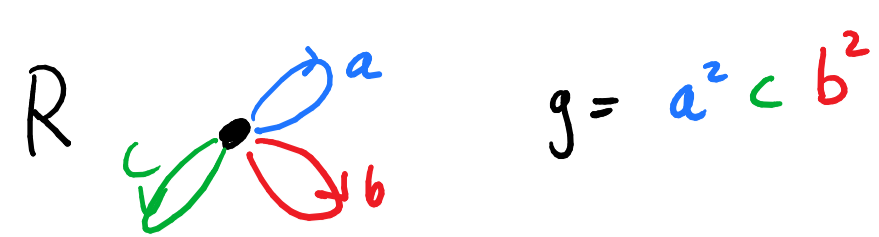
# B

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## Figures

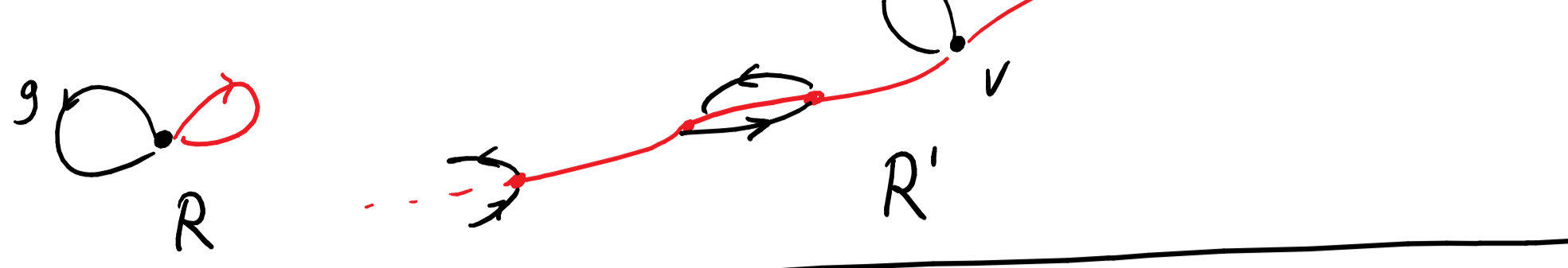
The figures appearing in the next “mega-page” are made using vector-graphics, so zooming will not degrade quality.

Corollary I.2.8:

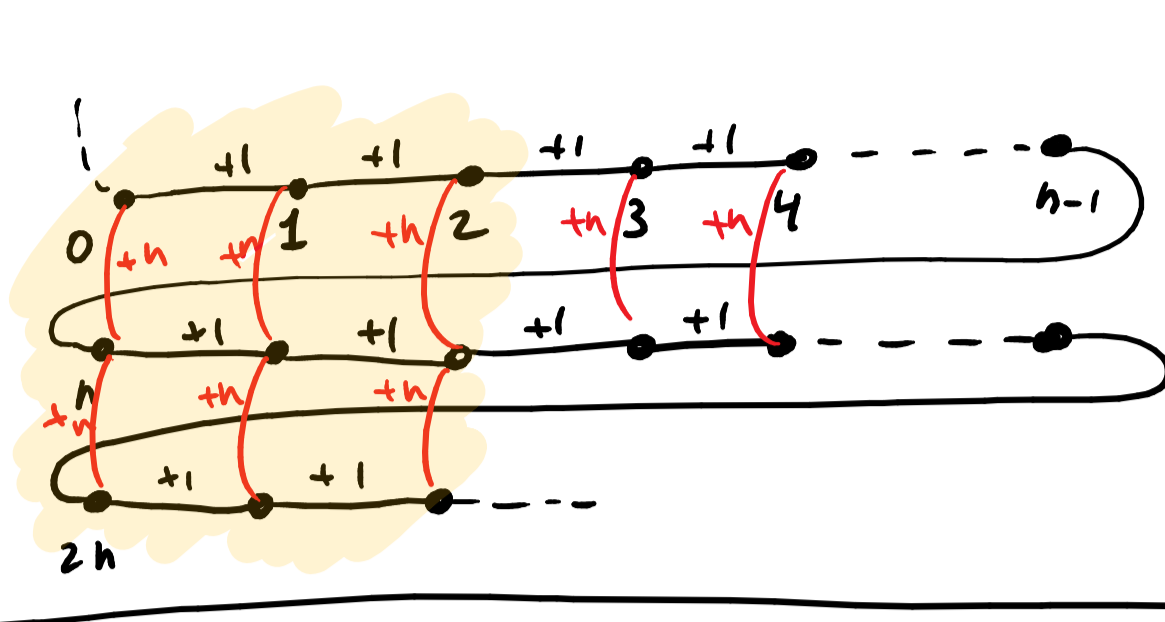


(dotted edges added to complete  $R_g$  to a finite cover of  $R$ )

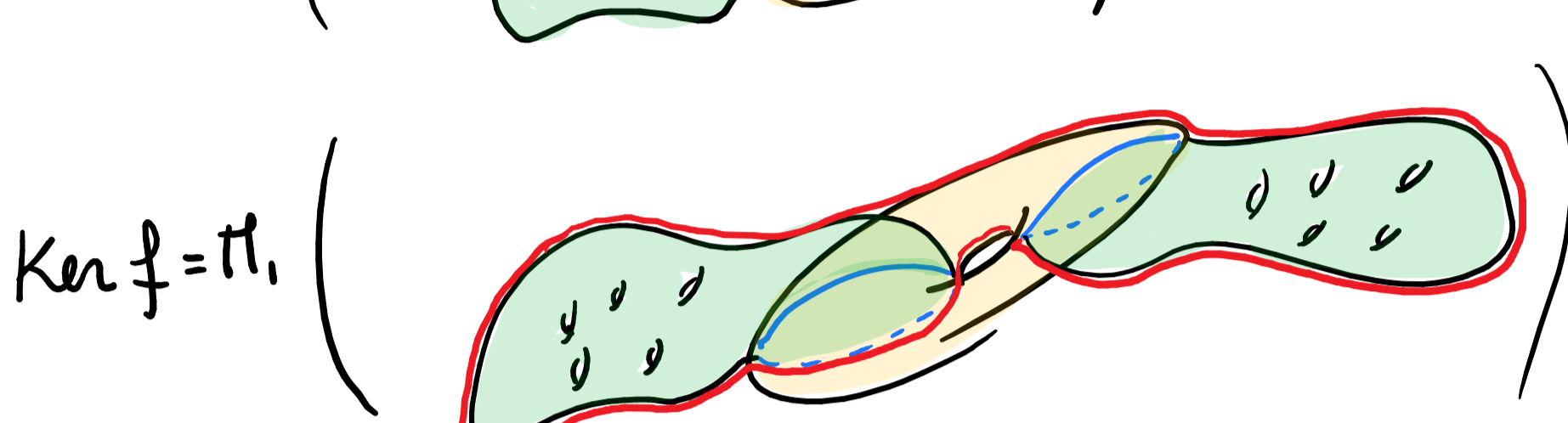
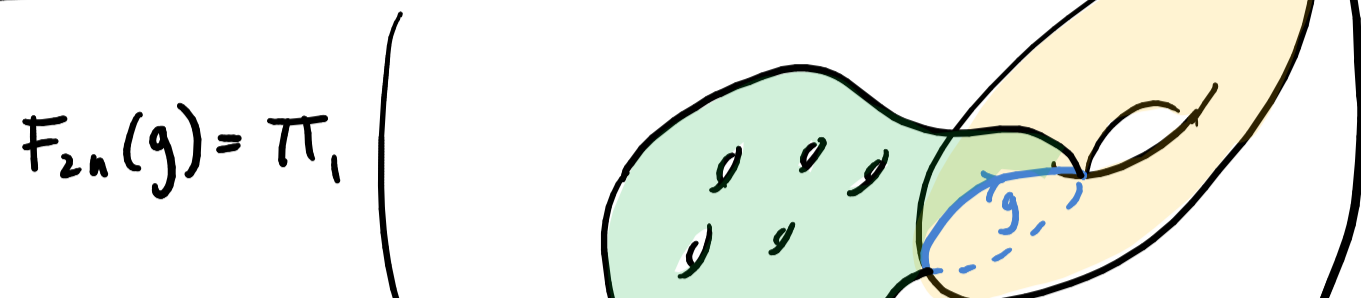
Proof of Thm I.2.1



Examples II.1.6.2

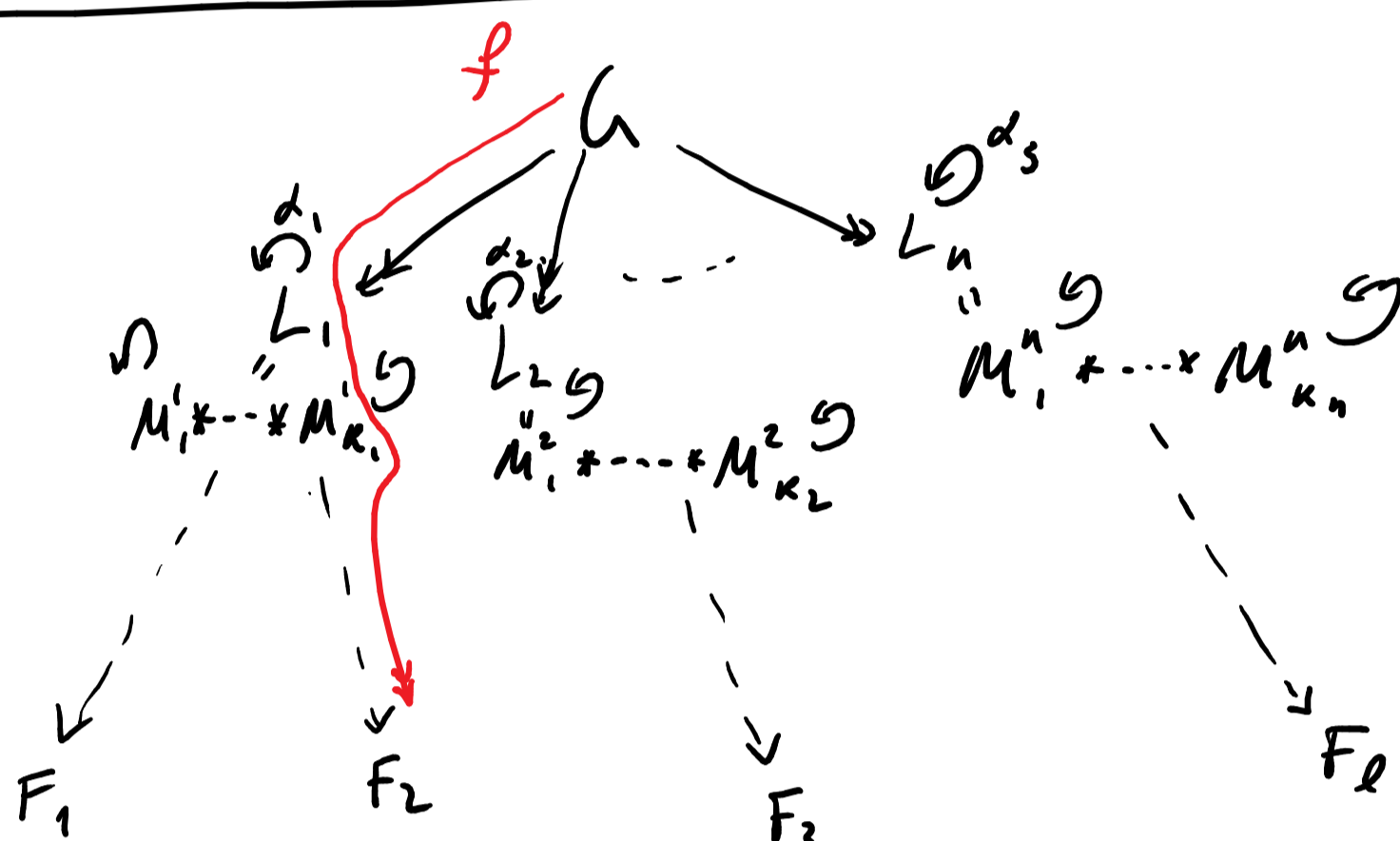


Example II.2.17

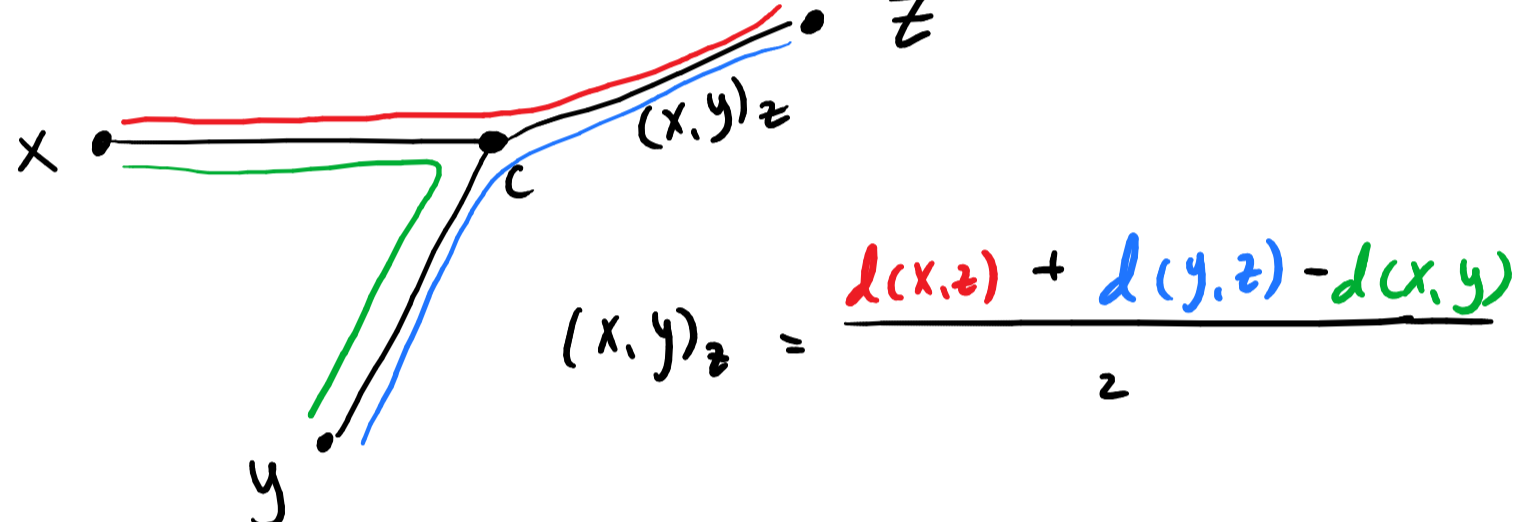


$Z$  is highlighted in red.

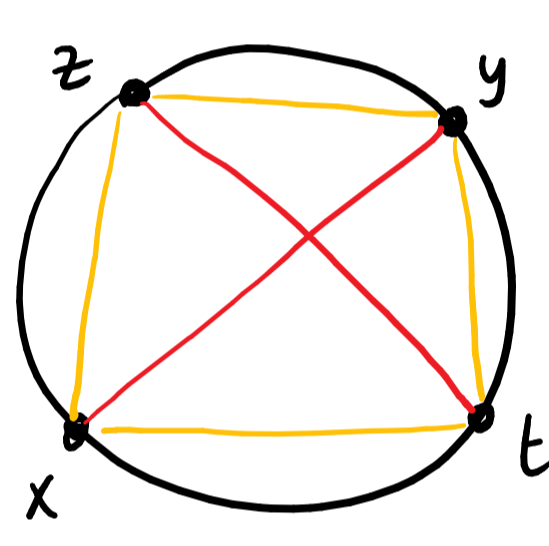
Introduction to Section II.3



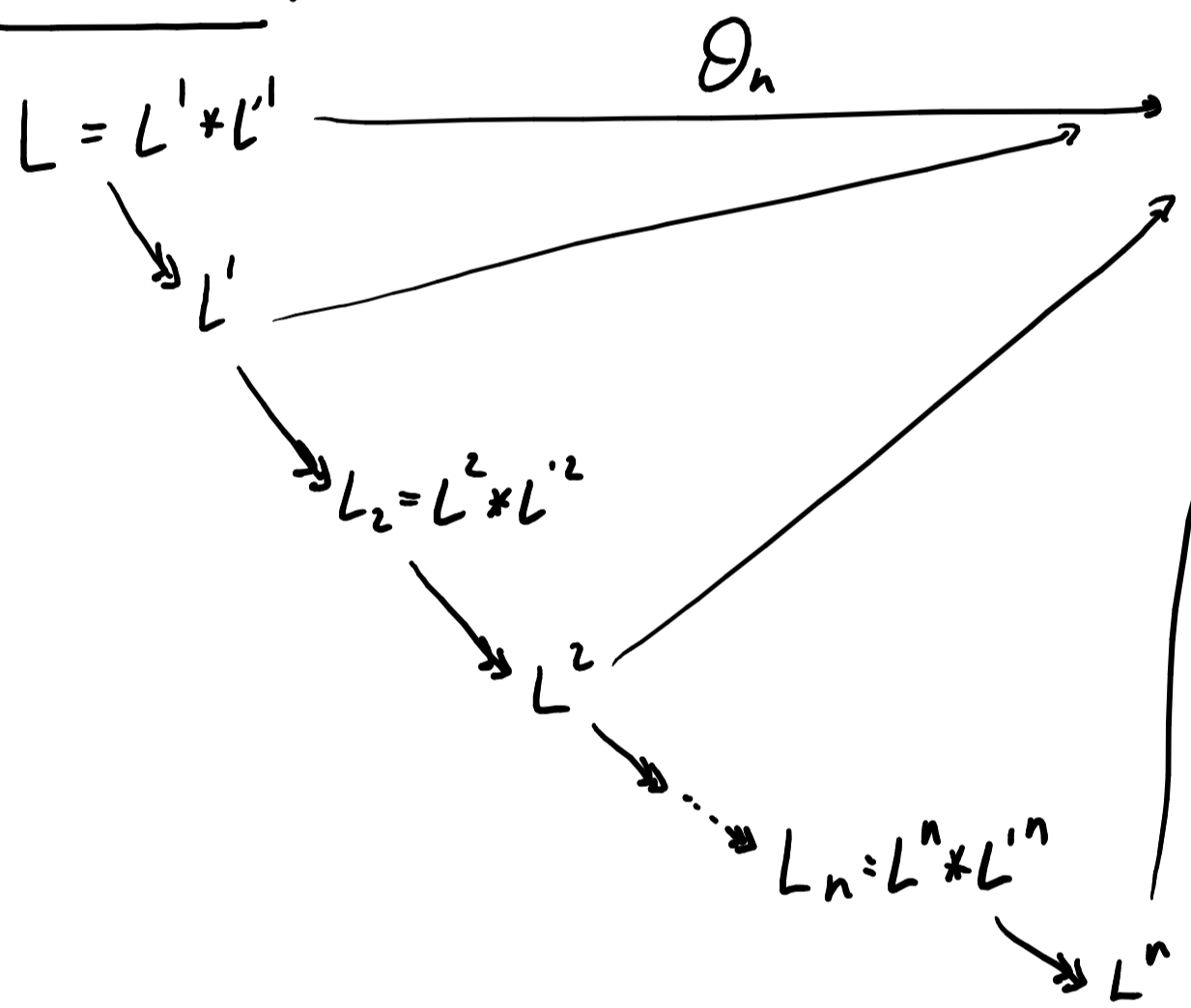
Definition II.3.9



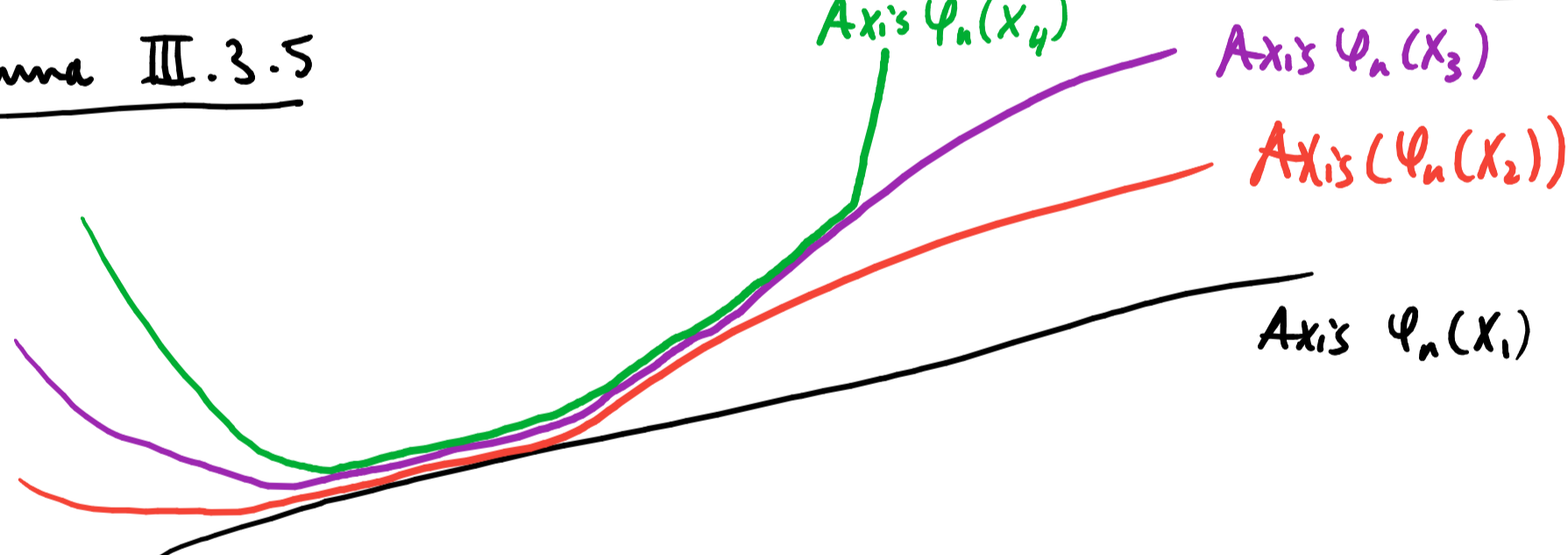
Remark II.3.12



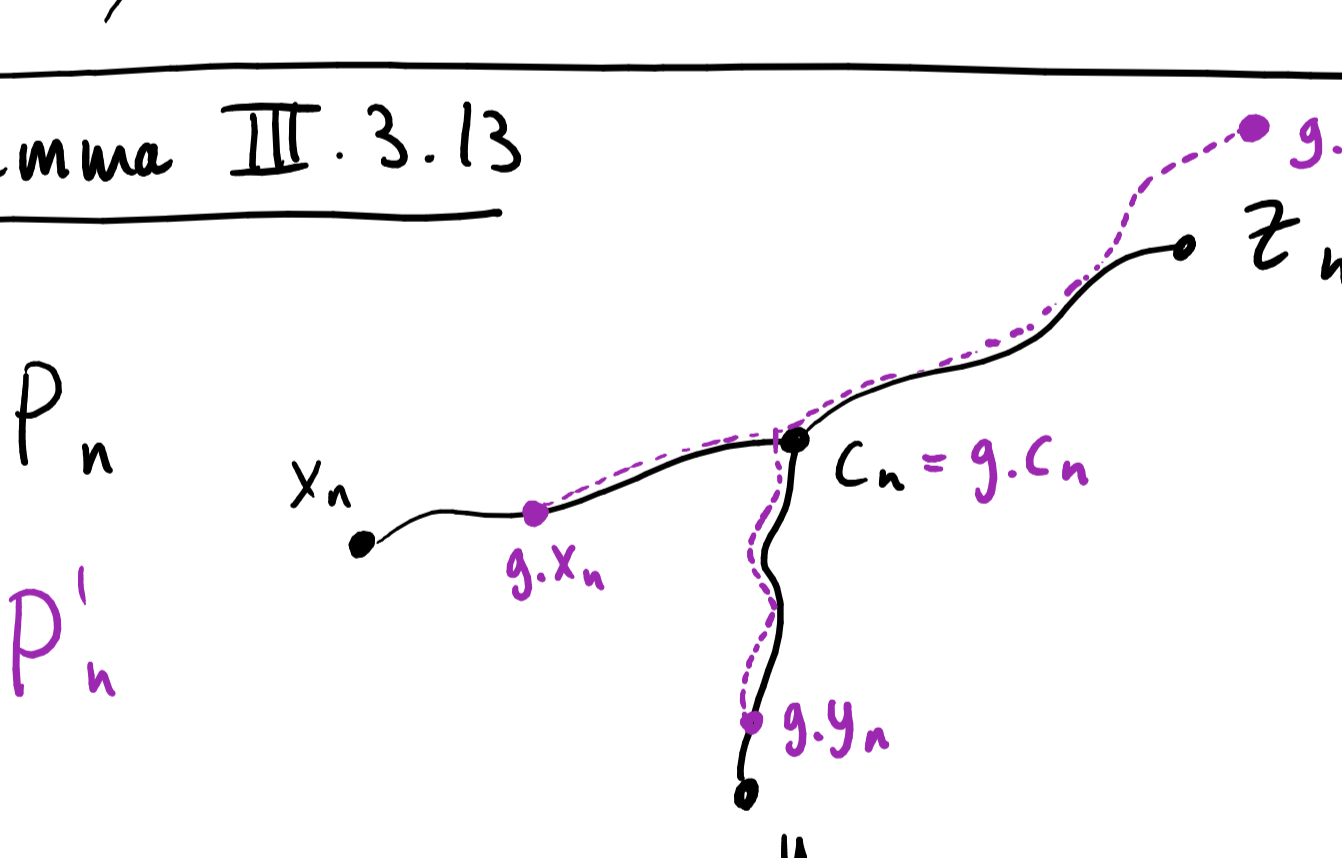
Lemma III.3.4



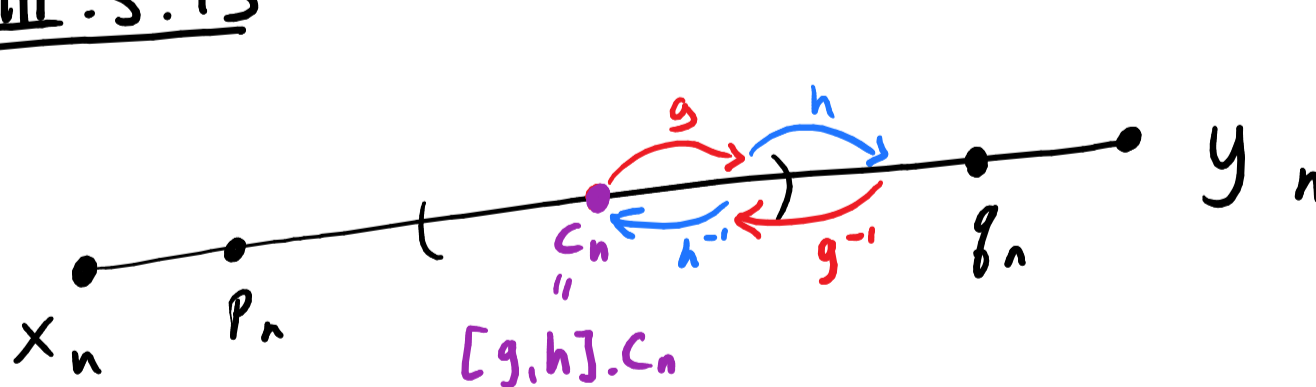
Lemma III.3.5



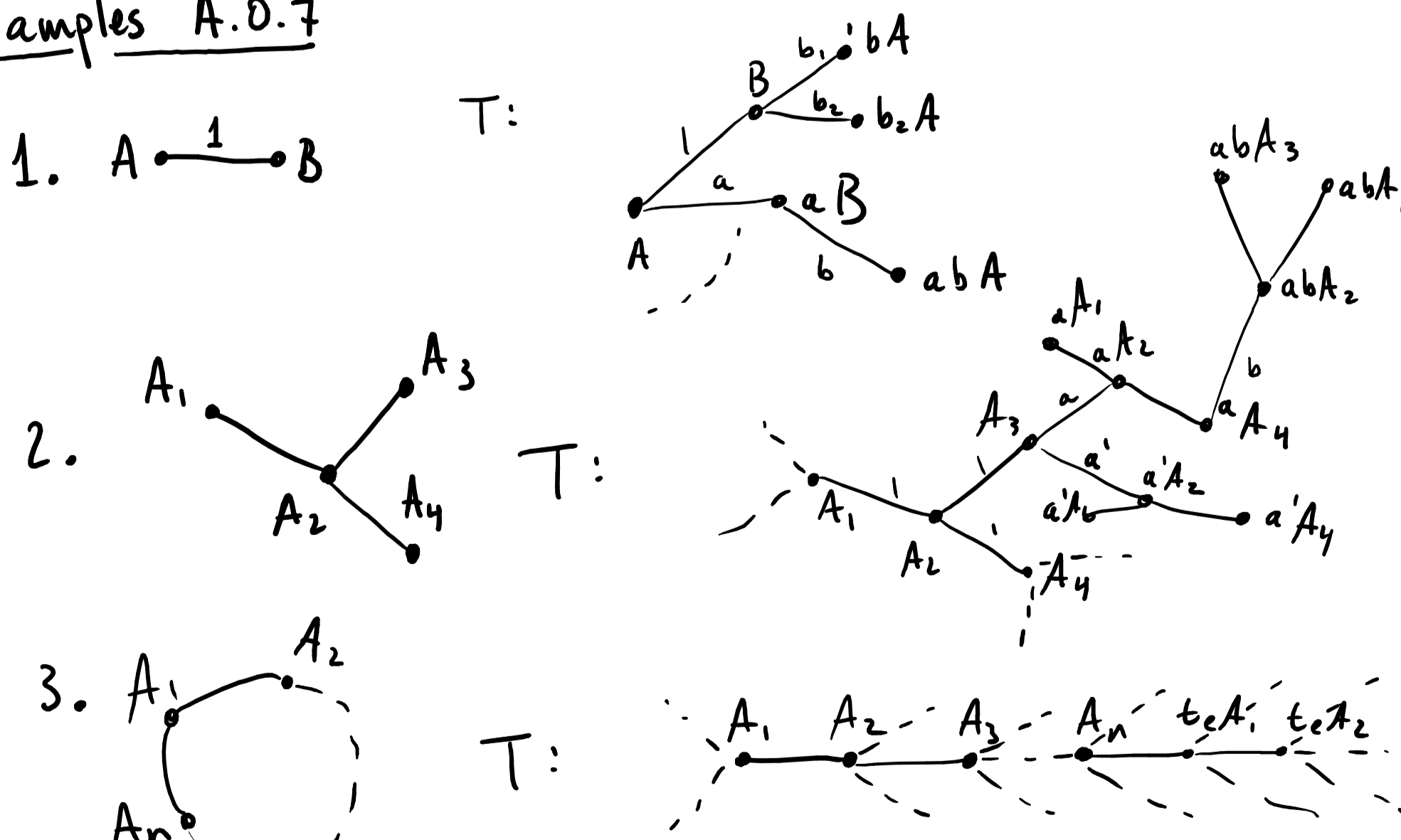
Lemma III.3.13



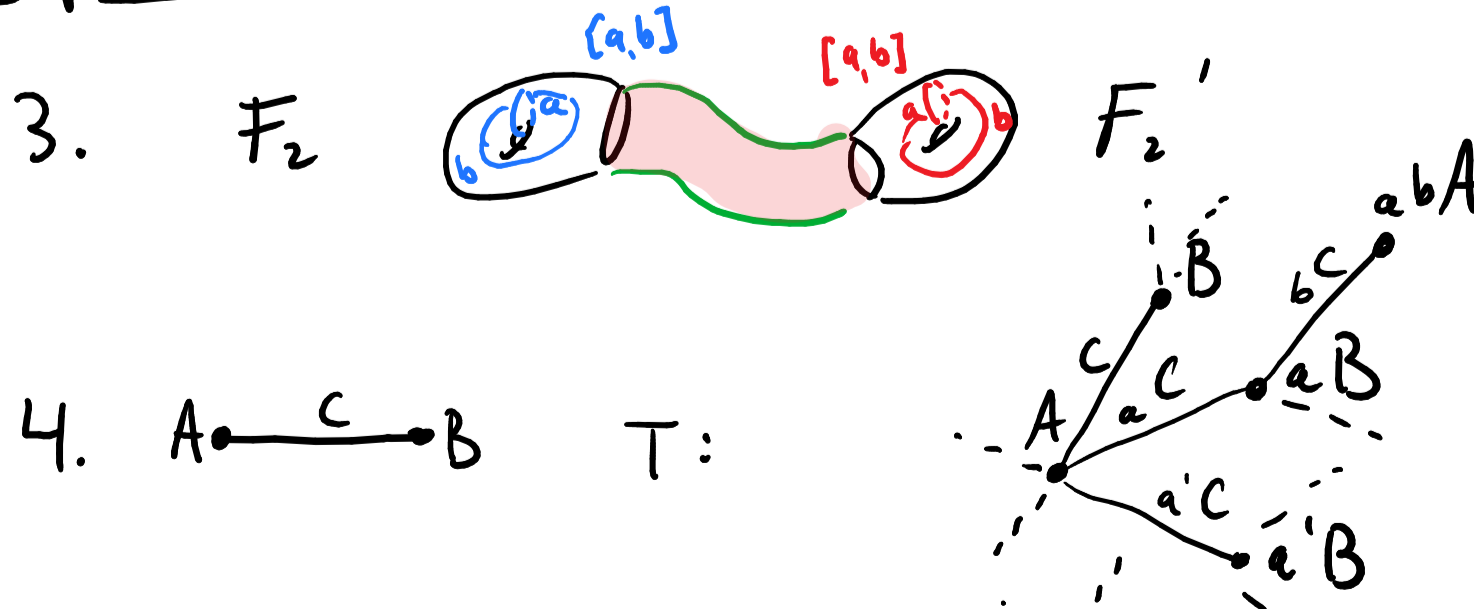
Lemma III.3.13



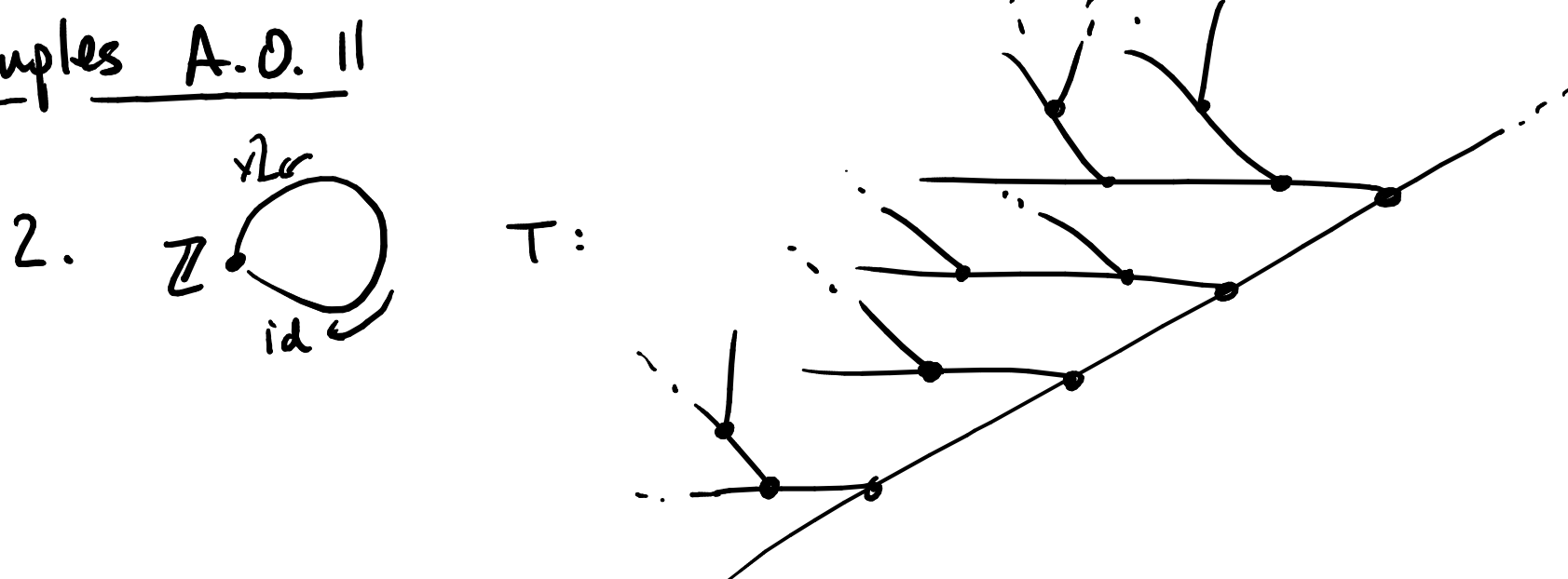
Examples A.0.7



Examples A.0.9



Examples A.0.11



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